Course Structure and Curriculum

Bachelor of Technology

in

Engineering and Computational Mechanics

(Effective from 2023-2024)



Applied Mechanics Department

Motilal Nehru National Institute of Technology Allahabad, Prayagraj-211004

VISION AND MISSION OF THE INSTITUTE

VISION

To attain a distinct identity for the Institute through technology innovation, knowledge creation and dissemination for the benefit of the society.

MISSION

- To nurture an eco-system for continuous enhancement of value-based teaching and learning process in the emerging areas of technology.
- To train quality human and knowledge resources in the service of society.
- To develop sustainable products and technologies.

VISION AND MISSION OF THE DEPARTMENT

VISION

To be at the forefront of creation and dissemination of knowledge and technology in the multidisciplinary fields of Engineering Mechanics and Materials towards solving the challenges and needs of the discipline and the society.

MISSION

- To create and disseminate knowledge resource and sustainable technology through research and innovation in emerging Technological domains.
- To nurture value-based leaders in the Engineering Mechanics, Materials and allied areas capable of solving the challenges and needs of the discipline and the society.

Program Educational Objectives (PEOs)

The *Program Educational Objectives* (PEOs) embody the expected accomplishments of students, who successfully graduate from the program, during their first few years (about 3-5) following their graduation. The PEOs for the present program are as follows.

PEO-1	To develop the ability and confidence among the students for successful analysis and sustainable development of method/product in related industry / R&D organizations by means of successfully applying their knowledge on engineering and computational mechanics and its engineering applications, acquired during their graduation.
PEO-2	To inculcate the professional attitude, effective communication and leadership skills in the students to work as leading collaborators on multidisciplinary projects.
PEO-3	To provide the necessary background and motivation to the students for life-long and self-learning for their personal and professional growth following the professional ethics, environmental and social responsibility.
PEO-4	To inculcate into students, the qualities required to ignite thought process necessary for critical thinking and innovation in their work so as to enable them to successfully pursue advanced studies / research.

Mission Statements	PEO-1	PEO-2	PEO-3	PEO-4
MS-1	3	2	3	3
MS-2	2	3	2	3

Mapping of Program Educational Objectives (PEOs) to Mission Statements (MS)

(Program Articulation Matrix)

1-Slight; 2-Moderate; 3-Substantial

Graduate Attributes (GAs):

The following *Graduate Attributes* (GAs), attained through the *Program Outcomes* mentioned later, would help the successful students passing through the program to achieve the aforementioned PEOs.

- 1. **Scholarship of Knowledge**: Acquire in-depth knowledge of specific discipline or professional area, including wider and global perspective, with an ability to discriminate, evaluate, analyze and synthesize existing and new knowledge, and integration of the same for enhancement of knowledge.
- 2. **Critical Thinking**: Analyse complex engineering problems critically, apply independent judgment for synthesizing information to make intellectual and/or creative advances for conducting research in a wider theoretical, practical and policy context.
- 3. **Problem Solving**: Think laterally and originally, conceptualize and solve engineering problems, evaluate a wide range of potential solutions for those problems and arrive at feasible, optimal solutions after considering public health and safety, cultural, societal and environmental factors in the core areas of expertise.
- 4. **Research Skill**: Extract information pertinent to unfamiliar problems through literature survey and experiments, apply appropriate research methodologies, techniques and tools, design, conduct experiments, analyze and interpret data, demonstrate higher order skill and view things in a broader perspective, contribute individually/in group(s) to the development of scientific/technological knowledge in one or more domains of engineering.
- 5. Usage of modern tools: Create, select, learn and apply appropriate techniques, resources, and modern engineering and IT tools, including prediction and Modeling, to complex engineering activities with an understanding of the limitations.
- 6. **Collaborative and Multidisciplinary work**: Possess knowledge and understanding of group dynamics, recognize opportunities and contribute positively to collaborative-multidisciplinary scientific research, demonstrate a capacity for self-management and teamwork, decision-making based on open-mindedness, objectivity and rational analysis in order to achieve common goals and further the learning of themselves as well as others.
- 7. **Project Management and Finance**: Demonstrate knowledge and understanding of engineering and management principles and apply the same to one's own work, as a member and leader in a team, manage projects efficiently in respective disciplines and multidisciplinary environments after consideration of economic and financial factors.
- 8. **Communication Skill**: Communicate with the engineering community, and with society at large, regarding complex engineering activities confidently and effectively, such as, being able to comprehend and write effective reports and design documentation by adhering to appropriate standards, make effective presentations, and give and receive clear instructions.

- 9. Life-long Learning: Recognize the need for, and have the preparation and ability to engage in life-long learning independently, with a high level of enthusiasm and commitment to improve knowledge and competence continuously.
- 10. Ethical Practices, Environment and Social Responsibility: Acquire professional and intellectual integrity, professional code of conduct, ethics of research and scholarship, consideration of the impact of research outcomes on professional practices and an understanding of responsibility to contribute to the community for sustainable development of society.
- 11. **Independent and Reflective Learning**: Observe and examine critically the outcomes of one's actions and make corrective measures subsequently, and learn from mistakes without depending on external feedback.

PEOs	GA-1	GA-2	GA-3	GA-4	GA-5	GA-6	GA-7	GA-8	GA-9	GA-10	GA-11
PEO-1	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark					\checkmark	
PEO-2	\checkmark										
PEO-3	\checkmark	\checkmark	\checkmark						\checkmark	\checkmark	\checkmark
PEO-4	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark		\checkmark

Mapping of Graduate Attributes (GAs) to Program Educational Objectives (PEOs)

PROGRAM OUTCOMES (POs):

PO-01	Engineering Knowledge: Apply knowledge of mathematics and computing, science, engineering mechanics fundamentals to the solution of complex engineering problems
PO-02	Problem Analysis: Identify, formulate and analyse complex problems to reach to proper conclusions using first principles of mathematics, natural sciences and engineering sciences.
PO-03	Design/Development of Solutions: Design solutions for complex mechanics based problems and design/develop the processes/software/components which meets specified needs and standards keeping in mind the health, safety, cultural, societal and environmental conditions.
PO-04	Conduct investigations: Conduct investigations of complex engineering problems using research- based knowledge and methods using data analysis and interpretation for provide valid conclusions.
PO-05	Modern Tool Usage: To apply appropriate techniques, resources and engineering and IT tools and knowledge for modelling and simulation of engineering problems with an understanding of the limitations.
PO-06	The Engineer and Society: Apply contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to professional engineering practice.
PO-07	Environment and Sustainability: Understand the impact of professional Engineering solutions in societal and environmental contexts and demonstrate knowledge of and need for sustainable development.
PO-08	Ethics: Apply ethical principles and commit to professional ethics responsibilities and norms of Engineering practice.
PO-09	Individual and Team Work: Function effectively as an individual, and as a member or leader in diverse teams as well as in multi-disciplinary settings.
PO-10	Communication: Communicate effectively with the engineering community and with society at large and being able to comprehend and make effective reports/documents and effective presentation.
PO-11	Project Management and Finance: Demonstrate knowledge and understanding of management principles and apply these to one's own work, as a member and leader of a team, to manage projects and in multidisciplinary environments.

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PO 12	Life-long	Learning:	Recognize	the	need	for	the	preparation	and	ability	to	engage	in
10-12	independe	nt and life-	long learnin	g in t	he bro	ades	t con	text of techno	ologic	al chang	ge.		

Program Specific Outcomes (PSOs)

PSO-01	Graduates will be able to apply fundamental knowledge of mathematics, science and engineering
	mechanics to investigate, identify, formulate and design complex problems in the engineering and
	computational mechanics and allied multidisciplinary areas.
PSO-02	Graduates will be able to develop and apply the appropriate techniques and modern engineering
	tools to solve complex real-life problems by working with multi-disciplinary team and inculcate
	skills for life-long and self-learning.

POs	PEO-1	PEO-2	PEO-3	PEO-4
PO-1	3	3	2	2
PO-2	3	3	1	1
PO-3	3	3	3	1
PO-4	2	2	1	1
PO-5	2	1	1	1
PO-6	1	3	1	1
PO-7	2	2	1	1
PO-8	1	1	3	2
PO-9	1	3	2	1
PO-10	1	1	3	1
PO-11	2	2	1	3
PO-12	1	1	2	2
PSO-1	3	2	1	1
PSO-2	1	1	3	2

Mapping of Program Outcomes (POs) to Program Educational Objectives (PEOs)

1-Slight; 2-Moderate; 3-Substantial

Course Structure and Detailed Curriculum

Semester wise Credit Distribution										
Semester	I	II	III	IV	V	VI	VII	VIII	Total	
Credits	23	23	26	26	22	22	15	14	161	

Semester I											
Code	Category	Course Name	L	Τ	Ρ	С	Hrs.				
CYN11502/ XXXXXX	CEF	Engineering Chemistry -II/Physics-1	2	1	2	4	5				
MAN11101	CEF	Mathematics-I	3	1	0	4	4				
HSN11600/CSN11601	PCE	Professional Communication/Introduction to Artificial Intelligence and Machine Learning	2	0	2	3	4				
AMN11101	CEE	Materials Science and Engineering	3	0	0	3	3				
AMN11102	CEE	Engineering Mechanics	3	0	2	4	5				
CHN11102	CEE	Engineering Thermodynamics	3	0	0	3	3				
XXXXXX	EAA	Extra Academic Activity-A/B	0	0	4	2	4				
		Total	16	2	10	23	28				

Semester II											
Code	Category	Course Name	L	Т	Ρ	С	Hrs.				
XXXXXX /PHN12501	CEF	Engineering Chemistry -II/Physics-1	2	1	2	4	5				
MAN12107	CEF	Mathematics-II	3	1	0	4	4				
HSN12600/CSN12601	PCE	Professional Communication/Introduction to Artificial Intelligence and Machine Learning	2	0	2	3	4				
CSN12401/ XXXXXX	CES	Data structures/Introduction to Simulation Tools/Engineering Innovation and Design/Introduction to Engineering and Design	2	0	2	3	4				
AMN12102	CEE	Fluid Mechanics	3	0	0	3	3				
MEN12102	PCE	Engineering Graphics	1	0	2	2	3				
CHN12400	PCE	Environment and Climate Change	2	0	0	2	2				
EAN12700-12705	EAA	Extra Academic Activity-A/B	0	0	4	2	4				
		Total:	15	2	12	23	29				
Extra Academic Activity-A: Professional Ethics and Social Values											
Extra Academic Activ	ity-B: (Optio	ns) Yoga, Language, Health, Multimedia, Sports and other a	vailat	ole c	hoice	s					

Semester III											
Code	Category	Course Name	L	Т	Ρ	С	Hrs.				
MAN13103	CEE	Linear Algebra and Discrete Mathematics	4	0	0	4	4				
AMN13107	CEE	Mechanics of Solids	3	0	0	3	3				
AMN13108	CEE	Biology for Engineers	3	0	0	3	3				
AMN13109	CEE	Thermo-Fluids Engineering	3	0	2	4	5				
AMN13105	CEE	Data Sciences and Machine Learning in Mechanics	3	0	2	4	5				
AMN13110	CEE	Engineering Analysis and Design	3	0	0	3	3				
XXXXXX	HSS	Management Concepts and Application/Business Economics	3	0	0	3	3				
XXXXXX	EAA	Extra Academic Activity-B*	0	0	4	2	4				
		Total:	22	0	4	26	30				

Semester IV											
Code	Category	Course Name	L	Т	Ρ	С	Hrs.				
AMN14102	CEE	Applied Mathematics and Computation	3	0	2	4	5				
XXXXXX	CEE	Analysis of Algorithms	3	0	2	4	5				
	GEE	OR MOOC/SWAYAM course #									
AMN14105	CEE	Advanced Mechanics of Solids	З	0	2	4	5				
AMN14106	CEE	Advanced Fluid Mechanics	З	0	0	3	3				
AMN14107	CEE	Biomechanics	3	0	0	3	3				
AMN14108	CEE	Dynamics of Mechanical Systems	3	0	0	3	3				
XXXXXX	HSS	Management Concepts and Application/Business Economics	3	0	0	3	3				
XXXXXX	EAA	Extra Academic Activity-B*	0	0	4	2	4				
		Total:	21	0	10	26	31				

		Semester V								
Code	Category	Course Name	L	Т	Ρ	С	Hrs.			
AMN15102	CEE	Continuum Mechanics and Constitutive Modeling	4	0	0	4	4			
AMN15103	CEE	Finite Element Methods	3	0	2	4	5			
AMN15300	MN15300 CEE Tinkering Lab									
AMN15104	CEE	Compressible Flow and Computations	3	0	0	3	3			
AMN15105	CEE	Design and Analysis of Experiments	3	0	0	3	3			
XXXXXX	CEL	Core Elective-I	3	0	0	3	3			
XXXXXX	EAA	Extra Academic Activity-B*	0	0	4	2	4			
		Total:	16	0	10	22	28			

		Semester VI								
Code	Category	Course Name	L	Т	Ρ	С	Hrs.			
AMN16351	CEE	Group Project	0	0	6	3	6			
AMN16101	CEE	Computational Fluid Dynamics	3	0	2	4	5			
AMN16102	N16102 CEE Mathematics for Geometrical Modeling									
AMN16103	CEE	Engineering Vibrations	3	0	0	3	3			
XXXXXX		Core Elective-II OR	3	0	0	3	3			
XXXXXX	UEL	MOOC/SWAYAM course#								
XXXXXX	HSS	Soft Skill and Personality Development	2	0	1	3	3			
XXXXXX	EAA	Extra Academic Activity-B*	0	0	4	2	4			
		Total:	14	0	15	22	29			

		Semester VII									
Code	Category	Course Name	L	Т	Ρ	С	Hrs.				
AMN17352	CEE	Group Project/Research Project	0	0	6	3	6				
AMN17101	CEE	Digital Image Processing	3	0	2	4	5				
XXXXXX	CEL	Core Elective-III	3	0	0	3	3				
XXXXXX	CEL	Core Elective-IV/MOOC/SWAYAM course#	3	0	0	3	3				
XXXXXX	EAA	Extra Academic Activity-B*	0	0	4	2	4				
		Total:	9	0	12	15	21				
* Optional Courses: Yoga, Language, Health, Multimedia, Sports and other available choices											
# Computer Graphics/Data Mining/Artificial Intelligence/Database Management Systems/High Performance computing/Parallel											

		Semester VIII					
Code	Category	Course Name	L	Т	Ρ	С	Hrs.
AMN18353	IT/GP	Industrial Training/Major Project	0	0	28	14	28
		Total	0	0	28	14	28
		Elective-I & II (V & VI Semester, ONE in each)					
	CEL	Optimization-I	3	0	0	3	3
	CEL	Mechanical Behaviour of Materials	3	0	0	3	3
	CEL	Aerodynamics	3	0	0	3	3
	CEL	Mechanical System Design	3	0	0	3	3
	CEL	Structural Mechanics	3	0	0	3	3
		Elective-III & IV (VII Semester, Any two)		-	-	-	
	CEL	Optimization-II	3	0	0	3	3
	CEL	Soft Robotics	3	0	0	3	3
	CEL	Characterization of Materials	3	0	0	3	3
	CEL	Product Design and Development	3	0	0	3	3
	CEL	Bio-Fluid Dynamics	3	0	0	3	3
		Honors (4-5 subjects)		-	-	-	
	CEL	Advanced Bio-Mechanics	4	0	0	4	4
	CEL	Biomimetics	4	0	0	4	4
	CEL	Poromechanics	4	0	0	4	4
	CEL	Mechanics of Composite Materials	4	0	0	4	4
	CEL	Multiscale Modeling	4	0	0	4	4
	CEL	Structural Reliability	4	0	0	4	4
	CEL	Structural Stability and Dynamics	4	0	0	4	4
	CEL	Advanced Heat Transfer	4	0	0	4	4
	CEL	Boundary Layer Theory	4	0	0	4	4
	CEL	Turbulent Flows	4	0	0	4	4
	CEL	Advanced Computational Fluid Dynamics	4	0	0	4	4

	Course Code	: AMN′	11101		N	lateria En	ls Scie gineer	nce an ing	d		Credits (I	T-P-Cr	: 3-0-0-	3
Pre-re	quisites: NIL						<u> </u>							
							Course	Outco	me					
S. No.					0	utcome	es					BT	BT D	escription
												Level		
CO1	Understand role	e of stru	cture at	differer	nt level o	on prop	erties.					1, 2	Rei Un	member, derstand
CO2	Apply concepts	of Mate	erials Sc	cience to	o analyz	ze engin	neering	problem	IS.			3, 4	Appl	y, Analyze
CO3	Select materials	s for diff	erent er	ngineeri	ng appl	ications	<u>.</u>					3		Apply
CO4	Predict the mec	hanical	, therma	al, electr	rical, ma	agnetic,	piezoel	ectric a	nd othe	r importai	nt properties.	3, 4	Appl	y, Analyze
					Articu	lation I	Matrix:	(CO-PC)-PSO I	Mapping)				
CO	PO1	PO2	PO3	PO4	PO5	P06	P07	PO8	PO9	PO10	PO11	P012	PSO1	PSO2
C01	2	1	-	1	1	1	-	1	-	2	2	2	3	3
CO2	3	3	2	2	3	1	-	1	2	2	1	2	3	3
CO3 3 3 3 3 2 2 2 2 1 2 CO4 2 3 2 1 5 5 5 1 1 1 1 1 1													3	3
CO4 2 3 2 1 - - - 2 1 1 1 Mod Svilabus													3	3
Mod Syllabus Hours												lours		
1	Introduction: Historical perspective of Materials Science; Structure and properties relationship of Engineering 05 Materials; Classification of materials; Introduction to Ceramics, Composites Materials: Processing and Applications; Advanced Materials. 05											05		
2	Structure of S Metallic structur computations, (Thermal charac	olids a res; Cer Crystallo terizatio	amic cr amic cr ography on techr	aracteri ystal str , Diffrac niques.	zation ructures rtion me	of Mate ; Crysta ethods, I	erials: allograpl Metallog	Introduc hic direc graphy,	ction to ctions a Introdu	crystal s nd planes ction to E	tructures and s , Miller indices, lectron microsc	systems; , Density copy and		07
3	Imperfections	in Crys	tals: ⊺y	pes of i	mperfe	ctions, [Dislocat	ions, Su	irface a	nd Bulk d	efects			03
4	Diffusion: Diffu Law's of diffusion	usion m on, Appl	echanis ications	sms, ste of Diffu	eady an usion.	id non-s	steady	state dif	ffusion,	Factors	that influence of	diffusion,		03
5	Phase Diagram Eutectoid, Perito and property ch	ns anc ectic an anges i	I Phase d perite n iron-c	e Trans ctoid re arbon s	sformat actions ystem,	t ions: (, Transf Iron-Ca	Unary, ormatio rbon (Fe	Binary, n rate e e-C or F	Equilib ffects a e-Fe3C	rium pha nd TTT d C) Diagrar	se diagrams, iagrams. Micros n.	Eutectic, structure		05
6	Mechanical Be	haviou	r of Ma	terials:	Elastic	and Pla	astic pro	perties,	Fatigue	e, Fractur	e, Creep.			10
7	 Thermal, Electrical, Magnetic, Optical Properties: Thermal behaviour of Materials; Electrical conduction, Semi conductivity, Super conductivity, Dielectric behaviour, Ferroelectricity, Piezoelectricity, Magnetic behaviour of Materials; Optical properties of materials and their applications 													
							Refe	rences						
• " • " • "	 "Materials Science and Engineering: An Introduction" by William D. Callister Jr., David G. Rethwisch. "Materials Science and Engineering: A First Course" by Raghavan V. "Mechanical Metallurgy" by George E. Dieter "Elements of materials science and engineering" by Lawrence H. Van Vlack 													

Cou	urse Co	ode: AN	/IN1110)2		Engin	eering l	Mechan	ics		Credits	s (L-T-P	-Cr): 3-0-	2-4
Pre-requisit	es: Non	e												
							Course (Outcom	e					
S.No.					Ou	tcomes					BT Lev	el	BT Des	cription
CO1	Identit the he equat	fy and q elp_of_fr ions of e	uantify a ee bod quilibriu	all the e y diagra ım.	xternal ams, the	forces a eir resul	ssociated tant and	d with the its loca	e rigid b ition and	ody with I use of	2, 3		Understa	ind, Apply
CO2	To loc and a	ate the ossessme	centroid ent of th	of an ar e interna	ea and o al forces	calculate in beam	the mon	nent of in	ertia of a	a section	2, 3		Understa	ind, Apply
CO3	Apply	Newton	s laws c	of motior	n to part	icles and	l rigid bo	dies.			3, 4		Apply/	Analyze
CO4	Solve simple	the pro progra	blems ms for p	involvinę roblems	g kinem s of real	natics, ei life.	nergy ar	nd mome	entum a	nd write	5		Eva	luate
					Articu	ulation M	Aatrix: (O	CO-PO-F	PSO Map	oping)				
CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01													PSO2	
CO1	3 3 3 3 3 3												3	3
CO2	3 3 3 3 3 3												3	3
CO3	3	3	3	3	3	-	-	-	-	-	-	-	3	3
CO4	3	3	3	3	3	2	-	-	2	2	-	-	3	3
Module							Sylla	bus						Hours
1	Reviev Shear	w of For force, a	ce, mon nd Bend	nent and ding moi	d Couple ment dia	e, Equilik agrams.	prium of I	rigid bod	ies, Cen	troid and	Moment o	f inertia,	Beams -	15
2	Kinem Impuls Kinetio	atics an se & Moi cs of sys	d Kinetio mentum stem of p	cs of par , Impact particles	ticles: F , and C : Conse	Plane and entral Fo ervation o	d Space r prce Moti of Energy	motion, F on. ⁄ and Mo	orce, Ma	ass and A , Steady r	cceleratior nass flow,	n, Work & Variable	Energy, mass.	10
3	Plane zero v	Kinema elocity, l	tics and Rotating	l Kinetic Jaxis, Fo	s of a r orce, Ma	igid bod ass and	y: Relativ Accelera	ve veloci tion, Wo	ity and A rk & Ene	Acceleration rgy, Impu	on, Instant Ise & Morr	aneous o ientum.	centre of	12
4 Introduction to three-dimensional kinematics and kinetics of rigid bodies.										03				
Experiments on parallel and concurrent forces, sliding friction, rolling resistance, moment of inertia, SFD/BMD and profor static and dynamic problems										orogramming				
References														
• Meriam J.L., Kraige L.G and Bolton J.N., Engineering Mechanics Statics and Dynamics, 9ed (An Indian Adaptation), Wiley I											ley India.			
 Beer F. Shames 	P. and J	noineeri	I E.K., N na Mech	lechanic nanics	CS TOT EI Prentice	ngineers	– VOI.1- w Dolhi	Statics,	vol.2- D	ynamics, l	vicGraw H	III, New `	rork.	

Shames I.H., Engineering Mechanics, Prentice Hall, New Delhi.
Hibbeler R.C., Engineering Mechanics - Vol.1 – Statics, Vol.2- Dynamics, Pearson Press.

Co	Course Code: AMN12102Fluid MechanicsCredits (L-T-P-Cr) : 3-0-0-3e-requisites: Engineering Mechanics, Mathematics-I												-0-3	
Pre-requ	requisites: Engineering Mechanics, Mathematics-I Course Outcome													
	1					Cou	ırse Out	come						
S.No.					Outco	omes					BT Leve	I B'	Г Descrij	ption
CO1	To giv applica	e fundar ation of n	nental k nass, mo	nowledg mentum	e of flui and ene	id, its pı rgy equa	roperties ation in f	, hydrost luid flow	tatic law	s and	2		Understa	nd
CO2	To dev and los	velop und sses in a t	lerstandi flow sys	ng about tem.	Dimens	sional Ar	nalysis, c	lifferent	types of	flows	2		Understa	nd
CO3	To lear	rn the im	portance	of flow	measure	ments ar	nd its app	plications	s in Indu	stries.	3		Apply	
CO4	To dev	elop bas	ic know	ledge of I	hydrauli	c machii	nes and i	ts applic	ations.		3, 4	A	pply/Ana	alyze
	1	1		Ar	ticulatio	on Matr	ix: (CO	-PO-PSO) Mapp	ing)	-	•	•	
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	2	1	1	1	-	-	-	-	-	-	2	3	3
CO2	3	2	1	1	2	-	-	-	-	-	-	1	3	3
CO3	-	-	2	-	2	-	-	-	-	-	-	-	3	3
CO4	3	3	2	-	-	-	-	-	-	-	-	2	3	3
Module			-				Syllab	ıs	-	-				Hours
2	e Syllabus I Introduction to Fluid Mechanics: Statics and Kinematics Fluid and continuum, Physical properties of fluids, Types of fluid flows, Rheology of fluids. Manometers, pressure transducers, pressure on plane and curved surfaces, centre of pressure, Kinematics of Fluid flow: steadiness, uniformity, rotational and irrotational flows, streamline, streakline, pathline, continuity equation, stream function and velocity potential, applications of potential flow. Dynamics Of Fluid Flow and Dimensional Analysis: Euler's Equation of motion along a streamline and its integration, Bernoulli's equation and its applications, momentum equation and its application to pipe bends. Dimensional Analysis, Buckingham's Pi theorem, important dimensionless numbers and their physical significance, geometric, kinematic and dynamic similarity, model studies, Hydraulic similitude. Laminar and Turbulent Flows: Equation of motion for laminar flow through pipes, Stokes law, transition from laminar to turbulent flow, types of turbulent flow, isotropic and homogenous turbulence, scale and intensity of turbulence, eddy viscosity, Prandtl's mixing length theory, velocity distribution in turbulent flow over smooth and rough surfaces, resistance to flow, minor losses, pipe in series and parallel, power transmission through a pipe.												08	
4	Introduction to Hydraulic Machines: Flow measurement by Pitot tube, orifice, Venturi, nozzle, and bend meter, rotameter, Introduction to Hydroultion to Hydroelectric power station and its											08		
	components, Classification of turbines and pumps, similarity laws and specific speed, efficiency, cavitation. References													
 Muns Hoch Fox, Som, Moha Sham Agar 	References Munson, Young and Okiishi's Fundamentals of Fluid Mechanics, 9e by Philip M. Gerhart, Andrew L. Gerhart, John Hochstein, Wiley. Fox, R.W., McDonald, A.T., Introduction to Fluid Mechanics, 7th edition, Wiley India. Som, S.K. and Biswas G, Introduction of Fluid Mechanics & Fluid Machines, TMH, New Delhi. Mohanty, A.K., Fluid Mechanics, PHI Learning, New Delhi. Shames, I.H., Mechanics of Fluids, McGraw Hill, International Students Edition. Agarwal, S.K., Fluid Mechanics and Machinery, TMH, New Delhi.												John I.	

- Rathakrishnan E., Instrumentation, Measurements and Experiments in Fluids, CRC Press, New York
- Jagdish Lal, Fluid Mechanics, Metropolitan Book Company Ltd., Delhi.

Course Code: MAN13103

Linear Algebra and Discrete Mathematics

Credits (L-T-P-Cr) : 4-0-0-4

Pre-requisites: Mathematics-I, II	
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Course Outcome S.No. Outcomes BT Level BT Description														
S.No.	S.No. Outcomes BT Level BT Descrip CO1 Understand the basic concepts of linear algebra, such as vector spaces, basis, dimension, linear transformation, solvability of a system of linear equations, etc. 2 Understand													
CO1	Unders dimens	stand the sion, line	basic c ar transf	oncepts ormatior	of linear	algebra algebra	, such a system o	s vector	spaces, equation	basis, s, etc.	2		Understa	ind
CO2	Unders diagon	stand the alization	basic co , and its	ncepts li applicat	ke eigen [.] ion to so	values, e lve engi	igenvect neering p	or, quadi problems	ratic forr 5.	n, and	2, 3	Uno	lerstand,	Apply
CO3	The un relation	nderstand	d and a oolean a	pply the lgebra	concep	ots of n	nathemat	ical log	ic, recu	rence	2, 3	Uno	lerstand,	Apply
CO4	Unders	stand the	simple of	concepts	of Grap	h theory	•				2		Understa	ınd
				Ar	ticulatio	on Matr	ix: (CO-	-PO-PSO	Э Марр	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	1	-	-	2	-	1	1	3	3	3
CO2	3	3	3	1	1	-	-	-	-	1	1	3	3	3
CO3	3	3	3	1	1	1	1	-	-	1	-	3	3	3
CO4	3	3	3	1	1	1	2	2	1	2	3	3	3	3
Module							Syllabu	us	1			I	1	Hours
1	Linear Algebra: Group, Ring, Field, Vector spaces, Subspaces, Linear dependence and independence, Basis and dimension, Dimension theorem. Eigenvalues and Eigenvectors: Linear Transformation, Rank–Nulity Theorem (Statement only),												7	
2	and dimension, Dimension theorem. Eigenvalues and Eigenvectors: Linear Transformation, Rank–Nulity Theorem (Statement only), Computation of Rank and nullity of LT, Eigenvalues and Eigenvectors, Cayley-Hamilton theorem, Application of Eigenvalues and Eigenvectors: Quadratic form, Diagonalization, Canonical forms.												9	
3	 Computation of Rank and nullity of L1, Eigenvalues and Eigenvectors, Cayley-Hamilton theorem, Application of Eigenvalues and Eigenvectors: Quadratic form, Diagonalization, Canonical forms. Mathematical Logic: Statements, Connectives, Statement Variables and Formulas, Tautologies, Equivalences and Implications, Disjunctive and Conjunctive Normal Forms, Inference Theory in Statement Logic Indirect Proofs 												7	
4	Combi and Un Relatio	natorics ordered ns (Diffe	: Permu Partition erence E	tations a s, Sterlin quations	nd Com 1g Numb), Solutio	bination ers of Fi on by Ch	s, Permu rst and S naracteris	itations a Second K stic Root	and Com find, Par ts, Gener	bination tition Fur ating Fu	s with rep nctions, Li nctions.	etitions (inear Rec	Ordered urrence	9
5	Lattice Modula Boolea	es and l ar and Di n Algebi	Boolean istributiv ras, Bool	Algebre ve Lattice lean Fun	a: Bool es, Comp ctions, F	ean Ma olements ree Bool	trices, B , Boolea lean Alg	Boolean n Algebr ebras, Re	Product, a, Stone	Partiall Represe ip with S	y Ordered ntation Th Statement	1 Sets, I neorem fo Logic.	Lattices, or Finite	9
6	Introd Binary maps, 0	uction to tree, spa Graph co	o Graph anning tr louring.	Theor ree, conn	y: Funda ectivity,	optimal	concepts graph ti	of grap raversals	hs and d , Planar	igraphs, ity of Gr	Tree and aphs, Dra	their pro wing gra	perties, phs and	10
	References													
 R.K. Jain & S.R.K. Iyenger, Advanced Engineering Mathematics, 5th edition, 2016, Narosa Pub. B.S. Grewal, Higher Engineering Mathematics, 44nd edition, 2018, Khanna Publishers. D.B.West, Introduction to Graph Theory, Prentice-Hall of India/Pearson J.A. Bondy and U.S.R.Murty, Graph Theory and Applications (Freely downloadable from Bondy's website; Google-Better Tremblay and Manohar, Discrete Mathematical Structures. Kolman, Busby and Ross, Discrete Mathematical Structures 												-Bondy)		
 Mo Erv 	tt, Kand vin Krey	el and Ba szig, Ad	aker, Dis vanced I	screte Ma Engineer	athemati ing Matł	cal Struc nematics	ctures , 10th Ec	lition, 20)15, Johi	n Wiley a	& Sons.			

• Qazi Zameeruddin & Surjeet Singh, Modern Algebra, 9th edition 2021, S Chand Publication

Course Code: AMN13107Mechanics of SolidsCredits (L-T-P-Cr) : 3-0-0Pre-requisites: Engineering Mechanics											0-0-3			
Pre-requisites: Engineering Mechanics Course Outcome C. No. Orteomore														
							Course	Outcon	ne					
S. No.						Ou	tcomes						BT	BT
													Level	Description
CO1	Under	stand the	he conc	ept of	internal	forces	and m	oments,	stress,	strain,	deformat	tions in	2	Understand
	memb	ers subj	ected to	axial, b	ending	and tors	sional lo	ads						
CO2	Comp elastic	rehend t ty	the conc	epts of p	orincipa	l stresse	es and st	rain to s	olve the	problem	is of engi	neering	2	Understand
CO3	Apply compo	the cor onents s	ncepts to uch as b	o calcula beams, sl	te stress naft, she	s, strain ells and	, and dis springs	splacem	ents in e	engineeri	ng struct	ture and	3	Apply
CO4	Analy by cor	se the n sidering	nechanio g approp	cal engin priate fai	neering	structui teria an	res and o d design	compon require	ents for ments.	safer me	echanical	l design	4	Analyze
Articulation Matrix: (CO-PO-PSO Mapping)														
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 3 3 2 1 5 2 5 1 1 3 3													PSO1	PSO2
CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 3 3 2 1 - - 2 - 1 1 3 3 CO2 3 3 3 1 1 - - 2 - 1 1 3 3														3
CO1 3 3 3 2 1 - - 2 - 1 1 3 3 CO2 3 3 3 1 1 - - - 1 1 3 3 CO3 3 3 3 1 1 - - - 1 1 3 3														3
CO2 5 5 5 1 1 - - - 1 1 5 5 CO3 3 3 3 1 1 - - - 1 1 3 3														3
Module Syllabus													Hours	
1	Stress	and St	train: U	Jniaxial	Stress a	and Stra	in, Hoo	ke's La	w, Stres	ss-Strain	Curves,	Elastic (Constants,	6
2	Strain Biovid	Energy	, Statica	Strain:	Stross	ot o E	ems, 1n	tross Tr	meets, 1	mpact Lo	bading.	of Strai	n Strain	8
2	Displa	icement	Relation	ns, Strai	n Trans	formati	on, Strai	in Meas	urement	s, Princip	pal Stress	ses and S	train	0
3	Bendi Beams	ng and s, Asym	Shear metric I	Stresses Bending	S: Pure	Bendin	g, Norn	nal Stres	s and S	hear Stre	esses in	beams, C	Composite	6
4	Torsic	on of Sl	haft, Sp	orings, a	nd Pre	ssure V	essels:	Torsion	of Circ	ular Sha	ft, Power	r Transm	itted by a	6
5	Shaft,	Compo	und Sha	ift, Com	bined L	oadings	$\frac{1}{2}$, Thin-V	Nalled S	hells, and do for	nd Spring	gs (Open	and Clos	sed Coils)	e
5	Integra	ation, M	facaulay	's Meth	od, Moi	ment-A	rea Metl	hod, Cas	tigliano	's Theor	em	enections	S. Double	0
6	Colun	nns and	d Theor	ries of	Failure	: Euler	's Theo	ry for I	Long Co	olumns,	Rankine	-Gordon	Formula,	6
	Eccen	trically	Loaded	Column	s, Theo	ries of f	failure	•	0					
							Refe	rences						
•]	Mechan	ics of M	laterials	, Gere a	nd Time	oshenko	, CBS P	ublication	ons.					
• Introduction to Mechanics of Solids, Crandall, Dahl and Lardener, Tata Mcgraw Hill Publications.														
• Mechanics of materials, Hibbert, R.C., 2005, Pearson Education.														
 Elements of Strength of Materials, S.P. Timoshenko and D.H. Young, East-West Press Pvt. Ltd. Publication Mechanics of Materials, Pytel and Kiusalaas, Cangage Learning Publications 												ns.		
 Mechanics of Materials, Pytel and Kiusalaas, Cengage Learning Publications. Mechanics of Materials, F. P. Popov, Prentics Hall Publications. 														
•	Strength	of Mat	erials. G	,	der. Ma	cmillan	India L	imited						
•	Strength	of Mat	erials, P	ytel and	Singer,	Harper	collins (College	division	publicat	tions.			

• Mechanics of Materials, Riley, Struges and Morris, John Wiley & Sons.

Course Code: AMN13108Biology for EngineersCredits (L-T-P-Cr): 3-0-0-3Pre-requisites: NIL											0-3				
Pre-requisites: NIL Course Outcome S No Outcomes BT Level BT Description															
	1					Cou	irse Out	come							
S. No.					Outco	omes					BT Level	B B	Г Descrij	ption	
CO1	To der	nonstrat	e a com	prehensi	ve unde	rstandin	g of the	e princip	les of h	uman	2,4	Unde	erstand, A	Analyse	
	physio	logy and	their a	pplicatio	on to en	gineerin	g, allow	ing then	n to inte	egrate					
CO2	To ana	ilvze and	l explair	the inte	errelation	ig conce	etween d	different	physiol	ogical	23	Unc	lerstand	Apply	
002	system	s enablii	ng them	to identi	fy and a	ddress e	ngineeri	ing chall	enges in	these	2, 5	Circ	ierstand,	rippiy	
	areas.		0		5		U	e	8						
CO3	To dev	elop the	necessar	y skills t	o apply j	physiolo	gical kno	owledge	to engine	eering	2, 4, 5	Unde	erstand, A	Analyse,	
	innova	tions and	applica	tions in I	healthca	re							Evaluati	on	
CO4	To eff	ectively	collabo	rate in	interdisc	iplinary	teams,	to com	municate	e and	2, 4, 5	Unde	erstand, A	Analyse,	
	exchan	ge ideas	with pro	ofessiona	ls from o	lifferent	fields, a	nd apply	knowled	lge to			Evaluati	on	
	healthc	are and	biomedi	novation cal engin	leering	ethical	awarene	ss m u	ie purst	III OI					
	nounne	ui e uiia	oronicar	Ar	ticulatio	on Matr	ix: (CO	-PO-PSO) Mapp	ing)					
СО	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 3 3 3 2 1 - - 2 - 1 1 3 3														
CO1	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$														
CO2	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$														
CO3	3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$													
CO4	2	3 2 2 1 1 - 1 1 - 1 2 2 3 3 2 1 2 2 2 2 1 2 1 2													
Module															
1	Ie Syllabus Cell: Structure and organelles - Functions of each component in the cell. Cell membrane – transport across membrane – Origin of cell membrane potential – Action potential. Homeostasis - Tissue: Types – Specialized tissues – functions. Blood: Blood composition - functions of blood – functions of RBC.WBC types and their functions Blood groups – importance of blood groups – identification of blood groups.												8		
2	Muscu Adapta Types	loskelet tion and of Joints	al Syste Remode , Major I	e m – S elling, Bo <u>Muscles</u>	keletal one Diso of Limb	Anatom rders, M s, and th	y, Bone uscle Tis eir action	e Compo ssue, Stru ns.	sition, icture of	Bone T Skeletal	Muscle, T	Types of I	, Bone Muscle,	8	
3	Cardio Homeo aspects	ovascula ostasis –(, Ventila	r syster Cardiac ators, Ox	n – Hea output – ygen Th	rt and Coronai erapy.	vascular y and P	system eriphera	, Lympl l Circula	natic Sy tion – H	stem E leart Sou	CG – Bl inds. Bohi	ood Pres	ssure – Applied	6	
4	Respir Oxyger – Card	atory sy n and car io-pulme	v stem: C bon dioz onary Re	Compone tide trans suscitation	nts of re sport and on	espirator l acid ba	y systen se regula	n – Resp tion. Pul	iratory l monary	Mechanis function	sm. Types test – Arti	of respi ficial res	ration - piration	6	
5	5 Gastro urinal system - Digestion, and absorption – Movement of GI tract, Structure and function of kidneys and Nephron – Mechanism of Urine formation – Urine Reflex – Skin and Sweat Gland – Temperature regulation.												5		
6 Nervous System – Structure and functions of Neurons, Synapse, Reflex action, and Receptors – Velocity of Conduction of Nerve Impulses – Nervous control of Heart.												5			
						I	Reference	es							
 References Essential of Human Anatomy and Physiology by Elaine.N. Marieb, Pearson Education, 11th Edition. The Human Body: An introduction for Biomedical and Health Sciences by Gillian Pocock, Christopher D. Richards, Oxf University Press, USA Introduction to the human body: the essentials of anatomy and physiology by Gerard J Tortora and Bryan Derrickson, J Wiley & Sons, 8th Edition. 													, Oxford on, John		

• Physiology for Engineers: Applying Engineering Methods to Physiological Systems by Michael Chappell and Stephen Payne, Springer, Biosystems & Biorobotics Volume 13.

Course Code: AMN13109Thermo-Fluids EngineeringCredits (L-T-P-Cr) : 3-0-2-4Pre-requisites: Fluid Mechanics, Thermodynamics										-2-4				
Pre-requisites: Fluid Mechanics, Thermodynamics Course Outcome														
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Level	I B'	Г Descrij	ption
CO1	To ide	ntify the	rmodyna	amic sys	tems, su	ırroundiı	ngs, wor	k and he	eat intera	action	2		Understa	nd
	using f	luids and	their ch	naracteris	stics in v	arious th	nermody	namic pr	ocesses.	_		_		_
CO2	To ide interac	ntify an tion e.g.,	d apply conduct	modes tion and	of heat convecti	transfer	related	to fluid	s and su	urface	3, 4	Ar	nalyze / A	vpply
CO3	To und	lerstand t	the conce	epts of th	nermody	namic la	ws and l	Entropy.			2		Understa	nd
	<u> </u>			Ar	ticulati	on Matr	ix: (CO	-PO-PSO) Mappi	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	2	1	1	1	-	-	-	-	-	-	2	3	3
CO2	3	3	3	1	2	-	-	-	-	-	-	1	3	3
CO3	-	3	1	-	1	-	-	-	-	-	-	-	3	3
Module							Syllab	us						Hours
1	Basic I	Equation	ns and St	teady Sta	ate Con	duction:	General	three-di	mension	al heat co	onduction	equation,	, Steady	10
	one-dimensional heat conduction through simple and composite planes, cylindrical and spherical walls without heat generation. Effect of variable thermal conductivity. Critical thickness of insulation. Steady one-													
	without heat generation, Effect of variable thermal conductivity, Critical thickness of insulation. Steady one-													
	dimensional heat conduction through plane wall, hollow cylinder, solid cylinder and solid sphere with uniform													
	heat ge	eneration	, Heat ti	ransfer f	rom finr	ned surfa	aces, gen	ieral equ	ation, ef	ficiency	and effec	tiveness	of fins,	
	conduc	tion in co	ooling of	turbine	balding,	optimur	n dimens	sions, con	mparisor	of fin m	aterials. T	wo-dime	ensional	
2	steady	state nea	t conduc	Contraction, Nu	merical	and grap	h C i l'	ethods, A	nalogica	ii solutio	n.			00
2	Unstea	iay State	e Heat v		Ion: He	anng and		ig with no.		e interna		Tronoio	erature-	Uð
	conduc	tion in se	or therm	nocoupie	s Lapla	ig and o	coomig ation Ser	with neg	of Varial	surrace	ned capa	citance n	othods	
	Heatin	α and C_{α}	oling of	f infinite	s, Lapia nlate v	vith finit	e intern	al and si	urface re	sistance	Numeric	al and ou	ranhical	
	analysi	s and Co	Joining U	1 mmmu	plate v	vitii iiiiit		ai and se		sistance,	Tumerie	ai and gi	apinear	
3	Conve	ction: La	aminar a	nd turbu	lent floy	v hvdro	dynamic	and the	rmal bou	ındarv la	ver Dime	ensional a	analysis	10
Ũ	and dir	nensionl	ess num	bers for	free and	forced c	convectio	on. Empi	rical rela	tions an	d practical	l solution	of free	10
	and for	rced con	vection	in pipes	, over p	lates an	d across	cylinde	rs and s	pheres,	combined	free and	forced	
	convec	tion, con	nbined fi	ree conv	ection a	nd radiat	ion heat	transfer.						
4	Therm	odynam	ic Laws	s and Er	ntropy:	Reversit	oility and	1 irrevers	sibility, s	statemen	ts of seco	nd law a	nd their	08
	discuss	ion, Equ	ivalence	e of Kelv	vin-Plano	ck and C	lausius :	statemen	ts, Carno	ot engine	e and Cari	not refrig	eration,	
	Therm	odynami	c temper	ature sca	ale and a	bsolute	zero tem	perature,	, Clausiu	s theore	m and Cla	usius ine	quality,	
	concept and characteristics of entropy Principle of increase of entropy and entropy of universe.													
Experime	ents rela	ted to flu	id mech	anics an	nd therm	o-fluids	along w	ith prog	ramming	g on adv	anced pro	blems		
References														
Intro Sons	duction 1, 1991.	to Therm	odynam	ıcs, Clas	sical and	1 Statisti	cal, Thir	d Editior	1, Sonnta	ıg, R.E.,	and Van V	Wylen, G	, John Ŵ	iley and
• Adva	nced En	gineerin	g Therm	odynami	ics, Beja	n, A., Jo	hn Wile	y and So	ns, 1988					
• Adva	nced Th	ermodyn	namics fo	or Engine	eers, Kei	nneth W	ark Jr., N	AcGraw-	Hill Inc.	, 1995.				
• Fund	amental	s of Heat	& Mass	s Transfe	r, Incrop	bera F.P.	and De	Witt. D.P	., John V	Viley &	Sons, 199	6.		

- Analysis of Heat and Mass Transfer, Ozisik. M.N., McGraw Hill Co., 1980.
- Heat Transfer Basic Approach, Eckert. E.R.G., and Drake.R.M., McGrawHill Co., 1985.
- Convection Heat Transfer, Bejan. A., John Wiley and Sons, 1984.

	Course Cod	e: AM	N13105	;	D	ata Scio Learni	ences a ng in N	nd Mac ⁄Iechan	chine ics		C redits (1	L-T-P-(Cr) : 3-0)-2-4
Pre-re	quisites: Ma	thematic	s, Intro	ductory	Comput	er Progr	amming	ç						
						Cour	se Out	come						
S.No.				0	utcom	es					BT Leve	I B'	F Descri	iption
CO1	To demonstr	rate unde	erstandi	ng of the	mather	natical fo	oundatio	ons and p	rogramı	ning	2, 3	Un	derstand,	, Apply
CO2	skills needed	d for dat	a scienc	e and m	achine l	earning	able in l	Maahina	laamin	-	2.4	Und	anstand	Analuza
CO2	To understa		naryze a	in possi				wiachine	learning	9 4: a a 1	2,4	Und		Anaryze
003	application i	to app related to	b Mecha	viacnine mics	Learn	ing for	analyzi	ng vario	ous prac	tical	3		Apply	7
	TI ····			Articu	lation	Matrix	: (CO-	PO-PS	O Map	ping)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	1	2	3	-	-	-	-	-	-	3	3	3
CO2	3	3	2	1	3	-	-	-	-	-	-	3	3	3
CO2 D <thd< th=""> <thd< th=""> <thd< th=""></thd<></thd<></thd<>													3	
CO3333311111333Mod uleSyllabusHou1Introduction to Data Science: Concept of Data Science, Traits of Big data, Web Scraping, Analysis vs Reporting4													Hours	
Mod Syllabus Hour ule 1 Introduction to Data Science: Concept of Data Science, Traits of Big data, Web Scraping, Analysis vs Reporting 4														
Mod uleSyllabusHou1Introduction to Data Science: Concept of Data Science, Traits of Big data, Web Scraping, Analysis vs Reporting4													4	
Mod uleSyllabusHow1Introduction to Data Science: Concept of Data Science, Traits of Big data, Web Scraping, Analysis vs Reporting42Introduction to Programming Tools for Data Science: Toolkits using Python- Matplotlib NumPy Scikit-learn6													6	
	NLTK, Visu	ualizing	Data- B	ar Char	ts, Line	Charts,	Scatter	plots, we	orking w	ith data	- Reading	Files, S	craping	-
	the Web, U	Jsing A	PIs (Ex	ample:	Using t	he Twi	tter AP	ls), Clea	ining ar	nd Mun	ging, Mai	nipulatin	g Data,	
	Rescaling, I	Dimensio	onality F	Reductio	n, Intro	duction	to RStuc	lio						
3	Mathematic	al Found	dations:	Linear	Algebra	- Vecto	rs, Matı	rices; Sta	atistics-	Descrit	ing a Sin	gle Set o	of Data,	4
	Correlation,	Simpso	on's Par	adox, C	Correlati	on and	Causati	on; Prol	bability-	Depen	dence and	i Indepe	ndence,	
	Distribution	Probab	ollity, B Control	ayes's	I heorer	n, Rano	iom Va	riables,	Contini	lous D	istribution	s, The	Normal Tosting	
	Confidence	, The Interval	Phack	LIIIII ing Bay	Theorem Jesian II	п; пур iference	ottiesis	and m	lerence-	Statist	ісаї пуре	Julesis	resting,	
4	Machine Le	arning.	Overvie	$\frac{115, Du}{2}$	Achine	learnin	o conce	nts = 0	ver fitti	no and	train/test	splits T	vnes of	16
-	Machine lea	arning –	Superv	ised. Un	Isupervi	sed. Rei	nforced	learning	z. Introd	uction 1	o Baves 7	Theorem	Linear	10
	Regression-	model	assump	tions, r	egulariz	ation (1	asso, ri	dge, ela	stic net), Clas	sification	and Reg	gression	
	algorithms-	Naïv	e Ba	iyes,	K-Near	est N	Veighbor	rs, lo	gistic	regres	sion, su	apport	vector	
	machines ((SVM),	decisio	on tree	s, and	rando	m fore	st, Clas	ssificatio	on Err	ors, Ana	lysis of	Time	
	Series- Line	ear Syst	ems Ar	alysis,	Nonline	ar Dyn	amics, l	Rule Ind	luction,	Neural	Networks	s Learni	ng And	
F	Generalizati	on	ahir- T		in M	aharia	Carr	C 411 - 1	in also d	Idard'	Sting for 1	tr./bc=1/1		A
3	Applications	s OI Ma irhiilant	Elow	Learning	In Me	CHANICS	Case	Studies	include	cuite F	ying faul ault Data	ty/nealth	y wind Motor	4
	Bearings H	uman A	ctivity R	lecognit	, Leaka	art Soun	d Classi	fication	etc	cuits, 1	aut Dete		10101-	
6	Deen learnir	ng. Intro	duction	to Neur	al Netw	orks Co	nvoluti	$\frac{1}{2}$ and Δ	rtificial	Neural	Networks	Applies	tions in	6
U	Engineering	Mechai	nics Pra	ctical's:	MATL	AB tool	s includ	ling Cur	ve Fittin	g Tool	ox. Classi	fication	Learner	Ū
	App, Deep N	Network	Design	er App,	Tensor	Flow, T	raining 1	nodels o	n GPUs	6	,			
Progra	mming in the	Python	for nree	licting «	necific d	outcom	es and a	nnlicatio	n to the	mecha	nics hased	nrohlen	ns in fail	ure/fault
analysis	S S S S S S S S S S S S S S S S S S S	- juion	, , , , , , , , , , , , , , , , , , , ,	sound s	pecific (, all Onl	s unu u	Phound		monu		PIODU	.s in juli	
						Re	ferenc	es						
• Suc	l, Keshav, Pal	kize Erd	ogmus,	and Seif	edine K	adry, ed	s. Introd	duction t	o Data S	Science	and Mach	ine Lear	ning. Bol	D–Books
on	Demand, 202	0. Zalara 1	Dati	The	T	1 P	1: .1 ·	7	Det			1		
• Kro	bese, Dirk P., 1 l statistical ma	Zaravko ethods. () Botev, CRC Pre	1 nomas	s i aimre).	e, and Ra	adisiav V	v aisman	. Data s	cience c	ina machii	ne tearni	ng: Math	iematical

• Cielen, Davy, and Arno Meysman. *Introducing data science: big data, machine learning, and more, using Python tools*. Simon and Schuster, 2016

Course Code: AMN13110 Engineering Analysis and Design Credits (L-T-P-Cr) : 3-0-0-3 Pre-requisites: Materials Science and Engineering, Mechanics of Solids Course Outcome BT Level BT Description CO1 To Identify and analyze different modes of failures in materials 2, 4 Understand, Analy CO2 To develop understanding of different design approaches in general and some 2, 3 Understand, Appl methods used in design To develop skill of material selection for the specific task based on different 4 Analyze CO4 To evaluate the material's performance with reference to the cost, societal health 5 Evaluate and safety Articulation Matrix: (CO-PO-PSO Mapping) Evaluate 2 3 1 - - - 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 3 2 3 3 2 3											0-0-3			
Course Course Court. Arrivering Engineering Analysis and Design Creatis (E - F1 - C1) : 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5 - 5														
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Level	I B'	Г Descri	ption
CO1	To Ide	ntify and	analyze	differer	nt modes	of failu	res in ma	terials			2,4	Unde	erstand, A	Analyze
CO2	To dev method	velop und is used in	derstandi n design	ng of di	ifferent c	lesign aj	pproache	s in gen	eral and	some	2, 3	Une	derstand/	Apply
CO3	To dev design	velop ski criteria	ll of ma	terial se	lection f	or the s	pecific t	ask base	d on dif	ferent	4		Analyz	e
CO4	To eva and sat	luate the fety	material	's perfo	rmance v	vith refe	rence to t	the cost,	societal	health	5		Evaluat	te
				Aı	rticulatio	on Matr	ix: (CO	PO-PS	O Mapp	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	2	2	3	1	-	-	-	-	-	-	-	3	2
CO2	2	2	3	1	3	-	-	-	-	-	-	-	3	2
CO3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$												3	3
CO4	3 2 2 3 1 - - - - - - 3 2 2 3 1 3 - - - - - 3 2 2 3 1 3 - - - - - 3 2 1 3 2 1 3 3 2 - - 3 2 3 1 2 2 3 3 1 2 - 1 1 3 3 2 3 1 2 2 3 3 1 2 - 1 1 3 3 2 3 Syllabus Analysis: Common causes and mechanism of failure, principles and techniques of failure analysis, fracture mechanics approach to failure problems, ductile and brittle fracture, fracture toughness, elements of design for fatigue failure failure failure medale Gradie Stragge and the S_N Curve areach initiation and propagation fatigue failure failure													3
Module	$\begin{array}{c c c c c c c c c c c c c c c c c c c $												Hours	
2	PO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS01P322313223133213213323231223312-11332213312-1133231223312-11332SyllabusItAnalysis: Common causes and mechanism of failure, principles and techniques of failure analysis, fracture mechanics approach to failure problems, ductile and brittle fracture, fracture toughness, elements of design for fatigue, Cyclic Stresses and the S–N Curve, crack initiation and propagation, fatigue failure models, measuring and estimating fatigue failure criteria, high temperature failure and creep, stress and temperature effects, wear failure, design failures, processing failure (forging, casting, machining etc.), failure problems in joints and weldsDesign Philosophies: Introduction to Uncertainties with examples relevant to different disciplines in science and engineering, Traditional design philosophies: factor of safety approach, partial safety factor approaches. Probability and statistics as tools for uncertainty quantification. Stochastic models for loads and structure capacities.Me												10	
3	2 1 5 2 1 5 2 - - 5 2 5 1 2 2 3 3 1 2 - 1 1 3 3 2 e Syllabus Analysis: Common causes and mechanism of failure, principles and techniques of failure analysis, fracture mechanics approach to failure problems, ductile and brittle fracture, fracture toughness, elements of design for fatigue, Cyclic Stresses and the S–N Curve, crack initiation and propagation, fatigue failure models, measuring and estimating fatigue failure criteria, high temperature failure and creep, stress and temperature effects, wear failure, design failures, processing failure (forging, casting, machining etc.), failure problems in joints and welds Design Philosophies: Introduction to Uncertainties with examples relevant to different disciplines in science and engineering, Traditional design philosophies: factor of safety approach, partial safety factor approaches. Probability and statistics as tools for uncertainty quantification. Stochastic models for loads and structure capacities. Methods: Modern Design Cycle Need Analysis and Broad Engineering Specifications Concept Design												7	
	Feasibi Mather Experin Ergono	lity stund natical, (mental T pmics and	dy and Graphica echnique	Evalua al, Analy es), Desi Factors	ation of ysis and ign for M s, Introdu	alterna Simulat Ianufact	atives, 1 ion (e.g. ure and 1 design s	Engineer , FEM, Reliabili ensitivity	ring Eco Monte (ty, Susta y analysi	onomics, Carlo, CI inability s, life pr	Modelin FD, Dimer and Envi ediction.	ng Tech nsional a ronment,	niques- nalysis, Safety,	
4	Basics selection shape: that income	of Mat on strateg shape fac clude sha	erials songy and p ctors, lin pe	election rocedure nits to sh	: strengt e, multip hape effic	h, stiffn le const viency, e	less, and raints an xploring	fatigue d conflic the mate	life con cting obj erials sha	nsideratio ectives, ape comb	on, mater Selection vinations,	ials indic of materi materials	ces, the ials and indices	8
						I	Reference	es						
• • • • • • • • • • • • • • • • • • • •	Practical Engineer (Butterw Probabili HO Mad Machine Machine	Stress A ing Mattor orth-Heit istic mod sen, S Ku Design, Element s and De	nalysis i erials 1: nemann) lel code renk, NC An integ ts: Life a esign, Th	n Engin An Intr (2000). J C Lind (1 grated ap nd Desig	eering D roductior Joint Cor 1986). M pproach, gn, BM I nd Scien	esign, R n to Pro nmittee ethods o Robert I Klebanov ce of M	onald Hu perties, on Struc of structu Nortor v, DM B aterial S	udson an Applicat tural Saf ral safety n, Prentic alram an election	d Harold ions and ety. y. Prentic ce Hall d FE Ny in Produ	l Josephs l Design ce Hall, l vstrom, C uct Desig	, CRC pre , MF Ash NJ. CRC press gn, Mike .	ess by, DRH Ashby ar	I Jones, Id Kara J	Elsevier Johnson,

• Materials Selection in Mechanical Design, MF Ashby, Elsevier

Co	ourse Co	ode: AN	/IN1410	5	Ad	vanced	Mecha	nics of a	Solids	C	redits (I	L-T-P-C	(r): 3-0 -	-2-4
Pre-requ	isites: M	lechanic	s of Soli	ds	-									
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Level	B	[Descri	ption
CO1	Unders	stand the	concept	of tenso	or						2,4	Unde	erstand, A	Analyze
CO2	Analyz	ze advano	ced conc	ept of st	ress and	strain in	structur	al proble	ems.		2, 3	Unc	lerstand,	Apply
CO3	Apply	the conc	ept of di	fferent e	lastic fu	nctions t	o solve c	complex	problem	S	3		Apply	
CO4	Evalua	te the inf	fluence of strain n	of variou	s geome	tric and	loading	paramete	ers in pla	ne	5		Evaluat	te
	5000550		strain p	A	ticulati	on Matr	ix: (CO	-PO-PSO	О Марр	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	1	-	-	2	-	1	1	3	3	3
CO2	3	3	3	1	1	-	-	-	-	1	1	3	3	3
CO3	3	3	3	1	1	1	1	-	-	1	-	3	3	3
CO4	3	3	3	1	1	1	2	2	1	2	3	3	3	3
Module		1					Syllab	us		•			I	Hours
1	04 3 3 3 1 1 1 2 2 1 2 3 3 3 3 1 Mathematical Preliminaries: Introduction to tensor algebra: symmetric and skew-symmetric tensor, summation convention, eigenvalue and eigenvector of tensor, spectral theorem, polar decomposition theorem, product of tensor, principal invariants of tensor, coordinate transformation of tensor, Tensor calculus: gradient, divergence, curl, differentiation of scalar function of a tensor. 0 2 Analysis of Stress and Strain: Definition and notation of stress, Cauchy stress tensor, equations of equilibrium, principal stresses and stress invariants, stress deviator tensor, octahedral stress components, General deformations, small deformation theory, strain transformation, principal strains, spherical and height is the stress tensor, being the stress of the stres													08
2	Addule Syllabus How 1 Mathematical Preliminaries: Introduction to tensor algebra: symmetric and skew-symmetric tensor, summation convention, eigenvalue and eigenvector of tensor, spectral theorem, polar decomposition theorem, product of tensor, principal invariants of tensor, coordinate transformation of tensor, Tensor calculus: gradient, divergence, curl, differentiation of scalar function of a tensor. 08 2 Analysis of Stress and Strain: Definition and notation of stress, Cauchy stress tensor, equations of equilibrium, principal stresses and stress invariants, stress deviator tensor, octahedral stress components, General deformations, small deformation theory, strain transformation, principal strains, spherical and deviatoric strains, Strain-displacement relations, strain compatibility, Generalized Hooke''s law, Strain-energy, stress and strain in curvilinear, cylindrical, and spherical coordinates, fundamental equations of plasticity. 10 3 Problem formulation and solution strategies: Eicld equations houndary conditions strass and displacement 12													10
3	Proble formula unique inverse	m form ation, Be ness theo , semi-ir	ulation a eltrami-N prem, Sa iverse, a	nd solut Aichell c aint-Vena nalytical	t ion stra compatib ant's pri , approx	tegies: F ility equ nciple, F imate, ar	Field equ ations, L Brief des nd nume	ations, b ame-Na criptions rical met	oundary vier's eq s about § hods.	condition uations, j general se	ns, stress a principle o olution str	nd displa of superp rategies -	osition, ositiect,	12
4	Two-d strain, polyno	imension Airy stre mials and	nal prol ess funct d Fourie	olems: I ion, pola r series 1	Plane str ar coordi nethod.	ess and nate forr	plane st nulation	rain prol and solu	blems, g itions, C	generalize artesian o	ed plane s coordinate	stress, Ai solution	ntiplane Is using	04
Experime program	ents rela ning to s	ted to te solve the	nsile, co basic ar	mpressi 1d advar	on, torsi iced pro	on and blems	shear te	sts, bena	ling of l	beams, bi	uckling oj	f column	s and M	ATLAB
						I	Referenc	es						
• Theo	ory of Ela	asticity b	y M. Fil	onenko-	Borodich	1								
• Adva	anced Me	echanics	of Solid	s by L.S	.Srinath									
• Theo	ory of Ela	asticity b	y S.P. T	imoshen	ko and J	. N. Goo	dier,							
• Elast	icity, Th	eory, Ap	plication	ns, and N	Jumerics	by Mar	tin H. Sa	ıdd						
• Adva	anced Me	echanics	of Solid	s by Otte	o T. Bru	hns								
Cont	inuum M	lechanic	s by A.J.	M Spen	cer									
• Adva	anced Me	echanics	of Mate	rials by 1	H. Ford	and J. M	. Alexan	der						
• The]	Linearize	ed Theor	v of Elas	sticity by	W. S. S	laughter	•							

Co	urse Co	ode: AN	IN141 0	6	A	dvance	d Fluid	Mecha	nics		Credits (1	L-T-P-C	(r) : 3-0 -	-0-3
Pre-requ	isites: F	luid Mec	hanics											
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Leve	l B'	Г Descrij	ption
CO1	An abi proble	ility to a ms in flui	pply bas ids engin	sic gove neering.	rning la	ws and	potential	flow th	eory to	solve	2,3	Und	lerstand /	Apply
CO2	An abi	lity to ide	entify Bo	oundary	layer sep	paration,	its cause	es and co	ontrol.		2		Understa	ind
CO3	An abi and oth	lity to ap	ply the cable are	concepts as	develop	bed for f	luid flow	⁄ analysi	s in aero	space	3, 4	A	pply/Ana	alyze
CO4	To und shocks	derstand	the basi	c aspect	s of dif	ferent ty	pe of co	ompressi	ble flow	s and				
				Ar	ticulatio	on Matr	ix: (CO-	PO-PS) Mappi	ing)				
CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01													PSO2	
CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 PS CO1 3 3 1 1 1 - - - - 2 3 3 CO2 3 3 3 1 2 - - - - 1 3 5 CO2 3 3 2 2 2 - - - - 1 3 5 CO3 2 3 2 2 2 - - - - - 3 5													3	
CO2	xor roi r													2
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$													3	
CO1 3 3 1 1 1 - - - - 2 3 CO2 3 3 3 1 2 - - - - 2 3 CO3 2 3 2 2 2 - - - - 1 3 CO4 3 3 - 1 1 - - - - 3 3 Module Syllabus 1 Basic Conservation & Governing Laws: Statistical & continuum methods, Eulerian & Lagrangian													1	
CO1 3 3 1 1 1 - - - - - 2 3 CO2 3 3 3 1 2 - - - - 1 3 CO3 2 3 2 2 2 - - - - 1 3 CO4 3 3 - 1 1 - - - - - 3 Module Syllabus H 1 Basic Conservation & Governing Laws: Statistical & continuum methods, Eulerian & Lagrangian													Hours	
2	Potent edge, f Joukov Viscou cylinde point fl sphere	ates, ma ntum and equation ial Flows low near vski trans s Incom ers, Stoke low, flow in a fluic	terial de l energy s, gover s: Stokes a blunt sformation pressibles' first p / in conv l, uniformation	rivatives , constit ning equ s stream nose for ons. le Flows problem, rergent a m flow p	, control utive eq ations for function ce and m Exact Stokes' nd divers past a spl	volume uations, or Newto s, solution solution second p gent chamere and	s, Reyno Navier- onian flu on of pot on a circu as for Co oroblem, nnels, flo cylinder	lds' trans Stokes e ids, bour ential equilar cylin puette flo pulsating ow over p , Ossen's	sport the equations adary con- uation, fl der and bow, Poise g flow be porous w s approx	orem (F differenditions low in a sphere, euille fl etween j vall. Sto imation	IS, Eulera (TT), consu- (TT), consu- interaction sector, flo conformal ow, flow back ow,	w around transforr between faces, sta imation, w flow.	a sharp nations, rotating gnation rotating	08
4	Introd B.L. ec and cor	uction to quation, 1 ntrol.	o Bound Integral	ary Lay solution	e r: Deri of B.L.,	vation o Lamina	f bounda ar and tur	ry layer rbulent b	equation oundary	n, how p layers;	ootential flo transition	ow comp ; B.L. sej	lements paration	08
5	Introd incomp nozzles	uction to pressible, s, shocks	o Comp subsoni and exp	ressible ic and su ansion v	Flow: The second	Velocity c flows, ayleigh a	of soun Mach nu and Fann	d and it umber ar o Flow.	s import nd its sig	ance, p nifican	hysical dif ce. Isentro	ference t pic flow	between through	06
						ŀ	Referenc	es						
 1. "Funda 2. "Founda 3. "Advaration of the second of the seco	imental Mations o need Flui dary Lay rn Comp imentals imentals luction to us Fluid	Mechanic f Fluid M id Mecha er Theor oressible of Aeroo of Fluid o Fluid M Flow", F	es of Flu Iechanica anics", K y", H. S Flow wi lynamica Mechanica F. M. Wl	ids", I. C ss", S.W. L. Murali chlichtin th Histor s" (2nd e ics", B.F s", R.W. nite, 2nd	J. Currie Yuan, F dhar & G g, 6th E cical Pers ed), J. D. X. Munso Fox & Edition,	A. Prentice- G. Biswa dition, M spective' Anderso on, D.F. A.T. Mc McGrav	Hall Ind as, Naros IcGraw- ', John E on, McG Young & Donald, w-Hill, 1	ia Pvt. L a Publis Hill Inc.,). Anders raw Hill t T.H. O 5 th Editio 991	td, New hing, 200 , 1986. son, McC kiishi, 21 on, John	Delhi.)5. Graw H nd Ed., Wiley,	ill. John Wile <u>:</u> 2001.	у.		

Cour	rse Code	e: AMN1	14102	1	Applied	Mathen	natics a	nd Comp	outation		Credits	(L-T-P-	Cr): 3-0	-2-4
Pre-requ	isites: M	Iathemat	ics and l	Program	ming ski	lls								
						Cou	irse Out	tcome						
S.No.					Outco	omes					BT Leve	I B'	F Descri j	ption
CO1	To Iden and app	ntify the plication	differend s of thes	ces betwo e methoo	een "Exa ds.	ict metho	ods & Co	omputatio	onal Met	hods"	2,4	Und	erstand, A	Analyze
CO2	To De mather	evelop 1 natics i.e	cnowled	ge of e elop the	expressir skill of I	ng a re Mathema	al-life	problem odelling.	in terr	ns of	2, 3	Uno	derstand,	Apply
CO3	To Ide Nonlin Differe	ntify and ear Prob entiation	d develo blems, In & Integr	p the sk nitial Va ration pro	ill to so due & l oblems.	lve real Boundar	life eng y Value	ineering Problen	problem 1s, Num	as e.g. erical	3		Apply	7
CO4	To dev	velop ski	ll of wri	ting Flo	w Charts	s of real-	-life eng	ineering	problem	is and	5		Evaluat	te
	transio	ini those		Ar	ticulatio	on Matr	ix: (CO	-PO-PSO) Марр	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	_	_	_	_	_	_	_	1	3	3
CO2	PO1 PO2 PO3 PO4 PO3 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 3 2 - - - - - 1 3 3 3 3 1 - - - - - 1 3 3 3 3 1 - - - - - 1 3 3 3 3 1 - - - - - 1 3 3 3 3 1 3 - - - 1 - 3 3 3 3 3 1 3 - - 1 - - 3 3												3	
CO3	3 3 3 2 - - - - - 1 3 3 3 3 1 - - - - - 1 3 3 3 3 1 - - - - - 2 3 3 3 3 1 - - - - 1 3 3 3 3 1 3 - - - 1 1 3 3 3 3 1 3 - - 1 1 - 3 3 3 3 3 1 3 - - 1 - - 3 3 2 Syllabus													3
CO4	3 3 3 2 - - - - - 1 3 3 3 3 1 - - - - - 1 3 3 3 3 1 - - - - - 2 3 3 3 3 1 - - - - - 1 3 3 3 3 1 3 - - - 1 3 3 3 3 1 3 - - 1 - - 3 3 ule Syllabus Review of Elementary Engineering Mathematics: Error and its propagation, Solution of homogeneous and													3
Module	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$												Hours	
1	Reviev	v of Elen	nentary	Engine	ering Ma	athemat	ics: Erro	or and its	propaga	tion, So	lution of h	omogene	ous and	3
	non-ho	mogeneo	ous equa	tions; Po	ower seri	es.								
2	Linear System Numer Transfe Eigenv	Algebra is of Line ical Asp prmation alue Prob	a: Mathear Equan bects in s, Jacob blem of	rices and ttions, G Linear i and Gi General	d Linear auss Elir Systems vens Roy Matrices	Transf mination s, Eigen tation M s, Singul	ormation Family values tethods, ar Value	ns, Oper of Metho and Eige Tri-diago Decomp	ational ods, Spe envectors onal Mat position,	Fundam cial Sys s, Diago rices, Q Direct a	entals of tems and S onalization R Decomp nd Iterativ	Linear A Special M and Si position I ve solvers	Algebra, Iethods, milarity Method,	8
3	Ordina equatic probler	ary Diff ons of se ns, probl	erential cond ore lems wit	Equati der, non- h variabl	ons: Int -homoge le coeffic	roductio neous li cients, sy	on to or near equ ystem of	dinary d ations o equation	ifferentia f second s.	al equat l order,	ions, horr free and f	orced os	s linear cillation	5
4	Partial solution	l Differe n, Hyper	e ntial E bolic, Pa	quation arabolic	s (PDE s and Ellip	s): Existotic PDE	tence ar s, nonlir	nd unique near PDE	eness of s.	f differe	ntial equa	ations, na	ature of	5
5	Nonlin Secant	ear Equ	ations:	Motivati n metho	on, Ope	n and br	acketing	g method, Merits an	Bisection	on, Fixe	d point, N ethods	ewton's	method,	4
6	Numer	rical Int	egration	n: Motiv	ation, N	ewton-K	Lotes me	thod, Tr	apezoida	al rule, S	Simpson's	rule, Rh	omberg	4
7	Integra	tion, Gat Value Pi	roblem:	Motivat	ion. Eule	er's meth	od. Mod	lified Eul	er metho	od. Rung	e-Kutta m	ethods. A	daptive	4
	integra	tions and	l multist	ep metho	ods.							,,		
8	Bound	ary-valu	ie and E	ligen-va	lue Prot	olem: M	ethods a	nd Appli	cations i	n Mecha	anics.			2
9	Statist	ical Con	nputatio	ons: Free	uency C	Chart, Re	egression	n Analysi	is, Least	Square	fit, Polyn	omial fit	, Linear	5
Program	and No	MATIA	R/Excel	on, Mult	iple Reg	ression,	Statistic	$\pm /Pvthore$	y Contro	a tha pr	ds. ablams			
Trogram	ning on		D/LACE			<u>) </u>	Reference	res	110 3011	e ine pr	Jotems			
	S. C. Cha R. W. Ha Amos Gi K.E. Atk	apra and amming, lat, Num inson, A	R. P. Ca Numeria nerical M n Introdu	inale, Nu cal Meth lethods f uction to	imerical ods for S or Engir Numeri	Methods Scientist neers and cal Anal	s for Eng s and En l Scienti lysis.	gineers. gineers (sts.	Dover B	ooks on	Mathema	tics).		

Сог	ırse Co	de: AM	IN1410)7		Bi	omech	anics			Cre	edits	(L-T-P	-Cr) : 1	3-0-0-	3
Pre-requ	isites:]	NIL														
Course (1. 2. 3.	Objectiv Mechar Kinetic Physiol	v es: To lics prin and kin ogical b	impart ciples v ematics ehavio	knowle which c s concej ur of bo	dge abo an be aj ots for a dy tissu	out: oplied t inalysir	o huma 1g huma	n struct in move	ure and ements.	function	ι.					
		-			-		Cour	se Out	come							
S. No.						Outco	omes						BT Le	evel	BT D	Description
CO1	To ur huma	iderstan n motio	d basic n.	concep	ots of n	nechani	cs for l	cinetics	and ki	nematic	analysis	of	2		Un	derstand
CO2	То со	mprehe	nd and	describ	e the na	ture of	loading	g in mus	culoske	eletal sys	tem		2		Un	derstand
CO3	To co ligam	onceptua ent and	alize th muscle	e basic	princi	ples of	tissue	biomec	hanics	of bone	, cartilag	ge,	2		Un	derstand
CO4 To apply the knowledge in biomechanical applications such as implant design and sports biomechanics 3, 4 Apply Articulation Matrix: (CO-PO-PSO Mapping)													ly, analyze			
					Artic	ulation	Matrix	x: (CO-	PO-PS	O Mapp	oing)					
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PC	012	PSO	l	PSO2
CO1	3	3	3	2	1	1	-	-	-	2	1		1	3		2
CO2	3	3	3	2	1	2	-	-	-	2	1		1	2	,	3
CO3	3	2	2	2	1	1	-	-	-	2	1		1	2		2
CO4	3	2	2	2	2	3	1	1	1	2	2		2	3		3
Module							S	yllabus								Hours
1	Hum Runn	an Mov ing, Gai	ement: t Analy	: Anatoı /sis, Kir	nical co netics: F	oncepts Kinetic	to desca Variabl	ribe Hui es, intei	man Mo pretatio	ovement, on of kin	Kinema etic data	tics:	Jumping	g, Walk	cing,	8
2	Musc muscl	le Meche e meche	hanics: anics, n	Skelet nuscle/ł	al musc oone int	le mor	phology ns	and pł	nysiolog	gy, musc	le consti	tutiv	ve model	ling, w	hole	6
3	Skele fractu	tal Bio res, ada	mecha ptation	nics: C and rer	omposi nodellii	tion an ng, mec	d struct hanobio	ture of ology	bone, l	oiomecha	anical pr	oper	ties of	bone, l	oone	6
4	Cellu metho tendo	lar and ods to m n and ca	d Tissu neasure artilage.	ue Bion the me , biome	nechar chanica chanica	i cs: C l prope l prope	ellular rties of rties of	biomec cell and ligamer	hanics: d biomont, tendo	cytoske plecules, pn, and c	eletons, structure artilage,	cell- e of	matrix collager	interac 1, ligan	tion, nent,	8
5	Impla fixatio replac	ant Des on devi cement,	ign an ce, joir articula	d Com nt repla ating sur	putatio cement rface, co	nal Bio , design omputa	omecha n of bo tional n	nics: B one imp nodeling	one-im lant sy g in bio	plant system, to mechanic	stem, im tal hip r cs	iplan epla	t materi cement,	ial, frac total	cture knee	8
~		11.00		<u>.</u>	1 .		R	eferenc	es		TT 1 0	-h				
	J J J J J J J J J J	Hall, "B	asics of	t Biome	chanics	s'', Mc	Graw H	iill Pub	lishing.	co. New	York, 9 ¹	" Ed	1t10n, 20	022.		
• 0	C. Ross I	Ether an	nd Craig	g A. Sin	imons,	"Introd	uctory l	Biomec	hanics f	From cells	s to orga	nism	ns", Cam	ıbridge	Unive	ersity Press,
• E	Dew Del D. L. I	an, 2009 Bartel,	9 T. Dav	vy Dw	ight, a	nd Kea	aveny '	Tony N	M. "Or	thopaedi	c biome	echa	nics-Me	chanics	s and	design in
n	nusculo	skeletal	system	ıs", Upp	er Sado	lle Rive	er, New	Jersey:	Peards	on Prent	ice Hall.	200	6.	- 11 7:11-1)0 <i>c</i>

• Hamill, J., & Knutzen, K. M. "Biomechanical basis of human movement", Lippincott Williams & Wilkins. 2006.

Co	ourse Co	ode: AN	IN141 0	8	Dyna	amics o	f Mecha	anical S	ystems		Credits (l	L-T-P-C	(r) : 3-0	-0-3
Pre-requ	isites: E	ngineerii	ng Mech	anics, M	athemat	ics								
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Level	I B'	Г Descri	ption
CO1	Unders	stand the	basics o	f variatio	onal calc	ulus and	l energy	methods			2,4	Unde	erstand, A	Analyze
CO2	Analyz body d	ze advand ynamics	ced conc	ept of d	ynamics	using La	agrangia	n dynam	ics and 1	multi-	2, 3	Unc	lerstand,	Apply
CO3	Apply	the diffe	rent con	cept of d	ynamics	to solve	comple	x problei	ms		3		Apply	r
CO4	Evalua rotatin	te the di g & recip	fferent procating	oaramete g masses	rs that in a and vi	nfluence brations	the dyn of the re	amics of al struct	f cams, g ures	gears,	5		Evaluat	ie
				Ar	ticulatio	on Matr	ix: (CO-	PO-PS) Mappi	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	-	-	-	-	-	-	-	1	3	3
CO2	3	3	3	1	-	-	-	-	-	-	-	2	3	3
CO3	3	3	3	1	-	-	-	-	-	-	-	1	3	3
CO4	3	3	3	1	3	-	-	-	1	-	-	3	3	3
Module	3 3 3 1 3 - - 1 - - 3 3 Introduction to Variational Calculus, Virtual work and Generalized forces, Energy methods Lagrangian dynamics: Degrees of freedom generalized coordinates and generalized forces, bolonomic and													Hours
1	 Syllabus Basic concepts: Introduction to Variational Calculus, Virtual work and Generalized forces, Energy methods Lagrangian dynamics: Degrees of freedom, generalized coordinates and generalized forces, holonomic and 													6
	3 3 3 1 3 - - 1 - - 3 3 Introduction to Variational Calculus, Virtual work and Generalized forces, Energy methods Lagrangian dynamics: Degrees of freedom, generalized coordinates and generalized forces, holonomic and non-holonomic constraints, Kane's equations, Lagrange's equations, Lagrange's equation from d'Alembert's principles, application of Lagrange's equation for conservative and non-conservative autonomous systems with holonomic and non-holonomic constraints, applications to systems with very small displacements and impulsive motion; Hamilton principle from d'Alembert's principle, Lagrange equation from Hamilton's principle. Multi-body dynamics: Space and fixed body coordinate systems, coordinate transformation matrix, direction													
3	Multi- cosines matrice equation applica	body dy s, Euler a es, angula ons, plan ations of	namics: Ingles, E ar veloci er kinen planer sy	Space an uler para ty and ac natic and ystems.	nd fixed interes, a construction of the second seco	body coo finite an on vecto ic analy	ordinate : d infinite rs, equat sis, kine	systems, esimal ro ions of n matic re	coordina stations, 1 notion of volute jo	ate trans time der multi-b pints, jo	formation ivatives of ody syster int reactio	matrix, d Etransform n, Newto n forces,	irection mations n-Euler simple	12
4	Cams	and Gea	rs, Bala	ncing of	rotatin	g and re	eciproca	ting mas	ses, Intr	oductio	on to Vibr	ations.		12
						I	Reference	es						
 Dyna Ener Kine Kine 	amics of gy princi matics a matics, I	Mechani iples and nd Dynar Dynamic	cal Syster Variation mics of l s and De	ems, Hai onal meth Machine sign of N	old Jose ods in A ry, R. L. Machiner	phs and Applied I Norton, ry, K.J. V	Ronald I Mechania McGrav Waldron	Huston, (cs, JN R v Hill and G. I	CRC Pre eddy, Jol Kinzel	ss.2002 hn Wile	y and Sons	3		
• Adva	anced En	gineerin	g Dynan	nics, Gin	sberg, J.	H., Harr	per and R	low. 198	8	, - J				
• Meth	nods of A	nalytica	l Dynam	ics, Mei	rovitch,	L., McG	raw Hill	Inc. 197	0					
• Syste	em Dyna	mics, Ka	ıtsuhiko	Ogata, 4	th Ed., P	Prentice 1	Hall; 200)3						
• Mod	eling and	1 Simulat	tion of D	ynamic	Systems	, Robert	L. Wood	ds and K	ent L. La	awrence	Prentice	Hall. 199	7	
• Mod	eling and	l Analysi	is of Dyı	namic Sy	vstems, 6	Ramin	S. Esfan	diari and	Bei Lu,	CRC Pr	ress 2010			
• Princ	ples of	Analytic	al Syster	n Dynar	nics, Ric	hard A.	Layton,	<u>Springer</u>						

Cours	e Code:	: MAN.	•••••		A	nalysis	s of Alg	orithms	5		Credits	L-T-P-	Cr): 3-	0-2-4
Pre-requ	isites: D	ata Struc	ctures an	d Discre	te Mathe	ematics								
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Level	l B '.	Г Descrij	ption
CO1	To und	lerstand	fundame	ntal algo	orithms f	or solvin	ıg a varie	ety of pro	oblems		2		Understa	nd,
CO2	To App program	ply basic mming, g	algorith greedine	ms e.g., ss, and p	sorting, s robabilis	searching	g, divide oaches	and-con	quer, dy	namic	3		Apply	
CO3	To ana betwee	lyze tim n differe	e and sp ent algori	ace com	plexity (of algori	thms and	d to eval	luate trad	leoffs	4, 5	An	alyze/ Ev	aluate
CO4	To dev	elop effi	cient alg	orithms,	, emphas	izing me	ethods us	eful in p	oractice		6		Create	;
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 PS01														
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 PO CO1 -2 -2 -1 -1 -1 -1 -1 -2 -													PSO2	
CO1	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 P 3 3 3 1 1 - - - 1 1 - 3													1
CO2	3	3	3	1	1	-	-	-	-	1	1	1	3	2
CO3	3	3	3	3	1	1	-	-	-	1	3	1	3	3
CO4	3	3	3	3	3	1	-	-	1	2	3	3	3	3
Module		•					Syllabu	15	•				•	Hours
1	Introdu	ction, R	eview of	basic co	oncepts, .	Advance	ed data st	ructures	like Bin	omial H	leaps, Fibo	nacci He	aps	6
2	Divide	and con	quer wit	h examp	les such	as Sortin	ng, Matri	x Multip	olication,	Conve	x hull etc			6
3	Dynam	nic progr	amming	with exa	amples su	uch as K	anpsack,	All pair	shortest	paths e	tc			6
4	Backtra	acking, H	Branch a	nd Boun	d with ex	xamples	such as '	Fravellir	ng Salesr	nan Pro	blem etc			8
5	Algorit	thms inv	olving C	omputat	ional Ge	ometry								6
6	Selecte matchi	ed topics	s such a	as NP-c	ompleter	ness, Aj	oproxima	ation alg	gorithms	, Rando	omized alg	gorithms,	String	6
						Ι	Referenc	es						
•]	Fundame The Desi	entals of	Compute Analysis	er Algor	ithms by	E. Horo	witz & S	S Sahni Hoperat	ft Ullma	n				

The Design and Analysis of Computer Algorithms by Ano, Hopcraft, Offman
 Introduction to Algorithms by Thomas H. Coreman, Charles E. Leiserson and Ronald L. Rivest

Co	urse Co	ode: AN	<u>IN151(</u>)3		Finite l	Elemen	t Metho	ods		Credits (1	L-T-P-C	Cr): 3-0	-2-4
Pre-requ	isites: M	lechanic	s of solid	ls, Fluid	Mechan	ics, App	lied Mat	thematics	s and Co	mputati	on			
						Cou	irse Out	come						
S.No.					Outco	omes					BT Leve	I B'	F Descri	ption
CO1	Identif natural	y the pri constrai	mary an ns	d derive	d depen	dent var	iables in	volved,	kinemati	c and	2		Understa	ind
CO2	Formu finite e	late, thro lement e	ugh use quations	of energes and imp	gy princi plement	iples and the same	l Variati e into con	onal met mputer p	hods, rel rogram	evant	3, 4	A	pply, An	alyze
CO3	Analyz progra	ze, interp m as wel	ret and o l as fron	communi n comme	icate res rcial fin	ults obta ite eleme	ined from ent Softv	m develo vare	oped con	nputer	4, 5	An	alyze, Ev	aluate
CO4	Use of	commer	cial FEA	A softwar	re and in	-house d	levelopn	nent of so	olvers/co	des	6		Create	;
				Ar	ticulati	on Matr	ix: (CO	-PO-PSO) Mappi	ing)				
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	1	-	-	2	-	1	1	3	3	3
CO2	3	3	3	1	1	-	-	-	-	1	1	3	3	3
CO3	3 3 3 1 1 1 1 - - 1 - 3 3 3 3 3 1 1 1 2 2 1 2 3													3
CO4	3 3 3 1 1 1 - - 1 - 3 3 3 3 3 1 1 1 2 2 1 2 3 3 le Syllabus													3
Module	3 3 3 1 1 1 2 2 1 2 3 3 Iule Syllabus													Hours
1	3 3 3 1 1 1 2 2 1 2 3 3 3 le Syllabus I Basic Concepts: Introduction, Weak formulations, Weighted residual methods, Variational formulations, weighted residual, collocation, subdomain, least square and Galerkin's method, direct method, potential energy method Image: Concepts: Basis steps, discretization, element equations, linear and quadratic shape													08
2	One-D functio solid m Plane ' Beams	imension ns, asser nechanics Truss: L : Introdu	nal Ana nbly, loc s, heat and ocal and oction, E	alysis: E cal and g nd fluid 1 l global c uler-Ber	Basis ste lobal sti mechanio coordina noulli be	eps, disc ffness m cs proble te systen eam elem	retizatio atrix and ems, axis ns, stress nent, nur	n, eleme l its prop symmetri s calculat nerical p	ent equa erties, be c proble ions, exa roblems	tions, li oundary ms, ample p	near and condition	quadrations, applica	c shape tions to	12
3	Scalar formul integra	Field P ation, his tion, con	roblems gher ord	in 2-D: ler elemen	Trianguents, six tation, N	ilar and node tri Iumerica	rectangu iangle, n il proble	ilar elem ine node ms	ents, cor quadril	nstant st ateral, r	rain triang naster eler	le, isopai nents, nu	ametric merical	10
4	Plane I and pla Bendin elemen	Elasticity ine strain ing of Ela its, Shear	y: Revie probler stic Plat deform	w of equ ns ces: Revie ation pla	ations of ew of cla	f elasticit assical pl y, numer	ate theor	-strain ar ry, plate b blems.	nd strain- bending e	displace elements	ement relat s, triangula	ions, plan	ne stress angular	10
Application Condition (Stiffness Solution	on throu ns, Auto & Mass (Gauss I	ugh Con matic M Matrice Eliminat	nputer Iesh Ge es, Load ion & ot	Program eneratior Vector), her meth	eming: 1 1, Noda Asseml hods), Po	Input fo l Coord bly of El ost Proc	or Geom linate an ement M essing. Reference	etric & nd Noda latrices t	Materia I Conne o Globa	ıl Conf ectivity, l Matric	iguration, Calculati es, Imposi	Loading on of E ing Boun	g and Ba lement 1 dary Cor	oundary Matrices Iditions,
Ener	av and E	inite Flo	ment M	athods in	Structur	ral Mach	anice. I	H Shan	nes and (ית דר	m			
 Energies Conc The list Finite An In 	ey and F cepts and Finite El te Eleme ntroducti	Applica ement M nt Proce on to Fir	tions of ethod V dures: K nite Elen	Finite El ol. I-II: (. J. Bathment Met	lement A D.C. Zie e. hods: J.I	nalysis: nkiwicza N. Reddy	R. D. C and R.L.	ook, D. S Taylor.	S. Malku	s and M	. E. Plesha	a.		

• Finite Element Methods in Engineering: S.S. Rao.

Cours	e Code	: AMN1	5104	Co	mpressi	ble Flo	w and (Comput	tations		Credits (l	L-T-P-C	(r) : 3-0	-0-3
Pre-requ	isites: A	pplied M	lathemat	ics and	Computa	tion, Ac	lvanced	Fluid Me	chanics,	, Introdu	ctory Gas	Dynamic	s	
						Cou	ırse Out	come						
S.No.					Outco	omes					BT Level	I B'	Г Descrij	ption
CO1	Unders compre	stand and essible fl	l apply th ow prob	he funda lems	mentals	of nume	erical sin	nulation	in the re	al-life	2,3	Und	lerstand /	Apply
CO2	Compr compre	ehensive essible fl	ly under ows and	erstand their sol	the go lution teo	verning chniques	equatio	ons pert	inent to	o the	2,3	Und	lerstand /	Apply
CO3	Analyz	the une	derlying	complex	x flow pł	nysics of	the com	pressible	e flows.		4		Analyz	e
CO4	Facilita	ate in dev	eloping	the in-h	ouse cod	les.					4		Analyz	e
				Aı	rticulatio	on Matr	ix: (CO·	-PO-PSO) Mapp	ing)				
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	-	1	1	-	-	-	-	-	-	2	3	3
CO2	3 3 3 1 2 - - - - 1 3 - 3 3 3 2 - - - - 1 3 1 1 3 3 3 3 3 - - - - 1 3												3	3
CO3	3 3 3 1 2 - - - - 1 3 - 3 3 3 2 - - - - 1 3 1 1 3 3 3 3 3 - - - - 3 e Syllabus												3	3
CO4	- 3 3 2 - - - - - 3 1 1 3 3 3 3 - - - - 3 ule Syllabus												3	
Module	03 - 3 3 3 2 - - - - - 3 04 1 1 3 3 3 3 - - - - 3 04 1 1 3 3 3 3 - - - - 2 3 odule Syllabus Syllabus												Hours	
2	Jost Jost												08	
3	Smooth Spatia fluxes (TVD) functio based g	I discret (advection scheme ans (minr gradients	ization on upwir , piecev nod, Han , average	based of a splitti vise line ten, TV e of grad	n finite ng scher er recons D, super lients)	volume nes, Roe struction bee) , V	method e's appro a, Green- iscous fl	Cell-ce eximate I -Gauss a uxes (cen	ntred an Riemann approach ntral diff	d cell-v solver, n, least- ference,	ertex sche total varia square apj Green's th	mes, Cor tion dimi proach), eorem, e	vective nishing Limiter lements	10
4	Tempo multist steppin time st	oral Dis age sche g scheme epping so	cretizati eme, trea es (alterr chemes f	ion: Ex atment of ating di for unste	plicit tin of source rection in ady flow	me step e term, nplicit (. //s	ping scl Courant- ADI), lov	hemes (Fridreic wer-uppe	Runge-F hs-Lewy er symm	Kutta m (CFL) etric Ga	ultistage condition uss-Siedel	scheme,)), Implio (LU-SGS	hybrid- cit time S)), dual	08
5	Develo dimensi Develo Curvili	pment bional Eu pment o near app	of num ilerand f Euler a roach. F	erical of Navier-S and Nav unction	codes: Co	One dim olvers, (es multi- niter at h	ensional Compres compone nigh shoc	Euler sible flo ent comp ck streng	solver, ow solve pressible th.	structur er based flow so	ed and ur on the li lor in bo	nstructure imiter ap th Cartes	ed two- proach, ian and	06
		0.01			1	1	keferenc	es						
ء د د د	"Physics "Numeri "Rieman "Introduo "Modern	of Shocl cal Comj n Solver ction to (Compre	x Waves outation s and Nu Compres	and Hig of Interr merical sible Flu	gh Tempo nal and E Methods iid Flow' Historic	erature H External I s for Flu ', Oosthu	Iydrodyr Flows, V id Dynar uizen Pat pective"	namic Ph Volume 2 nics", E. trick H. John D	enomen ", Charl F. Toro Anderso	a", Y. E es Hirsc on McG	. Zel'dovic h. raw Hill	ch, YuP.	Raizer.	

Course	Code: A	MN15	102 C	Continu	um Me	chanics	and Co	onstitut	ive Mo	delling	Credit	s (L-T-]	P-Cr):	4-0-0-4
Pre-requ	isites: A	dvanced	Solid M	lechanic	s									
						Cou	ırse Out	come						
S.No.					Outo	comes					BT Level	B	Г Descrij	ption
CO1	Make u	use of the	e concep	ts of ten	sor form	alism for	r practica	al applica	ations		2,4	Unde	erstand, A	Analyse
CO2	Identif	y stresse:	s acting	on comp	onents s	ubjected	to comp	lex load	s		2, 3	Unc	lerstand,	Apply
CO3	Apply	deformat	tion and	strain co	oncepts f	or practi	cal situat	tions			3		Apply	
CO4	Develo	p constit	tutive rel	lations a	nd solve	2 D elas	ticity pro	oblems			6		Evaluat	e
				Aı	rticulatio	on Matr	ix: (CO-	PO-PSO) Mapp	ing)	1			
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	1	-	-	2	-	1	1	3	3	3
CO2	3	3	3	1	1	-	-	-	-	1	1	3	3	3
CO3	3	3	3	1	1	1	1	-	-	1	-	3	3	3
CO4	3 3 3 1 1 - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 Syllabus Mathematical Preliminaries and Introduction: Index notation, range and summation convention, free and dummy indices, Kronecker delta, Levi-Civita symbol, co-ordinate transformations, Cartesian tensor properties of tensors, tensors as linear operators, invariants of tensor, eigen values and Eigen vectors, pola												3	3
Module	3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 - 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 Syllabus Mathematical Preliminaries and Introduction: Index notation, range and summation convention, free and dummy indices, Kronecker delta, Levi-Civita symbol, co-ordinate transformations, Cartesian tensor properties of tensors, tensors as linear operators, invariants of tensor, eigen values and Eigen vectors, pola													Hours
1	POIPO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS0333212-11333331111333331111113333311111133333111221233339SyllabusMathematical Preliminaries and Introduction:Index notation, range and summation convention, frequencies of tensors, tensors as linear operators, invariants of tensor, eigen values and Eigen vectors, poladecomposition, scalar, vector and tensor functions, comma notation, gradient of a scalar, gradient of a vector, divergence and curl of a tensor, integral theorems of vectors and tensors. Notion of a continuum configuration, mass and density, descriptions of motion, material and spatial coordinates.Kinematics of Deformation and Motion: Deformation gradient tensor, stretch and rotation, right and												n, free ensor, , polar	08
	3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 1 3 3 3 3 3 1 1 1 1 - - 1 - 3 3 3 3 3 1 1 1 2 2 1 2 3 </td <td>nt of a</td> <td></td>												nt of a	
	vecto	r, diverg	ence and	d curl of	a tensor	, integra	l theorem	ms of ve	ctors and	d tensors.	Notion of	of a conti	nuum,	
	confi	guration,	mass ar	nd densit	y, descri	ptions o	f motion	, materia	and spa	atial coor	dinates.			10
2	Kine loft (matics of Courses	of Defor	mation	and Mo	tion: De	eformation	on gradi	ent tenso	or, stretch	and rota	ttion, rig	ht and	10
	relati	ons infi	nitesima	l strain t	ensor in	finitesin	nal stretc	h and ro	tation c	omnatihi	lity condi	tions pri	ncinal	
	strain	is and str	ain devi	ator, ma	terial an	d local ti	ime deriv	vatives, s	stretchin	g and vor	ticity, pa	th lines, s	stream	
	lines,	vortex 1	ines, Re	ynolds t	ransport	theorem	, circula	tion and	vorticity	<i>.</i>	571	,		
3	Force	es and S	tresses:	Body a	nd surfac	ce forces	, Cauch	y Stress '	Tensor,	First and	Second H	viola-Kir	chhoff	6
	Stress	s Tensor	, Deviate	oric and	Pressure	e Compo	nents, Pi	rincipal S	Stress.					
4	Fund	lamenta	l Balanc	e Laws	of Conti	nuum M	lechanic	s: Balan	ce of Ma	ss – Cont	inuity Eq	uation; B	alance	8
	of Lii Mom	near Moi	mentum Delence	- Equat	ions of N	Motion /	Equilibr	ium Equ	ations; I	Moments	of Mome	entum (A	ngular	
	Entro	onv Seco	nd Law	of Ther	gy - Firs nodvnar	nics: Cla	usius-Di	ihem Ine	cs, Energ	gy Equali Dissinati	on, Equa on Functi	ons	state –	
1.	Cons	titutive	Relation	ns and	Materia	l Model	s: Const	itutive A	Assumpti	ons: Idea	I Fluids:	Elastic 1	Fluids.	
-	Нуре	relastic 1	Material	; Notion	of Isotr	opy; Iso	thermal	Elasticity	/ - Ther	modynam	ic Restrie	ctions, M	aterial	
	Fram	e Indiffe	rence, M	laterial S	ymmetr	y; Hooke	e's law, S	stokes pr	oblem aı	nd Newto	nian fluid	s.		
						I	Referenc	es						
•	Introdu	ction to	the Mec	hanics of	f a Conti	nuous M	ledium: 1	Lawrenc	e E. Mal	vern.				
•	An Intr	oductior	to Cont	tinuum N	Mechanio	es: Mort	on M. G	urtin.						
•	Introdu	ction to	Continu	um Mec	hanics fo	or Engin	eers: Ray	y M. Boy	wen.					
•	Continu	ium mec	hanics f	or engin	eers: G.	I homas	Mase an	a George	е Е. Mas	se.				
	Nonlin	allu Pro	inuum N	a Contin Aochania	uum Me	vita Elan	George	E. Mase.	Ronat ar		Wood			
	Continu	uim mec	niuuiii N hanice a	nd place	icity: Ha	nte Elell n Chin V	Jent Alla Vu	1y818: J.	Donet al	iu K. D. V	w 00 0 .			

Course	Code:	AMN1	5105	De	sign an	d Anal	ysis of l	Experin	nents	(Credits (L-T-P-	Cr) : 3-0	-0-3
Pre-requ	isites: N	Aathema	tics – I,	II										
						Cou	rse Out	tcome						
S.No.					Outco	omes					BT Lev	el I	BT Desci	ription
CO1	To intr	oduce D	esign of	Experin	nents and	d its imp	ortance	in engine	eering.		2		Underst	tand,
CO2	To stud factors	ly and ur	nderstan	d basic s	tatistical	method	s, analys	is of var	ious, blo	cking	2		Unders	tand
CO3	To stu engine	dy and ering pro	apply v blems.	arious l	Factorial	experii	nent tec	hniques	in desi	gning	3,4		Apply, A	nalyze
CO4	To stu Rando	dy and m effect	apply 1 models	Regressi in engin	on anal	ysis, Re oblems.	sponse	surface	methods	s and	3,4		Apply, A	nalyze
				Arti	culation	ı Matri	x: (CO	-PO-PS	O Map	ping)		I		
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	2	3	2	2	-	-	_	_	1	1	2	3	3
CO2	3 2 2 3 1 - - - 2 1 2 3 3 2 3 2 2 - - - 1 2 3 3 2 3 2 2 - - - 1 - 2 3 3 3 3 1 - - - 2 1 3 le Syllabus												3	
CO3	3 2 2 3 1 - - - 2 1 2 3 3 2 3 2 2 - - - 1 - 2 3 3 3 3 3 1 - - - 1 - 2 3 ule Syllabus Introduction to measurements: Principles of Measurement Basic Elements of a Measuring Device Force												3	
CO4	CO3 3 2 3 2 2 - - - 1 - 2 3 CO4 3 3 3 3 1 - - - 1 - 2 3 Module Syllabus E 1 Introduction to measurements: Principles of Measurement, Basic Elements of a Measuring Device, Force													3
CO3 3 2 3 2 2 - - - 1 - 2 3 CO4 3 3 3 3 1 - - - 1 - 2 3 Module Syllabus H 1 Introduction to measurements: Principles of Measurement, Basic Elements of a Measuring Device, Force												Hours		
1	CO3 3 2 3 2 2 - - - 1 - 2 3 CO4 3 3 3 3 1 - - - 1 - 2 3 Module Syllabus H H Introduction to measurements: Principles of Measurement, Basic Elements of a Measuring Device, Force and Torque Measurement Temperature Measurement Pressure Measurement Eluid Velocity H												4	
	04 3 3 3 3 1 - - - - 2 1 3 odule Syllabus H 1 Introduction to measurements: Principles of Measurement, Basic Elements of a Measuring Device, Force and Torque Measurement, Temperature Measurement, Pressure Measurement, Fluid Velocity													
	Measu	rement, l	First and	second	order sy	stems.	6.5	•					<u> </u>	
2	Experi	mental	design :	and ana	ilysis: S	trategy	of Exper	rimentati	ion, app	lications	of Expendent	Design	Design,	6
	Compa	rison De	s, Oulde esigns, 1	Inference	es Abou	t the m	ean and	Varianc	es of N	ormal D	istributio	ns. Dete	ermining	
	Sample	e Size,	The Ra	ndom E	ffects N	Iodel, 1	The Reg	ression	Approa	ch to th	e Analys	is of V	variance,	
	Nonpar	rametric	Method	s in the A	Analysis	of Varia	ance							
3	Blocki	ng Facto	ors and l	Factoria	l Exper	iments:	The Ran	domized	Comple	ete Block	Design,	The Lati	n Square	6
	The Ty	, The Gi	raeco-La	um Squa ial Desi	are Desi on The	gn, Баla Genera	inced In I Factori	al Desig	n Fittin	Designs,	Advanta nse Curv	ge of Fa	Surfaces	
	Blocki	ng in a F	actorial	Design	gii, The	Genera	i i detoii	ai Desig	,11, 1 10011	ig nespo			Jurraces,	
4	Two-L	evel Fac	ctorial/]	Fraction	al Fact	orial De	signs: T	he Gene	eral 2^k D	esign, A	Single R	eplicate	of the 2^k	8
	Design	, Unrepl	licated 2	2^k Desig	n, Addi	ion of (Center F	oints to	the 2^k	Design,	blocking	a Repli	cated 2^k	
	Factori	al Desig	n, confe	Sunding	1n the 2 of the 2^k	[*] Factor	The Ord	gn, Con	founding r Fractic	g the 2^{κ} ,	Factorial 2^k Design	Design	11 Two noral 2^{k}	
	^p Fracti	onal Fac	torial D	esign.	of the 2	Design,	The One	e-Quarte	Tractic		2 Design	, The Ot		
5	Regres	sion M	odeling:	Linear	Regress	sion Mo	dels. Es	timation	of the	Paramet	ers in Li	near Re	gression	6
	Models	s, Hypotl	nesis Tes	sting in N	Aultiple	Regress	ion, Con	fidence l	Intervals	in Multi	ple Regre	ssion, P	rediction	
	of New	Respon	se Obse	rvations	Regress	sion Mo	del Diag	nostics,	Testing	for Lack	of Fit.			
6	Respo	nse Surf	ace Met	hodolog	gy: Intro	duction	to Respo	nse Surf	ace Met	hodolog	y, The Me	ethod of	Steepest	6
	Ascent	, Analys	is of a Se	econd-O	rder Res	ponse Si	urface, E	xperime	ntal Des	igns for l	Fitting Re	sponse S	Surfaces,	
	Experi	ments wi	ith Com	puter Mo	odels.							_		
7	Rando	m Effec	ts Mode	els: Ran	dom Eff	ects Mo	dels, Th	e Two-F	actor Fa	ctorial v	vith Rand	om Fact	ors, The	4
	Square	s. Appro	ximate <i>I</i>	7 Tests.]	Non-nor	mal Resi	nination	nd Trans	formatic	ons. Unb	alanced D	ata in a l	Factorial	
	Design	, The Ar	<u>alysis</u> o	<u>f Cova</u> ri	ance, Re	peated I	Measures	3		, 0.10				
						ŀ	Referenc	es						
• Iı	nstrumen	itation, n	neasuren	nent and	analysis	s, Nakra	, B. C., a	nd K. K	. Chaudł	nry, Tata	McGraw	-Hill Ed	ucation.	
• [esign an	d Analy	sis of Ex	xperimer	its, Doug	glas C. N	/lontgom	nery, 8th	Edition,	Wiley.	D • • • = =			
• D	esign an	id Analy	sis of Ex	perimer	ıts (Sprii	iger Tex	ts in Sta	tistics), I	Angela N	И. Dean,	Daniel V	OS		

Course Code: AMN16103 Engineering Vibrations Credits (L-T-P-Cr): 3-0-0- Pre-requisites: Mechanics of Solids, Applied Mathematics and Computations Course Outcome BT Level BT Description S. No. Outcomes BT Level BT Description Course Outcome CO1 Describe fundamentals of mechanical vibrations along with their classification 2, 4 Understand, An CO2 Differentiate among single, two and multiple degree of freedom (DOE) systems. 2, 3 Understand, An CO3 Analyze, predict and measure the performance of systems undergoing single, 3 Apply two and multiple Triculation Matrix: (CO-PO-PSO Mapping) F CO4 Solve complicated mathematical models using Numerical methods and software 6 Evaluate applications All 1 - - 1 1 3 3 CO4 Solve complicated mathematics Systems - 1 1 3 3 CO4 3 3 1 1 - - 1 1 3 3 CO4 3 3 <t< th=""><th>-0-3</th></t<>												-0-3		
Course Code: AMN16103Engineering VibrationsCredits (L-T-P-Cr) : 3-0-0-3Pre-requisites: Mechanics of Solids, Applied Mathematics and ComputationsCourse OutcomeS. No.OutcomesBT LevelBT DescriptionCO1Describe fundamentals of mechanical vibrations along with their classification2, 4Understand, AnalyCO2Differentiate among single, two and multiple degree of freedom (DOF) systems.2, 3Understand, ApplyCO3Analyze, predict and measure the performance of systems undergoing single, two and multiple3ApplyCO4Solve complicated mathematical models using Numerical methods and software applications6EvaluateCO4PO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS01PSCO133311111331CO3CO23331111113311CO33331111113331CO33331111113331CO4Solve complicated mathematical models using Numerical methods and software6EvaluateSolve complexitySolve complexitySolve complexitySolve complexitySol														
						Cou	rse Out	come						
S. No.					Outco	omes					BT Level	B	Г Descrij	ption
CO1	Descri	be funda	mentals	of mech	anical vi	brations	along w	ith their	classifica	ation	2, 4	Unde	erstand, A	Analyse
CO2	Differe	entiate an	nong sin	gle, two	and mult	tiple deg	ree of fre	eedom (I	DOF) sys	stems.	2, 3	Unc	lerstand,	Apply
CO3	Analyz two an	ze, predio d multip	ct and m le	neasure t	he perfo	rmance	of syste	ms unde	rgoing s	ingle,	3		Apply	<i>k</i>
CO4	Solve c applica	complica ations	ted math	nematica	l models	using N	umerical	method	s and sof	tware	6		Evaluat	æ
	applications Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 2 1 2 3												-	
CO	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 2 1 2 3<												PSO1	PSO2
CO1	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 - - 1 - 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 Syllabus Fundamentals of vibrations: Objectives, Types of Loadings, Essential Characteristics of Dynamic Problem												3	3
CO2	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 - - 1 - 3 <td>3</td> <td>3</td>												3	3
CO3	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 2 2 1 2 3 <td< td=""><td>3</td><td>3</td></td<>												3	3
CO4	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 - - 1 - 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 J 1 1 2 2 1 2 3 3 3 3 3 J 1 1 2 2 1 2 3 3 3 <t< td=""><td>3</td><td>3</td></t<>												3	3
Module	3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 2 2 1 2 3													Hours
1	3 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 1 - - 1 1 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 3 3 1 1 1 2 2 1 2 3 3 3 3 3 1 1 1 2 2 1 2 3 3 4 5 5 5 5 5 1 1 1 2 2 1 2 3 3 3 5 1 1 1 1 <th1< th=""> <th1< th=""> <th2< th=""></th2<></th1<></th1<>												06	
2	3 3 3 1 1 1 2 2 1 2 3 3 3 Syllabus Fundamentals of vibrations: Objectives, Types of Loadings, Essential Characteristics of Dynamic Problems, Discrete & Continuous systems, Simple harmonic motion, Combination of two simple harmonic motions, Beats, Fourier analysis, Rigid body dynamics vs. Vibration, Formulation of Vibration Problems: Taught String, Axial Vibration of Bar, Torsional Vibration of Shaft, Flexural Vibration of Beam, Membrane Single degree of freedom system: Analysis of Free and Forced Vibrations, Response to Harmonic, Periodic & Impulsive Loadings, Duhamel's Convolution Integral, Vibration Isolation, Response to General Dynamic Loading												Periodic ynamic	10
3	Two d vibratio undam	egree of ons, mass ped, two	f freedo s coupled degree d	m syste d system of freedo	m: Free , bending om syster	e vibrati g vibrati n, dynar	ons of s ons in tw nic vibra	pring co o degree tion abso	oupled system of freed orber, for	ystem, ge lom syste rced dam	eneral sol m, forced ped vibra	ution, To vibration tions	orsional ns of an	05
4	Multi- Evalua Eigen v values, method Holzer Shafts,	Degree of tion of S value pro Reducti l, transfo 's Metho Direct ti	of Freed tructura blems – on of d rmation d-Torsic ime integ	lom Syst l Propert solution ynamic 1 method, onal syste gration o	tems: Mo ty Matric of the ch matrices, Rayleigh ems, Jaco f linear s	odeling of ces and I naracteris Analys h's Meth obi's methobi's methobi	of Contir nfluence stic equa is of Dy od- Prop thod, Sto - Explici	Coeffic Coeffic tion, orth namic R perties of dola met t & Impl	stems as ients, Ei nogonalit esponse Rayleig thod, Fur licit metl	Multi-de gen value ty of norr - Superp h's Quoti ndamenta hods	gree of F e problem nal modes position n ent, Dunk l Frequen	reedom s , solution s, repeate nethod, I terley's f cy of Bea	ystems, n of the d Eigen teration ormula, ams and	10
5	Freque develop	e ncy Do pment, vi	main V ibration	' ibratio data acq	1 Analy uisition,	sis: Ove trending	er view, analysis	machine and fail	e-train r ure, node	nonitorin e, signatu	g parame re and roo	eters, Da ot cause a	ta base nalysis.	04
6	Vibrat control sensors	ion Con , Active s and actu	trol in S control uators fo	Structur and sen or active	res: Intro ni active control, s	duction, control, semi act	State sp Free la	bace repr yer and ol of aut	esentatio constrain omotive	on of equ ned damp suspensi	ations of bing layer on system	motion, rs, piezo ns.	Passive electric	05
						ł	Referenc	es						
 Ele Me Vit Me Me Acoustion 	ments of chanical chanical oration pr chanical chanical oustics a	f Vibratio Vibratic Vibratic roblems Vibratic Vibratic nd Noise	on Analy ons/Scha ons / SS in Engin ons /W.T ons – G.I e Control	vsis by M um Serie Rao/ Pea eering / C. Thoms X. Grove I/Smith,	feirovitc es/ McGr arson/ 20 S.P. Tim on / Prer er – S. Ch Peters &	h, TMH raw Hill 09, Ed 4 noshenko ntice Hill nand & 0 Owen/	, 2001 , o. l India CO. Addison	-Wesley	-Longma	an, Ed 2				

Co	ourse Co	ode: AN	/N1610)1	Con	nputati	onal Fl	uid Dyr	namics		Credits (l	L-T-P-C	(r) : 3-0 -	-2-4
Pre-requ	isites: A	dvanced	Fluid M	Iechanic	s, Therm	o-fluids	enginee	ring, Ap	plied Ma	themati	cs and Cor	nputation	IS	
						Cou	irse Out	come						
S.No.					Outco	omes					BT Level	I B'	Г Descrij	ption
CO1	To und	lerstand a	and math	nematica	lly mode	el the pro	blems in	n fluids e	ngineeri	ng	2,3	Unc	lerstand /	Apply
CO2	To dise	cretize th	e govern	ning equa	ations us	ing vario	ous discr	etization	techniq	ues.	2,3	Unc	lerstand /	'Apply
CO3	To ana	lyze and	evaluate	e the grid	l generat	ion for v	various p	roblems.			4, 5	Ana	alyze / Ev	aluate
CO4	To ana	lyze and	develop	new mo	dels for	external	, interna	l and uns	steady flo	OWS	6		Create	i,
	-			Ar	ticulatio	on Matr	ix: (CO-	-PO-PSO	О Марр	ing)				
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	1	1	-	-	-	-	-	-	-	3	3
CO2	3	3	2	1	1	-	-	-	-	-	-	-	3	3
CO3	2 3 2 3 3 - - - - - 2 3 2 3 3 3 3 1 2 - - 2 3 2 3 3 3 1 2 - 2 - 2 3 e Syllabus													3
CO4	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$													3
Module	2 3 3 3 3 1 2 - 2 - 2 3 e Syllabus													Hours
	2 3 3 3 1 2 - 2 - 2 3 Image: Syllabus Basic ideas of CFD & Governing equations (GE's) of Fluid dynamics: Introduction to CFD, role of CFD and its applications, future of CFD: Modeling of flow, control volume concept, substantial derivative, physical meaning of the divergence of velocity. Continuity equation, momentum equation, energy equation and its conservation form. Equations for viscous flow (Navier-Stokes equations), equations for inviscid flow (Euler equation). Different forms of GE's, initial and boundary conditions. FVM for Diffusion Problems: FVM for 1D steady state diffusion. 2D steady state diffusion. 3d steady state													08
2	FVM 1 diffusio	or Diffu on. Solut	ion of di	scretised	FVM for l equatio	r ID stea ns- TDN	Ady state	diffusio me for 2	n, 2D ste D and 3I	eady stat D flows.	e diffusior	n, 3d stea	dy state	08
3	FVM differen Hybrid	for Con ncing sc differen	nvection heme, (cing sch	- Diffusi Conserva eme for	on Prol ativeness 2D and 3	blems: , Bound 3D conve	FVM for dedness, ection-di	or 1D s Transpe iffusion,	teady st ortivenes Power-l	tate con ss, Upw aw sche:	vection-di ard differ me, QUIC	ffusion, encing s K scheme	Central scheme, e.	08
4	Solution SIMPL	on Algor JER, SIM	ithm fo 1PLEC,	r Pressu PISO alg	re-veloc orithm.	ity Couj	pling in	Steady I	Flows: C	Concept of	of staggere	d grid, Sl	IMPLE,	06
5	FVM f Implicit	for Unstant it meeth n proced	eady Flo ods for ure for t	ws: 1D 2D and ransient	unsteady 3D pro unsteady	y heat co blems, y flow ca	nduction Discretiz lculatior	(Explic zation of ns (transi	it, Crank f transie ent SIM	-Nicolso nt conv PLE, tra	on, fully in ection-diff nsient PIS	nplicit sc usion pr O algorit	hemes), oblems, hms).	08
In-nouse	sorrer u	evelopm) provie	ins F	Referenc	es						
•	"An Int 2nd edi "Comp 2012. "Comp 2004.	troductio ition, Pea utational utational	n to Cor arson Ed I Fluid D I Fluid F	nputation, ucation, ynamics low and	nal Fluid England for Eng Heat Tr	l Dynam , 2007. ineers" I ansfer" (ics: the I 3. Ander (2nd edit	Finite Vo sson & c ion), K.	olume M others, 1s Muralid	ethod", f	H.K. Verst ı, Cambrid T. Sundara	teeg and ge Unive arajan, N	W. Malal rsity Pres arosa Pul	asekara, ss, U.K., blishing,
•	"Nume "Princ	erical He iples of (at Trans Computa	fer and H tional Fl	Fluid Flo uid Dyn	w", S.V. amics",	. Patanka P. Wesso	ar, McGr eling, Sp	aw-Hill, ringer-V	New Y erlag.	ork, 1980.			

Cou	rse Cod	e: AMN	N16102	Ν	Aathem	atics fo	r Geon	netrical	Model	ling	Credits	(L-T-P	-Cr): 3-	-0-2-4
Pre-requ	isites: M	lathemat	ics, Prog	grammin	g skills									
						Cou	irse Out	come						
S.No.					Outco	omes					BT Level	I B'	Г Descrij	ption
CO1	Unders	stand the	role of §	graphics	primitiv	es such a	as points	, line and	l circles.		1, 2		Rememb Understa	er, Ind
CO2	Apply elemen	concepts at focusir	s of grap ng design	hics to c n engine	create an ering pro	d analyz blems.	the me	echanism	and ma	achine	3,4	Aj	pply, Ana	alyze
CO3	Unders visualiz	stand th zation an	e conce d furthe	epts for r applica	genera	tion of analysis	geomet	ries and	l shape	s for	2,3		Understa	ind
CO4	Apply quality	the cond of the g	cepts for eometric	generat	tion of g	geometrie ped.	es and s	hapes an	d analy:	ze the	4	Aj	pply, Ana	alyze
				Aı	rticulati	on Matr	ix: (CO	-PO-PSO) Марр	ing)				
СО	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 2 1 - 1 1 - 1 - 2 2 2 2 3 2 2 2 2 3 1 - 1 2 2 1 2 3												PSO2	
CO1	2	1	-	1	1	1	-	1	-	2	2	2	3	3
CO2	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$													3
CO3	2 1 - 1 1 - 1 - 2 2 2 3 2 1 - 1 1 - 1 - 2 2 2 3 2 2 2 2 3 1 - 1 2 2 1 2 3 3 2 3 3 2 2 2 2 2 1 2 3 3 3 2 3 3 2 2 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 3													3
CO4	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$													3
Module					•	•	Syllab	us		•		•	•	Hours
1	Mathe Bresen Aided	matical : ham's al Mechani	represe lgorithm sm and l	ntation (, Circle Machine	o f graph generati Elemen	ics prim on algor t Design	itives: P rithms. C	oints & l Character	ines. Alg generat	gorithm fo tion, fill	or Lines – area func	DDA alg tions, Co	gorithm, omputer	07
2	Transf and thr	formatio ee-dimei	ns and p nsions, C	orojectio Compute	ons: Rigi r Aided J	d body tı Assembl	ansform y of Rig	ations, D id Bodie	eformat s, Projec	ions, Ger tions (Or	neric trans thographi	formation	n in two lique).	06
3	Repres curves or Hern Non-U	sentation (analytic mite Cub niform R	n of cur & synth bic Segm Rational	ves and netic), cu ents. Th B-Spline	l its typ rve inter ree-Tang es (NUR)	es: Intropolation gent theo BS)	duction, , manipu orem, Bé	Wire fr lation, D zier Segi	rame mo rifferenti ments, S	odels, Par al Geomo plines (P	rametric r etry of Cu olynomia	representa rves, Fer l and B S	ation of guson's plines),	08
4	Surfac Deviati Surface	e represtion of the generat	entation Surface ion meth	: Surface from the nods (Re	e model e Tanger volution	s, param 1t Plane: and Swe	etric rep Second l eep)	resentatio Fundame	on, surfa ental Ma	ce manip trix, Gau	oulation, E ssian and I	Blending s Mean Cu	surface, rvature,	07
5	Represe Bounda solid g applica	sentation ary repre eometry: ition.	n of soli sentation : CSG p	ds: Fund n, constr primitive	damental uctive so s, Boole	ls of soli olid geon an opera	id model netry, Eu ators swe	ling, Top Iler-Poin eep repro	care formesentation	of Surface mula, Eul on, analyt	es, Invaria ler operato ic solid r	ants of Sors, Cons nodelers,	urfaces, tructive design	06
6	Visual shading applica	realisat g, colour ttions, Co	ion and ring and omputer	comput renderi Graphic	er anim ng, Con s Standa	ation: M nputer an rd	lodel cle nimation	an-up, hi , animat	dden lin ion syst	e remova tems, typ	l, hidden es and te	surface re echnique,	emoval, design	06
						Ι	Reference	es						
 Comp Geon Com Math An Ir Kauf Curv 	puter gra netric Ma puter aid cematica utroducti mann Pu es and S	aphics, b odeling t ded engi l Elemen on to Spi iblication urfaces f	y Baker. by Morte neering (ts for Co lines for 1. for Com	enson, W design b omputer Use in C outer Aic	Viley Pub y Saxena Graphic Compute led Geor	olishers. a, & Sah s by Rog r Graphi netric Do	ay, Sprir gers and <i>cs and C</i> esign by	nger Scie Adams, 2 <i>Geometric</i> Farin, A	nce & B 2nd Edit c <i>Model</i> cademic	usiness M ion, McC <i>ing</i> by Ba Press.	Aedia. Fraw-Hill artels, Bea	Publishe atty, Bars	rs. ky, Morg	şan

Со	urse Co	ode: AN	/N171()1]	Digital	Image 1	Process	ing		C redits (1	L-T-P-C	(r) : 3-0 -	-2-4
Pre-requ	isites: L	inear Alg	gebra an	d Discret	te Mathe	matics								
	1					Cou	rse Out	come						
S.No.					Outco	omes					BT Leve	I B'	[Descrij	ption
CO1	To con process	mprehen sing.	d the p	rinciples	and te	chnique	s emplo	yed in	digital i	mage	2		Understa	nd
CO2	To and proper	alyze an ties, repr	d manij esentatio	oulate di	igital in nhancen	lages, ir lent.	cluding	underst	anding i	mage	2, 4	Unde	erstand, A	Analyse
CO3	To extr texture	ract and s features	select rel	evant fea ape featu	tures fro res.	m image	es, incluc	ling stati	stical fea	tures,	2, 4	Unde	erstand, A	Analyse
CO4	Unders different medica	stand the nt imagi al image	applicand ng moda analysis	tion of in alities an	nage pro nd the u	cessing se of im	in medi age pro	cal imag cessing t	ing, inclue technique	uding es for	2, 3	Und	lerstand,	Apply
medical image analysis. Image analysis. Image analysis. CO5 To apply different segmentation techniques to extract objects of interest from images, employing methods such as thresholding, edge-based segmentation, and region-based segmentation. 3, 5 Apply, evaluation techniques to extract objects of interest from and region-based segmentation. 3, 5 Apply, evaluation techniques to extract objects of interest from and region-based segmentation. 3, 5 Apply, evaluation techniques to extract objects of interest from and region-based segmentation. 3, 5 Apply, evaluation techniques to extract objects of interest from and region-based segmentation. CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01											luate			
				Ar	ticulatio	on Matr	ix: (CO	-PO-PSO	Э Маррі	ing)				
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	To apply different segmentation techniques to extract objects of interest from images, employing methods such as thresholding, edge-based segmentation, and3, 5Apply, evaluationArticulation Matrix: (CO-PO-PSO Mapping)PO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS01333212-1133333112-1133													3
CO2	16 apply different segmentation techniques to extract objects of interest from images, employing methods such as thresholding, edge-based segmentation, and region-based segmentation. 5, 5 Apply, evaluation for the extract objects of interest from region-based segmentation. Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - - 1 1 3 3													3
CO3	To apply different segmentation techniques to extract objects of interest from images, employing methods such as thresholding, edge-based segmentation, and3, 5Apply, evaluationArticulation Matrix: (CO-PO-PSO Mapping)PO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS01333212-11333331111333331111133													3
CO4	Images, employing methods such as thresholding, edge-based segmentation, and region-based segmentation. Images, employing methods such as thresholding, edge-based segmentation, and region-based segmentation. Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 1 3 3 2 1 - - 2 - 1 1 3 3 2 3 3 1 1 - - - 1 1 3 3 3 3 3 1 1 1 - - 1 1 3 3 2 3 3 3 1 1 1 - - 1 1 2 2 4 2 2 3 2 1 - - 1 1 2 2													2
CO5	2	2	2	2	1	-	-	-	-	-	1	2	2	2
Module							Syllab	ıs						Hours
1	Introd contras Repres models	uction - st, hue, s entation,	Elemen aturation Image	ts of dig n, mach Analysis	gital ima band ef , Digitiz	ge proce fect. Ima ation of	essing sy aging sy `an anal	vstems - stems - og imag	Element Digital I e. Color	s of vis mages image	ual percep - Propertie fundamen	otion, brig s, Types tals - RG	ghtness, , Image B, HSI	08
2	Basic Histogr Logica frequer Freque	concepts ram trans l (Booles ncy dom ncy dom	s of ima sformatio an) oper nain - H nain filter	ge proc ons and l ations, C Fourier 7 rs - LPF.	essing: look-up Geometri Transfor HPF. B	Fundame ables. In c operat m, Prop PF. Note	entals of nage enl ions, Co perties, th filter.	digital nanceme nvolutio Standard Homom	image pr nt in spat n-based Repressorphic fil	rocessir tial dom operationentation ters. To	g – Gray ain - Alge ons. Image , Optical mographic	level his braic ope enhance Represe reconstr	togram, rations, ment in ntation. uction.	06
3	Image thresho Segmen binary	Segmen olding, ntation, l morphol	ntation: Edge-ba Binary m ogy oper	Thresho ased se aspholog rations.	olding- generation	global g ion, R erations,	rayscale egion-ba element	thresho ased so structuri	lding, gl egmentat ng, conno	obal co ion, N ectivity	lor thresh Matching. , and prima	olding, o Morpho ary and ac	or local ological lvanced	12
4	Image occurre and sel	feature ence feat ection of	extraction of the extraction o	ion and Run leng s.	selection gth featu	n: Featu res, shap	res- Fear e feature	ture spaces. Featur	ce, Statist re selection	tical fea on – Ne	tures, Tex ed-PCA, st	ture featu tatistical a	ares-co- analysis	04
5	Applic Medica	ation of al images	image j s obtaine	processi d with n	ng: Ima on-ioniz	ging Mo ing radia	dalities tion.	- Medica	al images	s obtain	ed with io	nizing ra	diation,	10
						I	Referenc	es						
ImagDigitDigitFund	e Proces al Image al image amentals	sing, An Process process s of Digi	alysis ar sing by R ing for n tal Imag	nd Machi Rafael C. nedical a e Process	ne visio Gonzale pplicatio sing by A	n by Mil z, Richa ons by G Anil K. J	an Sonk ard E. W eoff Doi ain, Pea	a; Vacla oods, Pe 1gherty, rson Edu	v Hlavac arson Ed Cambrid cation, 1	; Roger ucation ge Univ st ed.	Boyle, Ce , 4 th ed. versity Pres	ngage Le ss, 1 st ed.	arning 4 ^t	^h ed.

Electives (I and II)

	Course	Code:	AM-			Opt	imizat	ion - I		C	redits (L-T-P-C	Cr) : 3-0	-0-3	
Pre-requ	isites: N	Aathema	tics			*									
						Cou	rse Out	tcome							
S.No.					Outco	omes					BT	BI	[[] Descri	ption	
											Level				
CO1	Develo	pment o	of the ski	ll of find	ing optii	mum val	ue of des	sired var	iable in a	a real-	2		Understa	nd,	
CO2	Develo	gineering	g problei	m. Jedge of	favoras	sing a	raal lifa	nrohlan	n in tori	ns of	2		Understa	nd	
002	mather	natics i.e	e to deve	elop the s	kill of N	Aathema	tical Mc	deling.		115 01	2		Ondersta	lina	
CO3	To dev	velop the	e skill t	o apply	Linear	& Non-l	linear Pi	rogramm	ing, Gra	adient	3,4	A	pply, An	alyze	
	Metho	ds & Art	tificial N	eural Ne	tworks	etc in rea	al life en	gineerin	g proble	ms					
CO4 To develop skill of writing Flow Charts of real-life engineering problems and transform those into computer programming 4 Analyz Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO6 PO7 PO8 PO10 PO11 PO12 PS01												e			
CO4 To develop skill of writing Flow Charts of real-life engineering problems and transform those into computer programming 4 Analyz Articulation Matrix: (CO-PO-PSO Mapping) CO PO3 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1															
CO4To develop skill of writing Flow Charts of real-life engineering problems and transform those into computer programming4AnalyzCO4PO1PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PSO1COPO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PSO1COPO1PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PSO1COPO1PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PSO1CO332123PO3PO4PO6PO7PO8PO9PO10PO11PO23332 <td cols<="" th=""><th>DSO2</th></td>														<th>DSO2</th>	DSO2
C01	To develop skill of writing Flow Charls of rear-life engineering problems and the figure of the engineering problems and the engineering problems and the figure of the engineering problems and the engineering p													PSO2	
	transform those into computer programming Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 2 1 - - - - 1 2 3 3 3 2 1 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3														
C02	transform those into computer programming Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 2 1 - - - - 1 2 3 3 3 2 1 1 - - - 1 2 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 5														
CO3	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 2 1 - - - - 1 2 3 3 3 2 1 1 - - - 1 2 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 - - - - 1 2 3 3 3 3 2 - - - - 1 2 3														
CO4	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 2 1 - - - - 1 2 3 3 3 2 1 1 - - - - 1 2 3 3 3 2 1 1 - - - - 1 2 3 3 3 2 1 1 - - - - 1 2 3 3 3 3 2 1 - - - - 1 2 3 3 3 3 2 - - - - 1 2 3														
Module				•	<u> </u>		Syllab	us	•	011		. .		Hours	
1	Introd	uction 1	to Optin	nization	: Design	n variab	les, Des	ign con	straints,	Objective	e function	n Design	space,	8	
	Solutio	n by cal	culus an	d numer	ical met	hods.	Giobai	opunia,	Classif		i opuniz	auon pro	Juleins,		
2	Linear	and No	nlinear	Progra	mming	Simple	x metho	d Geor	etric Pr	orammi	ng: Appli	cation to	simple	12	
-	problei	ns. Meth	od of ar	proxima	tion pro	grammi	ng, Kelly	y's Cutti	ng Plane	method.	ig. rippii	cation to	simple	12	
3	Gradie	ent Metl	hods: St	eepest de	escent a	nd Side	step met	hod. Co	njugate (Gradient i	method, I	Rosin's C	radient	12	
	Project	ion Met	hod, Zot	endik's 1	nethod o	of feasib	le direct	ions, Un	constrain	ned and C	Constraine	ed Optim	ization,		
1	and per	nalty fun	iction tec	chnique s	search p	Artificio	es. 1 Nourol	Naturo	l Duno	mia prog	rommina	Applia	ation to	0	
4	Proces	s Equipr	nent. Str	uctural N	Aechani	cs. Deve	lopment	of com	k, Dyna	grammes	ranning	, Applica		o	
	110000	<u>- Iquipi</u>		<u></u>		<u>I I I I I I I I I I I I I I I I I I I </u>	Reference	es	juiter pro	<u>B- 4111100</u>					
• E	ngineeri	ng Opti	mization	, Theory	and Pra	actice: S	. S. Rao								
• 0	ptimiza	tion of S	tructura	l and Me	echanica	l Systen	ns: J. S.	Arora							
• E	lements	of Struc	tural Op	otimizati	on: R. T	. Haftka	and Z.	Gürdal							
• 0	ost Opti	mizatio	n of Stru	ctures: F	Fuzzy Lo	ogic, Ge	netic Al	gorithm	and Para	allel Com	puting: H	I. Adeli a	and K. C	. Sarma	
• A	In Introd	luction to	o Optim	ization: 1	Edwin K	K. P. Cho	ong and	Stanisla [•]	w H. Zal	κ.					
• N	in a ser D	r Optimi	zation-'	Theory a	nd Algo	orithms:	L.C.W.	Dixon							
	Inear Pr	ogramm	ing Vol.	I: G. Ha	uley	al II+ C	Hadlay								
	ommea		manne P	rogramm	iiiig, vo	л.п. О .	Tauley								

Cou	irse Co	de: AM	-XXXX	X	Mec	hanical	Behavi	our of N	Iateria	ls	Cred	lits (L-T	-P-Cr):3-0-0-3
Pre-requ	isites: A	Advance	d Mech	anics of	Solids									
							Course	Outcor	ne					
S. No.						Outcon	ies					BT Le	evel	BT Description
CO1	To Ui	nderstan	d vario	us types	s of def	ormatio	n and f	ailure o	f engin	eering m	aterials	2		Understand
	subjec	ted to v	arious s	tatic and	l dynan	nic loadi	ngs							
CO2	To ur	nderstan	d how	deform	ation a	nd frac	ture oc	cur and	how s	structure	affects	2		Understand
	mecha	inical be	ehaviour											
CO3	To ev	aluate n	nechanic	cal beha	viour, r	neasurei	ments of	t mecha	nical pr	operties a	and test	3,4		Apply and
<u> </u>	metho	ds	4	.1	4. 1.4	•	1		1 11		1	2.4		analyze
CO4 To apply fracture mechanics to determine whether a material will fracture before 3,4 yielding												Apply and		
yielding Articulation Matrix: (CO-PO-PSO Manning)												anaryze		
yielding Articulation Matrix: (CO-PO-PSO Mapping) CO PO3 PO4 PO6 PO7 PO8 PO10 PO11 PO12 PSO1													1 PSO2	
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 3 2 2 1 - - 2 1 1 2													2	
C02	3	3	3	1	1	2	_	_	_	2	1	1	2	2
CO3	2	1	2	1	2	1	-	-	-	1	1	1	2	2
CO4	2	2	2	1	2	3	1	1	1	1	1	1	2	2
Module	_		. –				Syllab	ous				-		Hours
1	Elasti	city: Li	inear: C	Continuu	ım; Iso	tropic;	Anisotro	opic; M	ultiaxia	l; Atomi	stic Basi	is, Nonli	near i	in 8
	Crysta	lline M	aterials:	Pseudo	elastic	ity, Rub	ber Ela	sticity:]	Latex to	DNA, V	Viscoelas	ticity: E	lasticit	ty
	and Fl	uidity												
2	Plasti	city: Li	mit of E	lastic R	esponse	: Uniax	ial and l	Multiaxi	al, Mec	hanisms	in Crysta	alline Ma	terials	.: 6
	Disloc	ations,	Twins,	Mechar	nisms in	n Nanoc	crystalli	ne Mate	rials, S	trengther	ning via	Microstr	ucture	÷,
-	Enviro	onment,	And Ph	ysical S	ize									
3	Creep	: Time-	Depend	ent Plas	ticity, I	Deforma	tion Me	chanism	Maps	of Elasto	-plasticit	y, Creep	of Pu	re 6
1	Fract	s, Creep	of Cera	of Eroo	d Polyr	ners, Cr	eep Asy		, Super-	-plasticity	Stragg	erials	7.mo. a.1.c.a	al 9
4	Bodie	ure: Ev	olution b Defor	of Flac	Modes	Singu	Junnale	Failure ss Field	, Lillea	nlacama	ot Fields	Microst	ructur	al o
	Mecha	nisms o	of Fracti	ire Strer	nothenir	- Singu 10		ss riciu		pracemen	n Pielus,	, wherest	luctur	ai
5	Fatig	ie: Faili	ure Belo	w Fract	ure Stre	ess: Insid	dious Fa	ailure E	mpirica	1 Fatigue	Models	Microst	ructur	al 8
C	Mecha	nisms	of Prol	onged I	Fatigue	Lifetim	ie. Cha	racterist	cs of	Fatigue	Fracture	-Fatigue	Crac	zk U
	Propa	gations	Laws, S	train Co	ontrolled	l Fatigu	e, Fatig	ue Life (Calculat	tions, Hig	gh Cycle	Fatigue	Desig	n-
	Surfac	e Fatigu	ie Failu	re Mode	els- Dyn	amic Co	ontact				, i	Ũ	U	
							Refe	erences						
1. 1	Mechan	ical Beh	navior of	f Materi	als, 2 nd	Edition,	Thoma	s H. Cou	ırtney					
2.]	Mechan	ical Beł	navior of	f Materi	als, Eng	gineering	g metho	ds for D	eforma	tion, Frac	cture and	Fatigue,	4th E	dition. Norman E.

Dowling
3. Mechanical Behavior of Materials, 2nd Edition. Marc Meyers and Krishan Chawla

Cou	irse Co	de: AM	-XXXX	X		А	erodyn	amics			Crec	lits (L-T-P-	Cr) : 3-0-	0-3
Pre-requ	i sites: F	Fluid Me	echanics	, Comp	ressible	Flow								
							Course	Outcon	ne					
S. No.						Outcon	nes					BT Level	BT D	escription
CO1	To un	derstand	l fundan	nentals of	of Aero	dynamic	es and F	light Pri	nciples.			2	Une	derstand
CO2	To and	alyze va	trious wi	ing conf	iguratio	ons of lo	w-speed	l and hig	gh-spee	d aircraft	s.	2,4	Undea	rstand and nalyze
CO3	To rea param	lize the eters.	fundam	entals o	f wind t	unnels a	and meas	suring p	rinciple	s of vario	us flow	3,4	Ap	ply and nalyze
CO4	To u applic	nderstar ations.	nd the	latest	develop	oment a	and tren	nds in	Aerody	ynamics,	newer	3,4	Ap	ply and nalyze
	Articulation Matrix: (CO-PO-PSO Mapping) CO PO3 PO6 PO7 PO8 PO10 PO11 PO12 PSO1													
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 3 1 2 2 1 - - 2 1 1 2 CO2 1 3 1 2 1 - - 2 1 1 2														PSO2
CO1	Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS CO1 3 3 1 2 2 1 - - 2 1 1 CO2 1 3 1 3 1 3 - - 2 1 1													2
CO2	CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS CO1 3 3 1 2 2 1 - - 2 1 1 1 2 1 - - 2 1 1 1 2 1 1 3 1 3 - - 2 1 <													
CO3	CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 P CO1 3 3 1 2 2 1 - - 2 1 1 1 CO2 1 3 1 3 1 3 - - 2 1 1 1 CO3 2 3 2 3 2 3 - - - 1 1 1													
CO4	2	2	2	1	2	3	3	-	-	-	1	1	2	2
Module							Syllab	ous						Hours
2	Wing pressu	s and a are, mo	irfoils, oment co ible Flo	lift and befficie	annes: l Drag, ent, Apj eory:	Centre <u>olicatio</u> Design	of pres	ssure ar tential f foils us	alleration di aero di aero dow in ding co	dynamic aerodyn onformal	c center, amic pr transfo	Coefficier coblems. rmation, K	nt of tutta	6
	condi Horse	tion, K e shoe v	arman - vortex,]	- Treff Biot - S	tz prof avart l	iles, Tl aw, Pra	hin aero Indtl lift	ofoil Th ting line	e theor	nd its ap y, Panel	plication method	ns. Vortex 1 s.	line,	
3	Com theory	p ressib y, Prano	le Flov dtl- Gla	v Theo uert Ru	ry: Po ile, Lin	tential earised	equatio	n for c onic flo	ompres w, Me	ssible flo thod of o	ow, sma characte	all perturba ristics.	tion	6
4	Airfo Drag wings for su	ils, Wi diverge s (ASW person	ngs and ence Ma / and F ic airpla	d Airpl ach nun SW), s anes.	lane co nber, S upersor	nfigur: hock st nic airf	ation ir all, sup oils, wa	High- er critic ave drag	Speed al airfo g, delta	Flows: bils, Tran wings,	Critical nsonic a Design	Mach num rea rule, Sv considerat	ber, vept ions	8
5	Visco Mease wall s Lates	uremen shear st st devel	w Meant of for ress, Fla lopmen	asurem rce and ow visu ts and	ents: ' momen alizati trends	Types nts in v ons. s in Aei	of wind vind tur rodyna	d tunne mels. M mics: U	ls – F Ieasure JAV, N	Now vision Tement of MAV.	ualizatio pressur	on processe e, velocity	es – and	8
							Refe	rences					I	
 L.J J.D Rat Sha 	. Clance . Ander thakrish apiro, A	ey, Aero son, "Fu nan.E., .H., Dyn	odynamio undamer Gas Dyr namics &	cs, India ntals of namics, & Thern	an Editio Aerodyn Prentice nodynar	on 2006 namics" e Hall of nics of (, Sterlin , McGra f India, 1 Compres	g Book w-Hill 1 1995. ssible Fl	House, Book C uid Flo	Mumbai. o., New Y w, Ronale	York, 19 d Press,	85. 1982.		1 1005

- E.L. Houghton and N.B. Caruthers, Aerodynamics for Engineering Students, Edward Arnold Publishers Ltd., London, 1988.
- Zucrow, M.J., and Anderson, J.D., Elements of gas dynamics McGraw-Hill Book Co., New York, 1989.
- W.H. Rae and A. Pope, "Low speed Wind Tunnel Testing", John Wiley Publications, 1984.

Cou	irse Co	de: AM	N-XXX	XX	N	lechani	ical Sys	tem De	sign	(Credits (l	L-T-P-C	Cr): 3-0 -	0-3
Pre-requ	isites: So	olid Mec	hanics, l	Engineer	ing Ana	lysis and	l Design							
	1					Cot	irse Out	come						
S.No.					Outco	omes					BT Level	B'	Г Descrij	otion
CO1	Studen fundan utilizin	ts will b nentals f g a syste	be able for designers appr	to apply n of a r oach.	knowle nore cor	dge of nplex a	basic sci nd divers	ience an se engin	d engine eering sy	ering ystem	1, 2		Rememb Understa	er, nd
CO2	Studen identify give a	ts will ha y the req tangible	ave abilit uiremen solution	ty to con ts of a de	nmunicat esign pro	e within blem an	the desi d will be	gn group e able to	effectiv formulat	ely to e and	3,4	A	pply, Ana	ılyze
CO3	Studen differer	ts will b nt phases	be able t s of the c	o evalua lesign	te the c	oncepts	and desi	igns dev	eloped d	luring	5		Evaluat	e
CO4	Studen and ver	ts will be rify the r	e able to esults.	test the	design b	y mathe	matical t	tools, pro	ototype te	esting	4	A	pply, Ana	ılyze
	Students will be able to test the design by mathematical tools, prototype testing 4 Apply, Argan, Apply, Apply, Argan, Apply,													
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	2	1	-	1	1	1	-	1	-	2	2	2	3	3
CO2	and verify the results. Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 2 1 - 1 1 - 1 - 2 2 2 3 2 2 2 2 3 1 - 1 2 2 3 3 2 3 3 2 2 2 2 1 2 3												3	
CO3	and verify the results. Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 2 1 - 1 1 - 1 - 2 2 2 3 2 2 2 2 3 1 - 1 2 2 3 3 3 2 3 3 2 2 2 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 3 2 3 3 3 2 3 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 3 3 2 </td <td>3</td>												3	
CO4	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 2 1 - 1 1 - 1 - 2 2 2 3 2 2 2 2 3 1 - 1 2 2 3 3 2 3 3 2 2 2 3 2 3 3 3 2 3 3 2 2 3 2 3 3 3 2 3 3 2 2 3 2 3 3 3 2 3 3 2 3 2 3 2 3 Suitabut												3	
Module							Syllab	us						Hours
2	Design process machin Engine relatior Engine Probler types o Gatheri Deploy	Process s; System les, and ering fur hship, W ering Ac m Defini f require ing Infor	: Types ns Appr assembl actions a <i>Vorking</i> tivity M tion and ments, T mation of roduct T	of desig oach: Fu ies; The nd engin interrela <u>atrix, A</u> Need Ic Types of on Existi Design S	n work, indamen Applica eering cl tionship <u>case stua</u> lentificat Custome ing Prod	The role tals of ' tion of haracteri physic ly ion, Ide er require ucts, Est jon, Tea	e of the Technica Systems istics, Co cal effect ntifying ements, H tablishing	designer. al Systen concept onversion ts, Produ Custome Functiona g the Eng viour an	, creativi n: Systen s in Eng of energent act and or Needs, al require gineering d Tools.	ty, The m, plant gineering gy, mate functior , System ements a g Charac Gather	morpholo , compone g Design, rial and sign d decomponent interface, nd compare cteristics, (ing Inform	gy of the ents, equ Identifica gnals, Fu osition d importa ny requir Quality F nation, T	e design ipment, ation of nctional iagram, nce and ements; unction ypes of	07
3	Design Function relocation Physican Liquid	Informa onal anal ing funct al effects al quantit pressure	tion, Sor ysis and tions, su –Physic ties, Solu	urces of variants bdividin cal effect ations for r; Concep	Design I Creativ g functions for gen r basic fu pt evalua	nformation e thinking ons, comperating inctions; tion: abs	ion ng, Funct nbining o force an ; Generat solute an	tions, cla or elimin d other f ting conc d relative	ssification ating fur unctions ept varian e, Case s	on of fun actions, , Physica ants from atudy	ctions, fur Study of s al laws and 1 sub-solut	nctional v system eo d effects ions, cas	variants, quation, relating e study:	07
4	Decisio making selectio	on Makin g, Decision on proces	ng and C on theor ss, Weig	Concept y, Decis hted Dec	Selectio sion tree cision M	n: Introc ; Evalua atrix, Ar	duction, tion pro- nalytic H	Decision cesses, U ierarchy	Making Jsing mo Process	g - Beha odels in (AHP)	vioral asp evaluatior	ects of a	lecision Concept	04
5	Config Belt an for asse	uration – d Pulley embly	- Produc example	t archite e and De	cture and etail desi	l Part de gn, Man	esign, En nufacturi	nbodime ng consid	nt/Param lerations	etric – S in desig	Steps in pa gn, guideli	rametric nes in de	design, esigning	05
6	Mather Choosi for Mat	natical N ng appro thematic	Modellin priate m al Mode	g Conce odel, Ai 1 Buildir	pts: Moo ds to mat 1g, Geon	dels – Ic thematic netric mo	conic, An al model odelling,	nalog, sy lling – Di Finite E	mbolic a imension lement N	and a pr al analy Iethod,	oof-of-cor sis, scale r Case Study	ncept, pro nodel, A y	ototype; Process	05
						I	Reference	es						
 G.E.I Hunci J.R.I Davi R.J.E Mart Princi Total 	Dieter, "] lal, M. S Dixon, "I d G.Ulln Eggert, "I in S Ray iples of l Design:	Engineer ., "Syste: Design En nan, "Tho Engineer , "Eleme Design: I : Stuart F	ing Desi matic M ngineerin e Mecha ing Desi ents of E Nam P S Pugh, Pea	ign: A M echanica ng and d nical De gn", Pea ngineerin Suh, McC arson Ed	laterials al Desigr esign for sign Pro rson/Pre ng Desig Graw Hil ucation	and Proo ing: A C manufa cess", M ntice Ha n", Pren 1 1999	cessing A Cost and acture" F IcGraw I all. atlice Hall	Approach Manager ield Ston Hill	" McGra ment Per le Pub.	aw Hill. spective	?'', New Y	ork, ASN	ME Press.	,1997.

• Total Design: Stuart Pugh, Pearson Education

Cou	Course Code: AM-XXXXX Structural Mechanics Credits (L-T-P-Cr) : Pre-requisites: Engineering Mechanics, Mechanics of Solids Course Outcome Students will be able to understand different type of plane structures and possible 2 CO2 Students will be able to understand different type of plane structures and possible 2 1 CO2 Students will be able to analyse plane structures and evaluate deflections, reactions 4, 5 CO3 Students will be able to analyse plane structures and evaluate deflections, reactions 4, 5 CO4 Students will be able to understand the basic construction of bridges 3,4 CO4 Students will be able to understand the basic construction of bridges 3,4 CO4 Students will be able to understand the basic construction of bridges 3,4 CO4 Students will be able to understand the basic construction of bridges 3,4 CO1 3 3 2 1 - - 2 1 1 3 CO2 3 3 1 1 2 - - 2 1 1 3 CO3 2 1 2 </th <th>: 3-0-0-3</th>											: 3-0-0-3		
Pre-requ	Course Code: AM-XXXXXStructural MechanicsCredits (L-T-P-Cr) : 3-0re-requisites: Engineering Mechanics, Mechanics of SolidsCourse OutcomeNo.OT action of Students will be able to understand different type of plane structures and possible loadings on such structuresBT LevelBT IO1Students will be able to analyse plane structures and evaluate deflections, reactions4, 5AO2Students will be able to analyse plane structures and evaluate deflections, reactions4, 5Aand internal forces for trusses, beams and framesFFO3Students will be able to extend the study of linear elastic analysis to include nonlinear aspects of structure behaviour3O4Students will be able to understand the basic construction of bridges3,4UnOPO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PSO1PO13322121130O2233311221130O42221221130O42221211120O33311221130 <tr< td=""><td></td></tr<>													
~ ~ ~ ~	Interfails information of solution Course Outcome No. Outcomes BT Level BT I 1 Students will be able to understand different type of plane structures and possible 2 U 1 Students will be able to understand different type of plane structures and possible 2 U 2 Students will be able to analyse plane structures and evaluate deflections, reactions 4, 5 A 3 Students will be able to extend the study of linear elastic analysis to include nonlinear aspects of structure behaviour 3 3 4 U 44 Students will be able to understand the basic construction of bridges 3,4 U OPO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 F 91 3 3 2 2 1 3 2 92 3 3 1 2 - - 2 1 1 3 2 93 2 1 2 - - 2 1 1 3 2 94 PO2 PO3 PO4 PO5 PO6 PO7 PO8 <th< td=""><td></td></th<>													
S. No.	<i>a</i> 1					Outcon	ies	. 1				BT Le	evel	BT Description
COI	Stude: loadin	nts will gs on su	be able ach struc	to unde	erstand	differen	it type o	of plane	structu	res and p	ossible	2		Understand
CO2	Stude: and in	nts will ternal fo	be able prces for	to analy trusses	/se plan , beams	e struct and fra	ures and mes	l evalua	te defle	ctions, re	eactions	4, 5	5	Analyze, Evaluate
CO3	Studen	nts will s of stru	be able t	o exten	the stu	dy of li	near elas	stic anal	ysis to i	nclude no	onlinear	3		Apply
CO4	Studen	nts will	be able	to under	stand th	e basic	constru	ction of	bridges			3,4		Understand
	Students will be able to understand the basic construction of bridges 3,4 Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 2 1 - - 2 1 1 3 3 3 3 1 1 2 - - - 2 1 1 3 2 1 2 1 - - - 1 1 2													
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO	1 PSO2
CO1	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 I 3 3 3 2 2 1 - - 2 1												3	2
CO2	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 F 3 3 3 2 2 1 - - 2 1												3	3
CO3	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS 3 3 3 2 2 1 - - 2 1												2	2
CO4	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 2 1 - - 2 1 1 3 3 3 3 1 1 2 - - 2 1 1 3 2 1 2 1 - - - 2 1 1 3 2 1 2 1 - - - 1 1 1 3 2 1 2 1 - - - 1 1 1 2 2 2 2 1 2 3 1 1 1 1 1 3 syllabus Analysis of Plane Structures: Introduction and Classification of Structures, Review of AF												3	2
Module	Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS0 3 3 3 2 2 1 - - 2 1 1 3 3 3 3 1 1 2 - - 2 1 1 3 2 1 2 1 2 - - - 2 1 1 3 2 1 2 1 2 1 1 1 1 1 1 1 1 1 2 2 2 2 1 2 3 1 1 1 1 1 1 1 1 1 3 4 2 2 2 1 2 3 1 1 1 1 1 1 3 <tr< td=""><td>Hours</td></tr<>													Hours
2	3 3 3 1 1 2 - - 2 1 1 3 3 3 3 1 1 2 - - - 2 1 1 3 2 1 2 1 2 1 2 1 1 1 3 2 1 2 1 2 1 - - - 1 1 1 2 2 2 2 1 2 3 1 1 1 1 1 1 1 1 1 1 3 e Syllabus Analysis of Plane Structures: Introduction and Classification of Structures, Review of AFD SFD and BMD for Beams, Degrees of Freedoms, Static and Kinematic Indeterminacy or Structures, Analysis of Compound and Complex Trusses, Analysis of Plane Frames Displacements of Plane Structures, Maxwell's Reciprocal & Betti's Theorem, Unit Load method, Deflection of trusses and plane frames Rolling loads and Influence Line Diagrams: Introduction, Influence Line Diagrams fo Beams & Trusses, Absolute Maximum Bending Moments, Muller- Breslau principle and it applications												of s, d or 6 ts s 10	
4	Truss Frame Plasti Frame	es, Fra es and (ic Anal es.	mes ar Grid Str Iysis of	nd Gric ructure: Struc	Struc (inclu tures:	tures; \$ ding pl Introdu	Stiffnes	s Meth s Meth space Plastic	iod- Aj structu Analys	pplication	$\frac{1}{2}$ ams, Fr	eams, T	Trusse	s, 10 s, le 6
5	Arche Three Analy	es, Cal e-Hinge vsis of C	bles ar d & Ty Cables,	nd Sus wo-Hin Susper	pensio ged Ai ision bi	n Brid ches, S ridges v	ges : In Spandre with thr	troduct Brace ee and	tion, L ed Arcl two hir	inear A h, Influe nged stif	rch, Edence Lin fening g	dy's Th les for A irders	eoren Arche	n, 8 s,
	, 1,	1 .	TT'1 1 1		D 11	. ,.	Kefe	rences						
 Struc Struc Struc Elem Struc Intern Matri 	tural Ai tural Ai tural Ai entary S tural Ai mediate ix Analy	nalysis, nalysis, nalysis i Structur nalysis, Structu ysis of F	Hibbele Aslam I n Theor al Analy L.S. Ne ral Anal Framed S	r, Pears Kassima y and P vsis, C. I gi and F lysis, C. Structure	on Publ li. Ceng ractice, H. Norri S. S. Jan K. Wat es, W. V	age Lea Alan W s, J. B. gid, Tat ng, Tata Veaver	arning P iilliams, Wilbur a a Mcgrav Mcgrav (Jr.) and	ublication Elsevies and S. U aw Hill I v Hill Pro- J. M. C	ons. r Public Jtku., Ta Publicat ublicatic dere, CB	ations ata Mcgra ions ons S Public.	aw Hill P ations.	ublicatio	ons	

Electives (III and IV)

	Course	Code:	AM-			Ор	timizat	tion-II			Credits (L-T-P-(Cr) : 3-0	-0-4
Pre-requ	isites: (Optimiza	tion-I											
	1					Cou	rse Ou	tcome						
S.No.					Outco	mes					BT Level	B	F Descri	iption
CO1	To und	lerstand	the basic	es of Op	timizatio	on.					2		Understa	ınd,
CO2	To und	lerstand	the basic	cs of Gei	netic Alg	gorithm.					2		Understa	and
CO3	To be a life pra	able to ag actical er	pply the ngineerir	basics of ng applic	f Genetio ations.	c Algorit	thm and	optimiza	tion for	real	3,4	A	pply, An	alyze
Interplactical origineering applications.Articulation Matrix: (CO-PO-PSO Mapping)COPO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS01PS01														
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 PS CO1 3 2 3 2 2 - - - 1 1 2 3													PSO2	
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 2 3 2 2 - - - 1 1 2 3 CO2 3 3 3 1 - - - 1 1 2 3													3	
CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 2 3 2 2 - - - 1 1 2 3 CO2 3 3 3 1 - - - 2 1 2 3													3	
CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 2 3 2 2 - - - 1 1 2 3 CO2 3 3 3 3 1 - - - 2 1 2 3 CO3 3 2 3 2 3 - - - 1 - 2 3													3	
Module		I	I		<u></u>		Syllab	ous	1	1	I	1		Hours
1	Basics Based	of Optin Algorith	nization, ms, Brie	, Optimiz ef Overvi	ation Pr iew of E	oblems, volution	Point to ary Con	Point Al	gorithms 1,	s, Simu	ated Anne	aling; Pop	oulation	12
2	Genetic scheme Particle	c Algori es and s e Swarm	thms (Tl selection Optimiz	heory an pressur zation,	d Advar e; Oper	ators on	erators), Real-v	Genetic alued Re	Represe epresenta	ntation ations,	search op Niche and	erators, s	election sharing,	12
3	Memet Evolut	tic Algor ion; Con	rithms; E Istraint F	Evolution Iandling	Strateg in optin	ies, Gen nization	etic Prog problem	grammin Is,	g, Evolu	tionary	Programn	ning, Diff	erential	08
4	Real L	ife appli	cation of	f optimiz	ation A	lgorithm	s, Introd	luction o	f Multi-o	objectiv	e Evolutio	nary Algo	orithms	08
						I	Referen	ces						
• G • Ir • L	oldberg ndustrial awrence	, David I applicat , Davis.	E. "Gene ions of ("Handb	etic algor Genetic A ook of ge	ithms in Algorith enetic al	search, ms by C gorithms	optimiz harles L s." <i>Van I</i>	ation, an Karr an Nostrand	d machin d L.Mich l Reinhol	ne learr nael Fre ld (199	ing. Addis eman, CR l).	on." <i>Read</i> C Press	ding (198	39).

Cou	irse Co	de: AM	I-XXXX	XX		S	oft Rob	otics			Credits (1	L-T-P-C	(r) : 3-0	-0-3
Pre-requ	i sites: B	iology fo	or Engin	eers, Flu	id Mech	anics, M	echanics	s of Solic	is, Dyna	mics of	Mechanica	al System	S	
						Cot	ırse Out	come						
S. No.					Outco	omes					BT Leve	I B'	۲ Descri	ption
CO1	Unders and act	standing tuation n	the fund nechanis	lamental ms, desig	s of soft gn princi	Robotic	es, inclue d applica	ling mat tions.	erials, se	ensing	2,4	Unde	erstand, A	Analyse
CO2	Unders inspire	stand the s robotic	e connec s	ction bet	ween b	iology a	nd robo	tics and	how bi	ology	2,3	Unc	lerstand,	Apply
CO3	Explain environ	n the in nment or	mpact o n perforn	f morph nance.	nologica	l feature	es of s	oft robo	t bodies	s and	3,4	Aj	pply, An	alyse
CO4Apply soft technologies, materials, actuation and sensing system to real world3,4Analyse, Applications, Applications, Applications, Applications, Applications, Applications, Applications, Application, Appli												pply		
applications. Articulation Matrix: (CO-PO-PSO Mapping) CO PO3 PO4 PO6 PO7 PO8 PO10 PO11 PO12 PS01 PS01														
Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 3 2 1 - - 2 - 1 1 3 3													PSO1	PSO2
CO1	applications. Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 CO1 3 3 3 2 1 - - 2 - 1 1 3 3 CO2 3 3 3 1 1 - - - 1 1 3 3													3
CO2	Articulation Matrix: (CO-PO-PSO Mapping) CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 P CO1 3 3 3 2 1 - - 2 - 1 1 3 3 CO2 3 3 3 1 1 - - - 1 1 3 3 CO3 2 2 2 1 1 - - 1 - - 2 2 2 2 2													3
CO3	CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 PS CO1 3 3 3 2 1 - - 2 - 1 1 3 3 3 2 1 - - 2 - 1 1 3 3 3 2 1 - - 2 - 1 1 3													2
CO1 3 3 3 2 1 - - 2 - 1 1 3 3 CO2 3 3 3 1 1 - - 1 1 3 3 CO2 3 3 3 1 1 - - - 1 1 3 3 CO3 2 2 2 1 1 - - 1 1 3 3 CO4 2 3 2 1 1 1 1 - - 1 1 2 2													2	
Module							Syllab	us				1		Hours
1	Introd	uction to	o soft ro	botics: a	lefinition	ns, differ	ence sof	t robots	vs. rigid	Robots,	Bioinspire	ed design	•	6
2	Polym	eric mat	terials fo	or soft re	obotics:	Elastom	ers, The	rmoplast	ics and t	extiles, A	Advanced	materials	•	10
	Soft ac	ctuation	- design	, modelli	ing, man	ufacturii	ng, and c	haracter	ization.	atria alt an	viant Antr	ation (Di	alaatria	
	elaston	ner actu	ators h	nouan vdraulic	ally an	uluic ac	electros	tatic ac	tuators	Ionic 1	ncar Actu olvmer-r	netal con	mposite	
	actuato	ors), The	rmal Act	uation (S	Shape m	emory al	lloys), M	lagnetic.	Actuatio	n, Biohy	brid Actu	ation, Ad	ditional	
	actuati	on (Man	ımalian a	and non-	Mamma	lian orig	in).							
3	Sensor	s: Resis	tive and	piezores	sistive se	ensors, C	Conducti	ve liquid	l sensors	s, Capac	tive sense	ors, Optic	al fiber	8
	sensors	s, Optica	I fiber so	ensors, s	oft logic	e, soft el	ectronics	s and sof	t sensing	g, Mode	ing and s	imulation	of soft	
4	Variat	ole Stiffr	ness mec	hanisms	s: Introd	uction to	variable	e stiffnes	s structu	res, Jam	ming mec	hanisms.		6
5	Design	and co	ntrol of	soft ro	bots: Ty	pical so	ft robot	architec	tures, O	n-board	control st	rategies (Model-	6
	Based	Control,	Data-Ba	sed Con	trol). Ap	plication	ns of sof	t robotics	s.			-	-	
]	Reference	es						
•]	Biologic	ally insp	ired robo	otics by	Yunhui I	Liu and I	Dong Su	n., CRC	press, 20)11				
• :	Soft Rob	otics: Tr	ansferrir	ng Theor	y to App	olication	by Alex	ander Ve	erl, Alin	Albu-Sc	häffer, Ol	iver Broc	k, and A	nnika
	Dootz Cr	oringer (2015											
]	Kaaiz, Sj	,			_	a .								
•]	Biorobot	ics by B	arbara W	vebb, Th	omas R.	Consi, A	AAAI Pr	ess, 2001	1	. 1 5 1	<i></i>	A .	9	
•]	Biorobot An Over	ics by B view of S	arbara W Soft Rob	vebb, The otics by	omas R. Oncay Y	Consi, A Tasa et a	AAAI Pr <i>l</i> . Annua	ess, 2001 Il Reviev	l v of Con	trol, Rol	otics, and	Autonon	nous Sys	tems

• Soft Robotics in Rehabilitation by Amir Jafari and Nafiseh Ebrahimi, Academic Press, 2021.

Cou	irse Co	de: AM	-XXXX	XX	Ch	aracter	rization	of Mat	erials		Credits ()	L-T-P-C	Cr) : 3-0	-0-3
Pre-requ	isites: M	laterials	Science	and Eng	ineering									
						Coi	ırse Out	come						
S. No.					Outco	omes					BT Leve	I B'	Г Descri j	ption
CO1	Studen materia	ts will h als chara	ave kno cterizatio	wledge on techn	and unde iques sue	erstandir ch as X-i	ng of the ray diffra	basic concentration, M	oncepts licroscop	of the by	2		Understa	ınd
CO2	Students will be able to analyze samples with the help of collected data by using different materials characterization techniques4AnalyStudents will have the capability to decide most appropriate technique required for the investigation of the structure and properties of different classes of materials3ApplArticulation Matrix: (CO-PO-PSO Mapping)PO1PO2PO3PO4PO5PO6PO7PO8PO9PO10PO11PO12PS01333212-113333311113322211122												Analyz	æ
CO3	Students will be able to analyze samples with the help of conlected data by using different materials characterization techniques 4 Analyse Analyse analyse samples with the help of conlected data by using different materials 4 Analyse Analyse analyse samples with the help of conlected data by using different materials 4 Analyse Analyse analyse samples with the help of conlected data by using different materials 4 Analyse analys												Apply	7
	materia	415		A	rticulatio	on Matr	ix: (CO-	PO-PSO) Mapp	ing)				
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	1		-	2	-	1	1	3	3	3
CO2	3	3	3	1	1	-	-	-	-	1	1	3	3	3
CO3	2	2	2	1	1	-	-	1	-	-	-	2	2	2
Module		I	I				Svllabi	15						Hours
1	for the investigation of the structure and properties of different classes of materials Articulation Matrix: (CO-PO-PSO Mapping) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01 3 3 3 2 1 - - 2 - 1 1 3 3 3 3 3 1 1 - - 1 1 3 3 2 2 2 1 1 - - 1 - - 2 2 1 3 3 Syllabus Crystallography: Overviews in bonding, Bravais lattices, Miller indices, imperfections in crystals, crystal structures of common metal, ceramics, polymers. symmetries in crystals, point groups, space groups, reciprocal lattice, morphology X-ray Diffraction Techniques: Production of X-rays, its properties and hazards, photon scattering, X-ray diffraction and Bragg's law, intensities calculations, Laue techniques, Debye-Scherrer techniques. modern diffractometers, diffractometer measurements, determination of crystal structure of powder sample, small angle scattering, line broadening, particle size, crystallite size, residual stress measurement, plane indexing, <td>5</td>												5	
2	O133212-1133O2333111133O32222111133O32222111122KyllabusCrystallography: Overviews in bonding, Bravais lattices, Miller indices, imperfections in crystals, crystal structures of common metal, ceramics, polymers. symmetries in crystals, point groups, space groups, reciprocal lattice, morphology2X-ray Diffraction Techniques: Production of X-rays, its properties and hazards, photon scattering, X-ray diffraction and Bragg's law, intensities calculations, Laue techniques, Debye-Scherrer techniques. modern diffractometers, diffractometer measurements, determination of crystal structure of powder sample, small angle scattering, line broadening, particle size, crystallite size, residual stress measurement, plane indexing, precise parameter measurement, phase identification, phase quantification, phase diagram determination, stereographic projection, pole figure, preferred orientation (texture analysis) and chemical analysis, profile												9	
3	Optica depth metallu disloca prepara	I Micros of field, argical s tions, p ation.	scopy: P viewing tudies (hase co	rinciples g area, qualitati ontrast 1	and ope contrast, ve and microsco	rations o geome quantita py, pol	of micros try of o tive), m arised 1	copy, res ptical m orpholog ight mid	solution, icroscop gy and croscopy	magnifi bes, app symmet v, hot-s	cation, nu lication o ry, grain rage micr	merical a f microso boundari oscopy,	perture, copy in ies and sample	9
4	Electro micros backsc transm	on Micro cope. geo attered e	oscopy: ometry o lectron i	Electror f electro mage, ir icroscor	n sources n micros nage pro ov (TEM)	s, electro copes, sj cessing,	on diffrac pecimen analysis	ction, pri handling of elect	nciples a and pre- ron micr	and oper paration o-graph	ation of s secondar s and fract	canning e y electron ography	electron i image, studies,	8
5	Scanni micros its prot	ing Prob cope, ato ping.	e Micro omic for	scopy:	Principle scope, m	es and op agnetic	peration of force mi	of scanni icroscop	ng probe y, topog	e micros raphy st	copes, sca idies, nan	nning tur oindentat	nnelling ion and	5
6	Therm calorin	al Anal Anal hetry, the	lysis: T ermo-me	hermo chanical	gravimet analysis	ric ana and the	lysis, di ir applica	fferentia ations.	l therma	al analy	sis, diffe	rential so	canning	4
]	Referenc	es						
• (•] •] • ?	Crystals Elements Electron Solid sta Fundame	and Crys s of X-ray Microsce te chemis entals of	stal struc y Diffrac opy and stry and Molecul	tures, R. ction, Cu Analysis its Appl ar spectu	J.D. Till Illity B. I s, P.J. Go ications, coscopy,	ey, John D., Addi oodhew, Antony Colin N	Wiley a son-Wes F.J. Hur R. West . Banwel	nd Sons, ley Publ nphreys, , Wiley S 1 and Ela	2006 ishing C Taylor a Student H aine M. I	o. & francis Edition. McCash,	s, Second Tata McC	edition. Graw-Hill	l Publish	ing

• Materials Characterization: Introduction to Microscopic and Spectroscopic, Yang Leng, John Wiley&Sons.

Course Code: AM-XXXXX			Prod	Product Design and Development Credits (L-T-				P-Cr) : 3	-0-()-3					
Pre-requisites: Engineering Analysis and Design															
Course Outcome															
S. No.						Ou	tcomes						BT Level	D	BT escription
CO1	Studen been d	nts will lesigned	be able 1 coverii	to visua ng differ	lize diff ent set o	ferent p of needs	roducts s	lying in	the san	ne catego	ory –but	that has	2,4	U	nderstand, Analyze
CO2	Studer	nts will	be able	to feel th	hemselv	es more	e knowle	edgeable	e- at the	end of th	ne course	.	2	U	Inderstand
CO3	Students will be able to identify needs and be able to suggest different alternative solutions 3 considering cost constraints.										Apply				
CO4	Studer analys ideas	nts will ses. Poss leading	be able sibility c to IPR.	to have of taking	a watch up entr	nful eye epreneu	on hap Irship ac	penings tivity, p	in their ossibili	surround ty of com	ling for ing up w	creative vith new	3, 4	I	Apply and analyze
					Articul	ation N	latrix: ((CO-PC)-PSO I	Mapping)				
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1		PSO2
CO1	3	3	3	2	2	2	2	2	-	-	-	2	2		2
CO2	3	3	3	2	2	2	2	2	-	-	-	2	2		2
CO3	3	3	3	2	2	2	2	2	-	-	-	2	2		2
CO4	3	3	3	2	2	2	2	2	-	-	-	2	2		2
Module							Syllab	ous							Hours
1 Introduction-Introduction to product design, Significance of product design, product design and development process, sequential Engineering design method, the challenges of product development, Development Process and Organizations-Generic Development Process, Concept Development, Adapting the generic PD process flows, AMF development Process, Product Development Development Process, Product Development									8						
2	Organizations, The AMF Organization. Product Planning and Identifying Customer Needs-Product Planning process, interpret raw data in terms of customers need, organize needs in hierarchy and establish the relative importance of needs, review of the process. Product Specifications Establish target specifications, setting final specifications										8				
3	3 Concept Generation-Activities of concept generation, clarifying problem, search both internally and externally, explore the output, Concept Selection-Overview, concept screening and concept scoring, methods of selection. Concept Testing-Elements of testing: qualitative and quantitative methods including survey, measurement of customers' response. Product Architecture-Modular and Integral architecture, implications, establishing the architecture, Delayed differentiation, Platform Planning. Industrial Design- Assessing need for industrial design, Impact of industrial Design, industrial design									10					
4	Embo and Er procee	diment nvironm lure, En	Design iental Gu	: Desiguideline	n for M s-Intelle gulations	anufact ctual Pr s from g	uring, p operty: overnm	rototypi Elemen ent, ISC	ing. Rol ts and or) system	bust Desi utline, pa 1.	gn. Intel tenting p	lectual P rocedure	roperty s, claim		8
	<u> </u>						Refe	erences							
•	Ulrich K	K. T, and	1 Eppinş	ger S. D	, Produc	t Desig	n and D	evelopn	nent						
• (Otto K,	and Wo	od K, P	roduct I	Design										

Course Code: AM-XXXXX			Biofluid Dynamics					Credits (L-T-P-Cr) : 3-0-0-3						
Pre-requisites: Biology for Engineers, A			Advance	ed Fluid	Mechai	nics								
Course Outcome										I				
S. No.						Ou	tcomes						BT	BT
CO1	Толл	To understand basic concents of fluid mechanics in context of physiclogical flow in human						human	Level	Understand				
01	body	ucistan	i Dasie (loncepta	s of fiul	u meen	ames m	COMUN	or piry.	siologica	i now m	numan		Analyze
CO2	To un	derstand	l the rhe	ologica	l of bod	v fluids	such as	blood						Understand
	_													
CO3	To an	alyse ph	iysiologi	ical flov	vs in hu	man cir	culation	and res	piratory	systems.				Understand
CO4	To de	sign and	l analyse	e bioflui	d mech	anics pr	oblems	related (o clinic	al applica	ations			Apply and
					Articul	ation N	Iatrix: (CO-PC)-PSO I	Mapping)			anaryze
СО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	1	1	-	-	-	2	1	1	3	2
CO2	3	3	3	2	1	2	-	-	-	2	1	1	2	3
CO3	3	2	2	2	1	1	-	-	-	2	1	1	2	2
CO4	3	2	2	2	2	3	1	1	1	2	2	2	3	3
Module				1	1	•	Syllab	ous		I		•	•	Hours
1	Introductory Fluid Mechanics: Fluid Properties, Basic Laws, Governing Equations; Laminar Flow, Couette Flow, and Hagen-Poiseuille Equation.							8						
2	2 Blood Rheology: Blood Composition, Blood Rheology, Relationship between Blood Composition and Rheology, Constitutive Equation for Blood, Large Artery Hemodynamic, Steady Blood Flow at Low Flow Rates, Unsteady Flow in Large Vessels						6							
 Circulatory System: Anatomy of the Vasculature, Gross anatomy of Heart, Cardiac pumping process, Cardiac Cycle, Cardiac Pumping Power and Ventricular Function, Arterial Pulse Propagation, Systolic and Diastolic pressure, Windkessel Model, Arterial Wall Structure and Elasticity, Pressure–Flow Relationships: Purely Oscillatory Flow, Osmotic Pressure, The Capillaries, The Veins, Cardiac Valve Dysfunctions and Heart Failure. 							6							
4	 The Interstitium: Interstitial fluid flow, Darcy's law, Clearance of Edema, Detailed parameter derivation Ocular Biomechanics: Ocular anatomy, Biomechanics of Glaucoma, Tonometry, Drainage of Aqueous Humor in Normal and Glaucomatous Eyes, Drainage of Aqueous Humor in Normal and Glaucomatous Eyes, Ocular Blood Flow, Optic Nerve Head Biomechanics, 								8					
5	Respi Elastic Syster Transt	ratory city and n during fer in Lu	System Surface Differe 1ngs, Pa	: Gross e Tensi ent Brea rticle Ti	Anato on Effe thing Co cansport	my and cts, Flo ondition in the I	1 Physic w Beha s, Studic Lung,	ology, 1 viour in es of Wa	Biofluid 1 Upper all Shear	Dynam and Lo r Stress ar	ics of H wer Hur nd Its Im	Breathing nan Resp plication	, Lung piratory s, Mass	8
							Refe	rences						
•]	Ethier, (Press.	C. R., &	Simmo	ns, C. A	. (2007). Introd	luctory b	piomech	anics: f	rom cells	to organ	nisms. Ca	mbridge	University
•	"Biome	chanics:	Motion	í", Flow	, Stress,	, and Gr	owth", `	r.C. Fu	ng, Spri 2	nger-Ver	1ag, 199	J		
•	ј.N. Ма рмр	zumdar,	, В10-fl М. "Сст	uia Mee	ular Dhe	, world	i Scienti	пс, 199 oth Бл	2. ition M	$\left[a_{\rm chv} 20 \right]$	01			
•	C Klier	nstreuer	"Bio-fl	uid Dvr	ulai Fily namics"	Tavlor	& Fran	, o Eu cis	111011, IVI	1080y, 20	01.			

B.Tech. (Honors)

(16-20 credits, during 5th to 7th semester)

Course Code: AM-XXXXX	Advanced Biomechanics	Credits (L-T-P-Cr) : 4	1-0-0-4
Pre-requisites: Biology for Engineers, E	Jiomechanics		
	Syllabus		
Kinematics: Body Segment Parameters	: Method of Measuring and Estimating	g Body Segment Parameters, Tw	o Dimensional
and Three-Dimensional Computational M	Aethods.		
Two-Dimensional Inverse Dynamics : F	'lanar Motion Analysis, Numerical For	mulations, Human Joint Kinetics	. Three-
Dimensional Kinetics: Data Required for	Three-Dimensional Analysis, Anthrop	ometry and Three-Dimensional	Kinetics
Calculations			
Computer Simulation of Human Mo	vement: Mathematical Formulations,	Free Body Diagrams, Lagrange	's Equation of
Motion, Numerical Solution Techniques,	Control Theory, Advantages and Limit	tation of Computer Models.	
Mechanics at the Nanoscale: Intermol	ecular Forces and Their Origins; Sing	le Molecules; Thermodynamics	and Statistical
Mechanics, Motion at the Molecular and	Macromolecular Level, Experimental	Methods at the Single Molecule	Level - Optical
and Magnetic Traps, Force Spectroscopy	, Light Scattering.		
Cellular Mechanics: Static and Dyna	amic Cell Processes; Cell Adhesion,	, Migration and Aggregation;	Mechanics of
Biomembranes; The Cytoskeleton and Co	ortex		
Tissue Mechanics: Elastic (Time Inc. Continuum and Microstructural Models Physical Regulation of Cellular Metaboli	lependent); Viscoelastic and Poroela ; Constitutive Laws; Electromechanica ism; Experimental Methods - Macrosco	stic (Time-Dependent) Behavio al and Physicochemical Propert pic Rheology.	or of Tissues; ies of Tissues;
	References		
• Fung, Y. C. Biomechanics: Mechani	cal Properties of Living Tissues. New	York, NY: Springer-Verlag, 1993	3.
• Nossal, R., and L. Lecar. Molecular	and Cell Biophysics. Cambridge, MA:	Perseus Books, 1991.	
• Lodish, H., et. al. Molecular Cell Bio	ology. New York, NY: Scientific Amer	ican Books/W.H. Freeman, 1995	<i>.</i>
• Dill, K. A., and S. Bromberg. Molec	ular Driving Forces. New York, NY: R	outledge, 2002. ISBN: 97808153	320517.
• Nihat Ozkaya and Margareta Nordin	Fundamentals of Biomechanics: 3 rd Ec	lition. VNR, New York.	
• David A. Winter Biomechanics and	motor control of Human Movements: 3	rd Edition, John Wiley & Sons. I	nc.
• D. Gordon, E. Robertson, Graham E	. Caldwell, Joseph Hamill Research Me	ethods in Biomechanics: Human	Kinetics
	, i		

Course Code: AM-XXXXX	Biomimetics	Credits (L-T-P-Cr) : 4	-0-0-4						
Pre-requisites: NIL									
Module	Syllabus								
Intro to bio inspired design, Case Studies. Biological vs Human Solutions, Evolution and rate of innovation, Nature as mentor,									
source of inspiration, Self-healing, Self	E-assembly, Hierarchal structures, Struct	ure-function relationship in biolo	ogical systems,						
Biomineralization, Bioprocesses, Systems Organization: Bees as a model, Locomotion: Control, balance, gait Bio-inspired									
robotics, Design Challenges, Design Process, Requirements, abstraction, process, Problem decomposition, Representation and									
Analogical thinking, Inventions inspired by nature for biomedical applications									
References									

• Benyus, J. M. (1997). Biomimicry: Innovation inspired by nature (pp. 9-10). New York: Morrow.

• Peter Forbes, The Gecko's Foot: Bio-inspiration: Engineering New Materials from Nature, W. W. Norton & Company , May 17, 2006

• National Research Council, Inspired by Biology, The National Academies Press, 2008

Cou	rse Code: AM-XXXXX	Poromechanics	Credits (L-T-P-Cr) : 4-0-0-4				
Pre-requisites: Heat Transfer, Advanced Fluid Mechanics, Finite Element Methods							
Syllabus							
Introduction: Concept of volume fraction; particle scale; continuum scale, Flow Through Porous Media: General conservation							
laws; con	stitutive assumptions; Darcy's la	aw; Richards's equation					
FE Form	nulation of Transient Fluid Co	onduction Problem: Strong and weak f	orms; Galerkin approximation; r	natrix problem;			
solution of	solution of elliptic and parabolic systems; time-integration algorithms-stability and accuracy.						
FE Forn	FE Formulation of Solid Deformation Problems: General conservation laws; constitutive assumptions; Hookean and non-						
Hookean	Hookean materials; strong and weak forms; Galerkin approximation; matrix problem.						
Counled	Counted Solid Deformation Fluid Flow Ducklang, Mixed variational minimized as interaction for (mixed) nearbolic systems						

Coupled Solid Deformation-Fluid Flow Problems: Mixed variational principles; time integration for 'mixed' parabolic systems, stability and accuracy; incompressibility constraint; the Lagrange multipliers and penalty methods, Advanced Topics on Multiscale Simulations for Porous Media

References

- R. de Boer, Theory of Porous Media, Highlights in the Historical Development and Current State, Springer Verlag, 2000
- L.E. Malvern, Introduction to the Mechanics of a Continuous Medium, Prentice Hall, Englewood Cliffs, NJ, 1969
- T. J. R. Hughes, The Finite Element Method, Prentice-Hall, Englewood Cliffs, NJ, 1987
- J. Bear, Dynamics of Fluids in Porous Media, Dover Publications, NY, 1972

Course Code: AM	Mechanics of Composite Materials	Credits (L-T-P-Cr) : 4-0-0-4						
Pre-requisites: Continuum Mechanics / Solid Mechanics, Basic Engineering Mathematics, Linear Algebra, Differential Equations								
Syllabus								
Introduction: Classification and characteristics of composites, Conventional vs. Composite materials, Advantages and limitations, Salient applications in various fields, Fabrication technologies, Properties of matrix and reinforcement materials. Micromechanics: Fiber volume fraction, micro-mechanical relations, determination of strength and stiffness, Environmental								
 Salient applications in various fields, Fabrication technologies, Properties of matrix and reinforcement materials. Micromechanics: Fiber volume fraction, micro-mechanical relations, determination of strength and stiffness, Environmental effects-Hygro-thermal behavior. Macromechanics: Basic stress-strain relationships for anisotropic materials, engineering constants for orthotropic materials, stress-strain relations for a lamina of arbitrary orientation, effective moduli, invariant properties of anorthotropic lamina, special cases of laminate stiffness, laminate strength analysis, concept of inter-laminar stresses and delamination. Failure theories and Damage mechanics: Failure mechanisms, maximum stress theory, maximum strain theory, Tsai-Hill theory, Tensor polynomial failure criterion, first ply failure theory, Introduction to damage theory based on continuum damage mechanics. 								
References								

- Mechanics of fibrous composites: Carl T. Herakovic
- Principles of Composite Material Mechanics: R. F. Gibson
- Mechanics of Composite Materials: R. M. Jones
- Introduction to Composite Material: Stephen W.Tsai and H. Thomas Hahn
- Composite Materials and their use in Structures: J. R. Vinson and T.W. Chou

Co	ourse Code: AM	Multiscale Modelling	Credits (L-T-P-Cr) : 4-0-0-4						
Pre-requ	Pre-requisites: Continuum Mechanics / Solid Mechanics, Differential Equations								
		Syllabus							
Introduc	Introduction: Examples and motivation for exploring multiscale behaviour of materials, Relevant material properties at different								
scales.									
Review o	of Preliminaries: Prerequis	ite mathematics, Fundamentals of Thermodynamic	es and statistical mechanics.						
Molecula	Molecular Dynamics and Related Issues: Particle-based methods, EAM/MEAM potentials: bridging from QM, Atomistic								
Plasticity	, Damage & Fatigue, Mole	cular Dynamic Simulation Methods.							
Meso-sca	le methods: Overview and	l need, Quasi-continuum methods, Density Function	onal method.						
Homoger	nization and Bridging: M	ulti-scale homogenization and stochastic homoge	nization, Inter-scale exchange and Scale						
bridging.									
Computa	tional Application: Vari	ational multiscale methods, Numerical resolution	and asymptotic behaviour of stochastic						
PDEs, En	riched continuum models a	nd design.							
		References							
• An I	ntroduction to Multiscale	Modelling with Applications, Pietro Asinari an	d Eliodoro Chiavazzo, Societa Editrice						
Escu	lapio								

- The Art of Molecular Dynamics Simulation, D. C. Rapaport, Cambridge University Press
- Molecular Dynamics Simulation: Elementary Methods, J. M. Haile, Wiley
- Material Inhomogeneities and their Evolution: A Geometric Approach, Marcelo Epstein · Marek Elzanowski, Springer
- Principles of Multiscale Modeling, E Weinan, Cambridge University Press

Course Code: AM-	Structural Reliability	Credits (L-T-P-Cr) : 4-0-0-4	
Pre-requisites: Mathematics			
	Syllabus		
Introduction: Course Overview, Basic St	tatistics, Theory of Probability, Probabilit	y Distributions (Continuous & Discret	ete),
Random Variables			
Analytical Methods Reliability Analysis:	Failure Surface & Definition of Reliability	ty in Normal Space (Cornell's Reliab	ility
Index), First Order Reliability Method	(FORM), Hasofer-Lind's Definition of	Reliability, Rackwitz-Fiessler Algorit	thm,
Asymptotic Integral, Second Order Reliabil	ity Method (SORM)		
Simulation Methods: Monte-Carlo Metho	ds Latin Hypercube Sampling, Variance R	eduction Technique, Importance Samp	oling

Simulation Methods: Monte-Carlo Methods Latin Hypercube Sampling, Variance Reduction Technique, Importance Sampling and Adaptive Sampling, Subset Simulation

Stochastic Analysis: Implicit Performance Function, Polynomial Response Surface Method (RSM), Stochastic Response Surface Method (SRSM), Stochastic Models of Loads, Code Calibration, Partial Safety Factors, LRFD Format, System Reliability, Time Varying Reliability Analysis

Additional Topics: Reliability Based Optimization, Introduction to Stochastic FEM, Case Studies, Term Project.

References

- Probability, Statistics and Reliability for Engineers and Scientists: Ayyub B. M, McCuen R. H.
- Probability, Random Variables and Stochastic Processes: Papoulis A.
- Structural Reliability Analysis and Design: Ranganathan R.
- Structural Reliability: Analysis and Prediction: Melchers R E.
- Methods of Structural Safety: Madsen H O, Krenk S. and Lind N. C.
- Reliability Based Structural Design: Choi S. K, Grandhi R. V. and Canfield R A.
- Reliability and Optimization of Structural Systems: Rackwitz R., Augusti G. and Borri A.
- Structural Reliability Using Finite Element Methods: Waarts P. H.,
- Reliability Assessment Using Stochastic Finite Element Analysis: Haldar A. and Mahadevan S.
- Computational Analysis of Randomness in Structural Mechanics: Bucher C.

Course Code: AM-	Structural Stability and Dynamics	Credits (L-T-P-Cr): 4-0-	·0-4					
Pre-requisites: Advanced Solid Mech	anics, Engineering Vibrations							
	Syllabus							
Introduction: Concepts of Stability, Equilibrium path, Stability criteria, Method of Neutral Equilibrium; Recapitulation of Critical								
Load for Euler Column, Effective-length	h concept and design curve, Effects of Imperf	ections / Initial curvature, Eccent	ricity of					
loading etc.; Inelastic buckling of columns, Double and Tangent Modulus theory, Shanley's theory, Beam-Columns, buckling by								
torsion and torsion-flexure								
Stability of Plates and Shells: Differen	itial Equations of plate Buckling linear theory,	stability of rectangular plates und	ler axial					
compression and shear, Effect of imper	fections, post-buckling behavior of plates; Sta	bility of cylindrical Shells under	uniform					
axial pressure and torsion, Effect of imp	erfections.	ntial Changetanistics of Domania D						
of continuous systems. Formulation of t	systems: Objectives, Types of Loadings, Esse	ential Characteristics of Dynamic P	roblems					
Continuous Systems: Figen Value Pro	blems and Orthogonality of Natural Modes. R	avleigh's Method Ravleigh Ritz	Method					
Free vibration of strings bars & shafts	Beams- Coupled natural modes Effects of Rota	ry inertia and Shear Natural Vibra	ations of					
Plates Discretization of continuous syste	ems: Dynamics matrix for flexural axial & Tors	ional effects Numerical Evaluation	n [.] Finite					
Difference, Newmark's, Wilson's, Houl	olt's Method. Introduction to Nonlinear Vibrat	ion.	in T linte					
Random Vibrations: Stationary & Erg	odic Random processes, correlation and autoco	rrelation functions, power spectral	density					
function, Response of Discrete and Con	inuous systems to Random excitations.							
Introduction to Nonlinear Analysis								
	References							
• Theory of elastic Stability: S. P. T	imoshenko and J. M. Gere							
Principles of Structural Stability 7	heory: A. Chazes							
Background to Buckling: H.G.All	en and P.S.Bulson							
Structural Stability of Columns ar	d Plates: N.G.R.Iyengar							
• Dynamics of Structures: W C Hu	ty and M F Rubinstein							
Structural Dynamics: M. Mukhop	adhyay							
• Dynamics of Structures: Clough a	nd Penzien.							
• Structural Dynamics: Theory and	Computation: Mario Paz.							
• Dynamics of Structures: J L Hum	ar							

C	ourse Code: AM-	Advanced H	eat Transfer	Cr	edits (L-T-	P-Cr):4	-0-0-4	
Pre-requisites: Heat Transfer								
Syllabus								
Introduction equation, A equations, Mixed cor Angles, Ra	on - Review of f Analytical solutions of two- boundary layer equations, F nvection flows, Conjugate he adiative Intensity, Heat Flux,	Fundamentals of h dimensional steady state orced convection over e eat transfer analysis. Ra Pressure and Characteri	eat transfer. heat conduction; xternal surfaces at diative Heat Trans stics, Radiative tra	Conduction: Transient co nd internal du sfer: Thermal ansport equation	General nduction. Co cts; Similarit radiation, Er on.	heat onvection: y solutions missive Po	conduction Governing s. Free and ower, Solid	
References								

- D.P. Incropera, P.P. and Dewitt, Fundamentals of Heat and Mass Transfer, Wiley Eastern
- Adrian Bejan, Convective Heat Transfer, Wiley India.
- Cengel Y A, Heat Transfer A Practical Approach, McGraw Hill
- Kays, Crawford and Weigand, Convective Heat and Mass Transfer, McGraw Hill.
- Siegel and Howell, Thermal Radiation, McGraw Hill.
- Kraus A.D., Aziz, A., and Welty, J., Extended Surface Heat Transfer, McGraw Hill
- Adrian Bejan, Allan D. Krams, Heat Transfer Handbook, John Wiley & Sons. 8. J. P. Holman, Heat Transfer, McGraw Hill

Course Code:	Boundary Layer Theory	Credits (L-T-P-Cr) : 4-0-0-4			
Pre-requisites: Advanced Fluid Mechanics, Heat Transfer.					

Syllabus

Incompressible Laminar Boundary Layers: Exact solutions of the NavierStokes equation exhibiting boundary layer at low viscosity. The boundarylayer equations in the spirit of Prandtl. Scaling, non-dimensionalisation and Reynolds number. Limitations of potential flow past a cylinder. Prandtl's boundary-layer equations in two dimensions deduced by order-of-magnitude arguments. Blasius solution: displacement thickness, skin friction, drag.

Transition and Incompressible Turbulent Boundary Layers: Concept of stability; basis of boundary layer stability analysis; physics of transition to turbulence. Reynolds stresses, mean velocity and shear stress in a turbulent boundary layer; the log law and power law profiles. Turbulent boundary layers in zero and non-zero pressure gradients. Separation in adverse pressure gradients. Concept of and occurrence in steady flows, and at rear stagnation point of impulsively started cylinder.

Boundary Layer Separation & Flow Control: Causes of boundary layer separation and its consequences, active and passive flow control, various different flow control techniques and their applications.

Introduction to Perturbation Theory: Regular and singular perturbations. Examples from algebraic equations and ordinary differential equations. The classical boundary-layer equations of Prandtl as the leading term in a matched asymptotic expansion. Exact solutions of the classical boundary-layer equations like Flow past a wedge: Falkner Skan. Far wake of a flat plate. Two-dimensional jet. Lock's mixing layer. Prandtl transformation. PrandtlGlauert law for subsonic flow; Ackeret's law and applications. Axisymmetric

flows: Mangler's transformation. Split disc Ekman layer problems: Stewartson layers. Glauert wall jet.

Thermal Boundary Layer: Introduction to thermal boundary layer, heat transfer in boundary layer, convective heat transfer, importance of non-dimensional numbers, Prandtl number, Nusselt number, Lewis number etc.

References

- "Boundary Layer Theory", Schlichting, H., McGraw Hill Inc.
- "The Laminar Boundary-Layer Equations", Curle, N., Oxford University Press.
- "Laminar Boundary Layers", Rosenhead, L. (Edited), Oxford University Press.
- "An Introduction to Fluid Mechanics", Batchelor, G. K., Oxford University Press.
- "Separation of Flow", C.T. Chung, McGraw Hill Inc.

Course Code:	Turbulent Flows	Credits (L-T-P-Cr) : 4-0-0-4						
Pre-requisites: Engineering Fluid Mechanics, Thermodynamics, Engineering mathematics, Statistical methods.								

Syllabus

Introduction: Flow instability and transition to turbulence, Nature of Turbulence, Indicial notation for tensors, Fourier transforms and Parseval's theorem. **Governing Equations of Turbulence, Eulerian, Lagrangian and Fourier descriptions of turbulence Statistical description of turbulence:** Reynolds Averaged Navier-Stokes equations, Reynolds stress evolution equations. **Kolmogorov's Hypothesis:** Diffusivity of turbulence and turbulence length scale. **Filtered Description of Turbulence:** Bridging methods and large eddy simulation (LES).

Turbulent Free Shear Flows: Free Shear Flows- jet flows including heat transfer- 2D flows, wall jet and plane jets, its structure; turbulent jets, turbulent mixing layer and buoyancy effects- its structure; turbulent wake flows, wake of self-propelled bodies; wall-bounded shear flows- its structure; boundary layer flows; thermal plume.

Dynamics of Turbulence: Linear Instability Theory, Nonlinear Stability Analysis, Dynamical Systems, Introduction to Chaos. Vorticity dynamics Reynolds stress and vorticity, vortex stretching, mean vorticity equation, kinetics energy and mean flow, kinetic energy of fluctuations, energy cascade, dissipation, material element deformation, mixing Navier-Stoke's equation for turbulent flow, turbulent energy dissipation equation.

Turbulence modeling: General comments on turbulence models; Method of solving turbulent equations- Direct numerical simulation (DNS), Large-eddy simulation (LES), Reynolds averaged Navier-Stokes equation (RANS), k- \in models. Turbulence models: Eddy viscosity models -zero equation models (constant eddy viscosity and mixing length models), one equation models, two equation models; Reynolds stress transport models (RSM). Wall treatments.

References

- "Turbulent Flows", S.B. Pope, Cambridge University Press, 2000.
- "Turbulence Modeling for CFD" David C. Wilcox, DCW Industries, 3rd Edition, 2006.
- "Viscous Fluid Flow", F.M. White, Tata McGraw Hill, 2011.
- "A First Course in Turbulence", H. Tennekes and J.L. Lumley, The MIT Press, 1972.
- "Turbulence", O. Hinze, McGraw Hill Inc.
- "Turbulent Flow: Analysis, measurement and Prediction", Bernard, P.S., A.D. Wallace, J.M., John Wiley & Sons Inc., New Jersey, 2002.

Course Code:	Course Code: Advanced Computational Fluid Dynamics Credits (L-T-P-Cr) : 4-0-0-4												
Pre-requisites: Computational F	luid Dynamics												
	Syllabus												
Finite Volume Method for complex geometries: Types of grids, Cartesian vs. curvilinear grids, Block-structured grids, Body- fitted grids in complex geometries, orthogonal grids, difficulties of curvilinear grids, structured/unstructured/hybrid. Mapping functions: grid transformation on complex geometries, Transformation of governing equation in plane, Conservative and Nonconservative form of equations, transformation of Laplace equation, N-S equations in transformed plane, matrices and Jacobians. Unstructured grids and its discretization, discretization of diffusion and convective terms, treatment of source terms, assembly of discretized equations, Boundedness and Transportiveness, TVD Scheme, Pressurevelocity coupling in unstructured meshes. staggered vs. co-located grid arrangements. Rhie and Chow's pressure interpolation. Accelerated CFD Methods: Advanced Numerical Techniques: Multigrid, Conjugate Iteration, and Generalised Minimal Residual (GMRES) Methods. Hardware Techniques: Introduction to PC and HPC Architecture. CPU and GPGPU parallel programming. Multiphase Flow Modeling: Introduction: Multiphase flow classifications (separated and dispersed flows). Examples, Challenges in modelling, Variables of interest, Fluid-particle coupling (1-way, 2-way, and 4-way coupling) Lagrange- Euler model: Discrete Phase Modelling (DPM) for particles and suspended phases. Discrete Phase Boundary conditions and its effects Discrete Element Method (DEM) Arbitrary Lagrangian and Euler (ALE) method, Immersed boundary method; Immersed interface methods, Hybrid methods Introduction to Euler-Euler model: Volume of Fluid (VoF) Method, Interface tracking & capturing methods, Level Set (LS) method, Coupled VoF-LS method, Eulerian multiphase model (EMM), Mixture (Algebraic Slip) mode (ESM), Eulerian Granular Multiphase model (EGMM) Comparison of Models and their selection Application of CFD for modelling and simulation: Practical problem solving using CFD techniques													
	References												
 "An Introduction to Compute Pearson Education, England, "Computational Fluid Dynam" "Using HPC For Computation Academic Press, 2015. "Computational Fluid Flow a 5. "Numerical Heat Transfer at the second second	itional Fluid Dynamics: The Finite Volume Method", H.K 2007. ics for Engineers", B. Andersson & others, 1 st edition, Camb nal Fluid Dynamics: A Guide to High Performance Compu nd Heat Transfer" (2nd edition), K. Muralidhar and T. Sunda and Fluid Flow", S.V. Patankar, McGraw-Hill, New York, 1	. Versteeg and W. Malalasekara, 2nd oridge University Press, U.K., 2012. ting for CFD Engineers", Shamoon Ja ararajan, Narosa Publishing, 2004. 980.	amshed ,										

B. Tech (Research): Pool-I

S No	Course Code	Subjects (Semester)	Credits (L+T+P)
1.	AM****	Advanced Biomechanics (V)	4-0-0
2.	AM****	Bioinstrumentation and Signal Processing (VI)	4-0-0
3.	AM****	Design, Innovation, and Entrepreneurship in Biomedical Engineering (VII)	4-0-0
4.	AM****	Elective* (VII)	4-0-0
		List of Electives	
1.	AM****	Artificial Intelligence in Biomedical Engineering	
2.	AM****	Biomaterials and Artificial Organs	
3.	AM****	Medical Imaging and Diagnostics	
4.	AM****	Finite Element Applications in Biomedical Engineering	
5.	AM****	Sports Biomechanics	

Course Code: AM-XXXXX Advanced Biomechanics							Credits (L-T-P-Cr) : 4-0-0-4							
Pre-requisites: Biomechanics														
	Course Outcome													
S. No.				0	utcom	es				BT Le	evel	BT D	escript	ion
CO1	To C mover	lassify nent	and	analyze	norm	nal and	a patho	ologica	l gait	2,4	ŀ	Understa	and, Ar	alyze
CO2	To un biolog	derstan	d how	mechan	nics at level	molect	ılar sca	le affec	cts the	2		Und	lerstand	l,
CO3	To ide tissues on by	entify the sand sl load, di	te struc how a o isuse, o	tural ar compre	nd mate hension	rial pro	perties alteration ther var	of biol tions bi riables	ogical rought	2		Und	lerstand	1,
CO4	To int	egrate	knowle f clinic:	edge an al appli	d skills	s of bio	omecha biome	nics in	other	3, 4	1	Analy	ze, Ap	ply
	Articulation Matrix: (CO-PO-PSO Manning)													
CO	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12												PSO	PSO2
CO1	3 2 2 2 1 - - 2 2 1											1	1 2	1
CO2	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$										1	2		
CO3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$											2	1	
CO4	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$												1	2
Modul e	Syllabus												Hours	
1.	Kinematics: Body Segment Parameters: Method of Measuring and Estimating Body													10
	Segment Parameters, Two Dimensional and Three-Dimensional Computational Methods											Methods		10
	Two-Dimensional Inverse Dynamics : Planar Motion Analysis, Numerical											Numerical		
	Formulations, Human Joint Kinetics. Three-Dimensional Kinetics: Data Required for													
	Three-Dimensional Analysis, Anthropometry and Three-Dimensional Kinetics													
2	Calcul		mulati	on of I	Tumon	Maria	monte	Mathan	antianl	Economia 1 of	iona I	Trac Dodre		0
2.	Diagra Theory	ums, La y, Adva	igrange ntages	s Equ and Li	ation c	of Moti n of Co	ion, Nu mputer	imerica Model	l Solut s.	ion Tech	iniques	s, Control		0
3.	Mecha Molec Macro Magne	anics a ules; T molecu etic Tra	at the hermod lar Lev ps, For	Nanos lynamic el, Exp ce Spec	scale: cs and eriment ctroscop	Interm Statisti tal Met by, Ligh	olecula ical Me hods at nt Scatt	r Forc echanics the Sin ering.	es and s, Moti gle Mo	Their on at the lecule Le	Origin e Mole vel - C	s; Single ecular and optical and		10
4.	Cellul Aggre	ar Mec gation;	hanics Mecha	: Static nics of	and D Biomer	ynamic mbrane	Cell P s; The	rocesse Cytoske	s; Cell eleton a	Adhesion and Corte	n, Mig x	ration and		8
5.	Tissue Depen Laws; Regula	e Mech dent) B Electr ation of	anics: Behavio romech Cellula	Elastic r of Ti anical ar Meta	(Time ssues; (and bolism	e Indep Continu Physico ; Exper	endent) ium an ochemic imenta); Visco d Micro cal Pro l Metho	oelastic ostructu operties ods - M	and Po ral Mod of Ti acroscop	roelast els; Co ssues; ic Rhe	ic (Time- onstitutive Physical ology.		6
]	Refere	nces						
• Fun	g, Y. C.	Biome	chanics	: Mech	anical	Propert	ies of L	Living T	lissues.	New Yo	ork, NY	: Springer	-Verlag	, 1993.
 Nos Lod Dill 9780 	 Nossal, R., and L. Lecar. Molecular and Cell Biophysics. Cambridge, MA: Perseus Books, 1991. Lodish, H., et. al. Molecular Cell Biology. New York, NY: Scientific American Books/W.H. Freeman, 1995. Dill, K. A., and S. Bromberg. Molecular Driving Forces. New York, NY: Routledge, 2002. ISBN 9780815320517. 									, 1995. ISBN:				
• Niha	at Ozkay	ya and l	Margar	eta Nor	dın Fui	ndamen	itals of	Biomed	chanics	: 3 rd Edit	10n. Vl	NK, New Y	ork.	

- David A. Winter Biomechanics and motor control of Human Movements: 3rd Edition, John Wiley & Sons, Inc. ٠ •
- D. Gordon, E. Robertson, Graham E. Caldwell, Joseph Hamill Research Methods in Biomechanics: Human Kinetics

Cour	se Cod	e: AM-	XXXX	XX	Biomedical Instrumentation and Signal Processing						Credits (L-T-P-Cr) : 4-0-0-4				
Pre-requ	isites:	Basics (of Instr	umenta	tion an	d Signa	al Proce	essing	8						
						Cou	urse Ou	itcome							
S. No.					Outc	omes					B	T Level	BT Desc	ription	
CO1	Unde Artifa	rstand T icts in F	Гуреs & Biomed	& Chara ical Sig	acteristi gnals.	cs and	Source	s of No	ises an	d		2,4	Unders analy	tand, /ze	
CO2	Desig Signa	n of Fil ls.	lters for	r Noise	and Ar	tifact F	Remova	l from	Biomed	lical		2	Unders	tand,	
CO3	Under Chara	rstand M Icteristi	Method cs.	s for A	nalyzin	g Bion	nedical	Signal				2	Understand,		
CO4	Explore Alternative Techniques of Analyzing Biomedical Signals 3, 4												Analyze, apply		
				Arti	culatio	n Matr	rix: (CO)-PO-I	PSO M	apping)				
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	P 0 1	PO12	PSO1	PSO2	
CO1	3	2	2	2	2	1	-	-	-	1	1	1	3	1	
CO2	3	3	2	1	1	2	1	1	-	1	1	1	3	2	
CO3	3	2	2	2	1	1	-	-	1	1	2	1	2	2	
CO4	3 2 2 2 1												2	2	
Module	D '	0		A 1'	1.7.4	Syll	abus	11	1 1 1	· 1 T			Hou	rs	
1.	Basic Concepts of Medical Instrumentation: Generalized Medical Instrumentation System, Measurement Constraints, Classifications, Static and Dynamic Characteristics, Design Criteria, Medical Instrumentation Development Process Regulation of Medical Devices												8		
2.	Theory, Analysis and Design of Biomedical Transducers: Optical, Photo Electric, Electrochemical, Electrical, Mechanical, Electromechanical and Thermoelectric, Applications to Biomedical Systems, Transducer Characteristic											, Photo- cal and cteristics	8		
3.	Medi Medi Ampl Meas and	cal Me cal Para ifiers, uremen Pressur	easuran meters Variou t Of EF e Mea phy Pi	nd Sen like EC is Typ EG, EM asuring	isor: C CG, Art es of G and ' Instru	haracte erial B Electro Their D ments	eristics lood Prodes us Diagnos in Bi	and D essure l sed in tic App iomedic	esign f Heart S ECG, licatior cal En	for Mea ounds, 1 EEG as in Me gineerin	Bio- Ancedici ng,	ement of Potential I EMG, ne, Flow Medical	8		
4.	Intro Intera of Ac Trans the El Math Cell M ECG,	duction action of tion Po mission lectrical ematic Membra EMG	f Signa f Signa tential n and T l Signa al Moo nne. Ne And Ev	Bioeleo ls in Ne along t Transdu ls. dels: E ural Co roked P	ctric E ervous S he Nerv ction P lectrica ontrol M	Phenon Systems ve Fibro rocess 1 Circu Iechani Is.	nenon: s. Discu es. Volt and Re nits Mo- ism, Ge	Gene Ission o tage Cli ceptors dels an enesis a	ration, f Initiat amp Ex . Frequ d Desc nd Cha	Transi tion and perime ency M ribing I racteris	missi l Pro nts, l lodu Beha tics	ion and pagation Synaptic lation of viour of Of EEG,	10		
5.	Remo Struct Proce Filter	oval of tured 1 sses, N ing.	f Nois Noise, Ioises a	e and Physic and Ar	Artifa	acts fr Inter Present	om Bi ference t in EC	i omedi , Stati G, Tin	cal Sig onary ne and	gnal: I and N Freque	Rand Jonst ency	om and ationary Domain	8		
]	Referen	ices							
Khandpur R.S., Hand book of Biomedical instrumentation, TMH. Rangayyan, R.M., 2015. Biomedical signal analysis (Vol. 33). John Wiley & Sons. Reddy, D.C., 2005. Biomedical signal processing: principles and techniques. McGraw-Hill Tompkins, W.J., 1993. Biomedical digital signal processing. Editorial Prentice Hall. Sörnmo, L. and Laguna, P., 2005. Bioelectrical signal processing in cardiac and neurological applications (Vol. 8). Academic Press.															

Co	Course Code: AM- XXXXX			Desi	ign, Inı	iovatio	n, and E Eng	ntrepre	eneursh	nip in Bi	omedical	Cr	edit	s (L-T-P-C	Cr): 3-0-0-3
Pre-I	equi	sites. Ad	lvance	d Bior	nechan	ics	Ling		5						
110-1	cyu	5105.710	ivance		neenan		Co	urse Oi	itcome						
S. No					(Outcom	es				BT Lev	el		BT Desc	ription
CO1	-	Design	and de	velop	devices	for bio	medical	applicat	ion.		2,4		ι	Jnderstand	, Analyze
CO2		Provide	innov	ative s	olution	s for he	althcare	problem	IS		2,3			Understan	d, Apply
CO3		Inculcat	e Entr	eprene	urship	abilities	in the a	ea of he	ealthcar	re.	4			Anal	yze
CO4		Develop entrepre	o leade neursi	ership s nip.	skill in	the area	of biom	edical e	ngineer	ring	3, 4			App	oly
					A	rticulat	ion Mat	rix: (CO)-PO-I	PSO Ma	pping)				
CO	PC 1	PO 2	PO 3	PO 4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	2	PSO1	PSO2
CO1	3	2	2	2	2	1	-	-	-	1	1	1		3	1
CO2	3	3	2	1	1	2	1	1	-	1	1	1		3	2
CO3	3	2	2	2	1	1	-	-	1	1	2	1		2	2
CO4	3	5 2 2 1 1 1 1 1 1 1 2 le Syllabus												2	
	dule Syllabus H Design Process: Creative and Design Thinking, Minimum Viable Product, Business Model H												Hours		
1. Design Process: Creative and Design Thinking, Minimum Viable Product, Business Model Development, Business Plan and Access to Funding. Elements Of Design Process Including Need Identification, Concept Generation, Concept Selection and Implementation with Specific Applications in Healthcare. System Synthesis, Design Analyses, Optimization, Impact on Patient Health and Comfort, Healthcare Costs, Clinical Trials and Regulatory Issues And Medical Ethics.											eed lons and				
2.	Orthopedic Implant Design: Design Concepts, Clinical Problems Requiring Orthopedic Implants 8 for Solution, Principles of Orthopedic Implant Design, Design Parameters. 8												its 8		
3.		Tissue Engineering: Scaffolds, Cells and Regulators, Case Study of Organ Regeneration, Design											gn 10		
		Paramet	ters, L	Design	Specif	ications	: Bioma	terials,	Biocon	npatibilit	y: Local	and S	Syste	mic Effec	ts,
		Corrosio	on and	Wear,	, Regul	ation of	Medical	Device	s	ina Cont	raction, D	egrada	ation	I OI Device	:8:
4.		Cardiov Musculo Applica Testing	vascul oskelet tion o of Me	ar Pro tal Sof f Elec dical I	osthese t Tissu tromec nstrum	es Desig es: Men hanical ent.	n: Hear iscus, In Biomed	t Valve terverte ical De	s and S bral Di vices, G	Stents, D sk, Dent Concept	Devices fo al and Ea of Protot	r Nerv r Impl type D	ve R lants. Devel	egeneration Design au lopment au	n, 10 nd nd
5.		Innovat	tions i	n Hea	lthcare	: Idea g	eneratio	n, mark	et resea	rch, pro	duct deve	lopme	nt ar	nd financin	ıg, 8
		Team de	evelop	ment a	ind bus	iness m	odel for (commer	cializat	ion of he	ealthcare i	nnova	tions	5.	
		Introdu	iction	to ent	repren	eursnip	: Health	care stai	t- ups.	Recent I	nnovatior	is in H	lealtr	icare.	
	7 T .	Maagare		more f		n En ein		A Dari		T					
	2. J 	A stars a	ck, Hu	man Ia	Tanth	n Engine	We also Die	id Desig	gn, 1 Mi	H. 					
	Ј. Г. 7		ани к. <i>т</i> :	Kaale		OOK OI		Julia N	y, MCG		Guulu aan 1	7	200	11	
	ann	as, I. V. I \sim	LISSUE	ana O	i gan R	egenera A Danie	non in A	auits. N	Dicerci	IK, IN I : 7	springer-	verlag	, 200 nci-	JI.	nlant Dazizz
	Cam	bridge Te	exts in	Biom	edical H	A. Pruit Engineer	ring).	mes of	ыота	eriais: r	undamen	lai Pri	ncip	les for fin	plant Design
• \	Vebs	ter J. G.,	Medic	cal Inst	trument	tation: A	Applicati	on and	Design,	4th ed.,	John Wil	ey & S	Sons	New Yor	k.
• J	. D.	Branzino	, Hand	lbook (of Bion	nedical l	Engineer	ing: Fu	ndamen	tals of B	iomedica	l Engiı	neeri	ing, CRC I	Press.
• Measuring the Gains from Medical Research by Kevin Murphy and Robert Topel, Published by the Universit										University of					
	hica	igo Press	0	t on 1	Dre d		Emer T	om de	nd Da	d C1	n Nation	1 D	0.017	f Economic	Desser-1
	studi	es in Inco	ontpu ome an	id Wea	alth Vol	lume 62	ernst E	ernat a	nu Dav		i, inationa	u bure	eau (JI ECONOM	uc Kesearch,
• (<u>Craig</u>	R. Davis	s "Calo	culated	Risk:	A Frame	ework fo	r Evalua	ating Pr	oduct D	evelopme	nt.			

Course Code: AM- VXXXX Finite Element A						ient Ai Engi	nalysis neerin	in Bior g	nedical		L-T-P-O	-Cr) : 4-0-0-4			
Pre-r	eau	isite	s: Adv	anced	Biome	chanics	. Finite	Eleme	s nt Meth	nods					
	- 1						<u>,</u>	Course	Outco	me					
S. No						(Outcom	nes				BT	Level	BT Desc	cription
CO1		To im	ident	ify the and typ	dime dime	nsion, ement(s	variabl	es invo used fo	olved, r finite	constrai element	ns to b analysis	e s.	2	Under	rstand
CO2		Tc ap	form plicatio	ulate, on in bi	programo omedic	m, and al engi	l solve	e a sol	lid me	chanics	problem	n 2	2,3	Under Ap	stand, plv
CO3		Tc de	analy	yze, in d comp	terpret	and ogram	commu or com	nicate mercial	results finite e	obtain element	ed from	n 2.	4	Ana	lyze
CO4		To an en	pursue alysis i gineeri	e highe n the d ng.	r /self-s omain	study a of solic	nd rese l mecha	arch, ir anics ap	volving oplication	g finite e on in bio	element omedical	3	, 4	Ap	ply
		Articulation Matrix: (CO-PO-PSO Manning)													
СО	PC 1	PO PO<												PSO1	PSO2
CO1	3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$												2	1
CO2	(°.)	3 3 3 2 2 1 - - 2 1 1 2 3 3 3 1 2 1 1 - 1 1 1 2													2
CO3	2	3 3 3 1 2 1 1 - 1 1 1 2 3 2 1 2 2 - - 1 2 2 1													1
CO4	3	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$													1
Modu	ıle							Syllabı	IS					Ho	urs
1.		The Finite Element and Finite Difference Methods: Gallerkin, Weighted 6													
	Residuals, Discretization,														
2.		Mechanical Analysis of Structures: Truss Systems, Beam Systems, 2D Solids											Solids,	8	8
		M	eshing,	Organ	Level	Analys	is of B	ones, D	DOFs, H	land Cal	lculation	s of Sim	ple FE		
		pro	oblems	, Unde	rlying I	DES N	licro- a	and mu	Iti-scale	analysi	is, voxel	models,	solver		
			intation	is, large		sorver	D !!		1.0				. .		
3.		Co	ontact	Analy	sis: Fr	iction,	Bondii	ng, Roi	ugh Co	ntact, I	mplants,	Bone-C	ement	5	6
			ow in	Poroue	snout te s Medi	sis a. Pote	ential n	rohlem	s Terz	aghi's c	onsolida	ation Co	nfined		
		an	d uncoi	nfined	compre	a. 100	of cartil	age	13, TCIZ	agin s c	onsonde	uion, co	iiiiicu		
4		н	oot Tr	oncfor	and M	Mass 7	ronen	ort. Di	iffusion	Condi	action at	nd Conv	ection	1	0
		Ea	uivalei	nev of	Equat	ions	Heat T	ransfer	and I	Mass T	ransport	Sequer	ntially-	1	0
		Co	upled	Poroela	astic an	d Trans	sport N	Iodels f	for Solu	te Trans	sport	, bequei	initiality		
		Co	mputa	ational	Biofl	uid D	ynami	cs: Ne	ewtonia	n vs.	Non-Ne	wtonian	fluid,		
		ро	tential	flow			-								
5.		A	oplicat	ion thr	ough (Compu	ter Pr	ogrami	ming &	Comm	ercial S	oftware	: Input	1	0
		fo	Geor	netric	& Mat	terial (Configu	iration,	Loadi	ng and	Bounda	ry Cond	litions,		
		Aι	ıtomati	c Me	sh Ge	neratio	n, No	dal Co	oordina	te and	Nodal	Connec	ctivity,		
		Ca	lculati	on of	Elemer	nt Mat	rices (Stiffnes	ss & N	Aass M	atrices,	Load V	ector),		
		As	sembly	y of Ele	ment N	<i>latrices</i>	s to Glo	bal Ma	trices, I	mposin	g Bound	ary Cond	litions,		
		So	lution	(Gauss	Elimin	ation &	t other	method	ds), and	Post Pr	ocessing				
								Refe	erences				L		
•	E	nerg	gy and I	Finite I	Elemen	t Meth	ods in S	Structur	al Mec	hanics:	I. H. Sha	mes and	C. L. D	ym.	
•	С	onc	epts an	d Appl	ication	s of Fir	nite Ele	ment A	nalysis	: R. D. (Cook, D.	. S. Malk	us and N	1. E. Ples	ha.
•	Т	he F	Finite E	lement	Metho	d Vol.	I-II: O	.C. Ziei	nkiwicz	and R.L	. Taylor				
•	• Finite Element Procedures: K. J. Bathe.														
•	Α	n In	troduc	tion to	Finite I	Elemen	t Meth	ods: J.N	N. Redd	v.					

- Finite Element Methods in Engineering: S.S. Rao.
- Yang, Z. C. (2019). Finite Element Analysis for Biomedical Engineering Applications. CRC Press.

Cou	Course Code: AM-XXXXX Medical Imaging and Diagnostics Credits (L-T-P-Cr) : 4-0-										0-4			
Pre-requ	isites: D	Digital in	nage pro	ocessing										
						Co	urse Ou	tcome						
S.No.					Outc	omes					BT Leve	1 B	T Descri	ption
CO1	Descri imagin systen	ibe the p ng equip ns.	hysics p ment, ir	orinciple Icluding	s underl X-ray, (ying the CT, MR	operati I, and n	on of me uclear in	edical naging		2		Understa	ind
CO2	Apply contex	mathen at of diff	natical n erent me	nethods edical in	of image naging r	e constru nodalitie	uction a	nd proce	essing in	the	2,4	Und	erstand, A	Analyse
CO3	Demo variou	nstrate a s imagir	n under 1g metho	standing ods in he	of the cealthcare	clinical a e.	applicati	ons and	relevan	ce of	2,4	Und	lerstand,	Analyse
CO4	Discuss radiation safety issues related to the operation of medical imaging equipment and implement appropriate safety measures in practice.													Analyse
	Articulation Matrix: (CO-PO-PSO Mapping)													
СО	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01												PSO2	
CO1	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$												3	
CO2	2 2 3 2 1 1 1 1 1 2 2 3 2 1 1 1 - 2 1 1 2												2	
CO3	2 2 3 1 2 1 - 1 2 2 1 3													2
CO4	2 2 2 1 1 2 1 1 2 1 1 2													2
Module														Hours
	X-ray Digita Fluor Angio	equipme al radiog oscopy: graphy:	ent bloc graphy: X-ray in cine an	k diagra discrete nage int	m, X-ray digital ensifier	y tube, c detector tubes, d tal subtr	collimato s, storag ligital flu	or, Buck ge phosp uoroscop	y grid, a hor, and by, Mai	ind pow film sc	er supply anning.		naging	08
2	Comp detect	outed To ors, viev	mograj ving sys	phy: Pr tems, Sp	inciples piral CT	of tomo scannin	graphy, g and ul	CT gen tra-fast	erations CT scan	: X-ray ners.	sources, c	ollimatio	n, X-ray	09
3	Magn static f Induc Block superc electro	etic Res magnetic tion of 1 diagra conducto onic corr	onance c field au nagneti m app rs). Gra	Imagin nd radio c resona roach dient m s. Functi	g: Fund frequence ance sign of MR agnetic onal MF	amental cy wave nals: bu I syste fields, RI (fMR	s of mag , Rotatio ilk magr m, Sys radiofre I).	gnetic reson and p netizatio stem m quency	sonance recessio n, relaxa nagnet coils (se	imaging n of nuc ation pro (perman ending a	g, Interacti elei. Decesses (T nent, elec and receiv	on of nuc 1 and T2 ctromagn ing), shi	clei with). et, and m coils,	12
4	Nuclea Radiat detecte circuit positro	ar Imag tion. Def ors. Gan , pulse l on emiss	ing Sys ectors: mma ca neight an ion tom	tem: Ra gas-fille mera: j nalyser. ography	dioisoto d, ioniz principlo Principl (PET)	opes: alg ation ch e of ope les of sin	pha, beta ambers, eration, ngle-pho	a, and ga proporti collimat oton emi	amma ra ional cou or, phot ssion co	diations unter, G tomultip omputed	, Radioph M counter lier tube, tomograp	armaceut , and scir X-Y pos bhy (SPE	icals atillation sitioning CT) and	10
5	Radia theraj badges	tion Th py: linea s, thermo	erapy ar accele o-lumine	and Ra erator, te escent de	diation ele gami osimeter	Safety ma maci rs, electr	: Effe hine. Ra onic do	cts of r adiation simeter.	adiation measu Radiatio	n: direct ring instant	t and inc struments ction in m	lirect. Ra : dosime edicine	adiation ter, film	09
							Referen	ices						
 William R. Hendee, E. Russell Ritenour, Medical Imaging Physics. Jerry L. Prince, Jonathan M., Medical Imaging Signals and Systems. Pearson Education. Andrew G. Webb, Introduction to Biomedical Imaging, IEEE Press. R.Hendee and Russell Ritenour, Medical Imaging Physics, William, Wiley- Liss. 														

Cou	Course Code: AM-XXXXX Biomaterials and Artificial Organs Credits (L-T-P-Cr): 4-								0-0-4					
Pre-requ	isites: E	Basic kr	nowledg	ge of bi	ology a	nd phy	siology	, Matei	ial scie	nce or e	ngineerir	ng backg	round	
Course Outcome														
S.No.					Outco	omes					BT Level	BT	Descrip	tion
CO1	Under their a	stand tl pplicati	he proportion	perties medicii	and ch	aracteri	istics o	f biom	aterials	and	2	τ	Understa	nd
CO2	Analy	se the	intera	ctions	betwee	en bio	materia	ls and	biolo	gical	2,4	Under	rstand, A	nalyse
CO3	Evalua	ate the c	lesign a	and fab	rication	metho	ds for a	rtificia	lorgans	5.	2, 4	Under	rstand, A	nalyse
CO4	Discuss the challenges and ethical considerations in the development 2, 4 Understand, A of artificial organs.												nalyse	
CO5	Identify emerging trends and future directions in the field of 2, 3 Understand, biomaterials and artificial organs. Understand,												Apply	
	oronia	corrain c	ina arti	Arti	culatio	n Matr	rix: (CO	D-PO-	PSO Ma	apping)				
CO	PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PS01												PSO2	
CO1	3 3 2 3 2 2 - - 3 1 1 3												3	
CO2	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$											2		
CO3	5 2 3 2 2 1 2 1 - 2 1 1 2 3 3 2 2 2 1 2 1 1 2 1 2											2		
CO4	3	2	2	2	2	2	2	1	1	1	-	1	2	2
CO5	3 2 2 2 2 2 2 1 1 1 1 2 2 1 2 1 3 2 3 1 - 1 2 1 1												3	
Module													Hours	
1	Introd	Ination	to Di	omotor	riola. T	Dofiniti	on and	alassi	Figation	of bio	motorial	Dropor	tion of	110013
	hioma	terials	(mechs	unical	chemic	al bio	logical	Δnn	lication	s of bi	material	s, Flope	dicine	00
	Selection criteria for biomaterials Examples of biomaterials used in medical devices													
	Biocompatibility and Host Response: Definition and importance of biocompatibility, Host													
	response to biomaterials (acute and chronic inflammation, fibrosis, foreign body reaction),													
	Factors affecting biocompatibility (surface properties, degradation rate, immunogenicity), In													
2	vitro a	nd in vi	1VO b10	compat	1b1l1ty t	esting i	method	s, Strate	egies to	improv	e biocom	patibilit	y L 4:	00
	engine	ering t	echnicu	g: Den	muon a	ana pri Paffolds	ncipies	of tis	sue eng	neering) printi	g, Scallo	fold_free	tissue	08
	engine	ering t	technia	ues (pe	ell she	et eng	, election	g. self	-assem	bly). C	ell sour	cing for	tissue	
	engine	ering, V	Vascula	rizatio	n and ir	nervati	ion of e	ngineer	red tissu	ies				
3	Design	n of Ar	tificial	Orga	ns: Def	inition	and ex	amples	of artit	ficial or	gans, De	sign crite	eria for	11
	artifici	ial orga	ns (bio	compat	ibility,	mechai	nical pr	opertie	s, funct	ional pe	rforman	ce), Hear	rt assist	
	device	s (ven	tricular	assist	t devic	es, to	tal arti	ficial	hearts),	Kidne	y replac	ement (devices	
	liver e	extracor	s, peritt rporeal	liver si	inport)	Lung	assist d	evices ((extrace	orporeal	membra	ne oxyge	enation	
	artifici	al lung)		-rr 51(),					-porour				
4	Regul	atory	Requir	ements	s for N	Iedica	l Devic	es: Ov	verview	of me	dical dev	vice regu	ilations	09
	(FDA,	Europe	ean Un	ion, oth	ner regu	latory	bodies)	, Classi	fication	n of med	lical devi	ices (Cla	ss I, II,	
	III), Pi	reclinic	al testir	\log and ϵ	evaluati	on (bio	compat	tibility,	safety,	efficacy), Clinica	al trials (phases,	
5	Case	, enapo Studies	\mathbf{A}	ost-ma	tions of	f Biom	ce (auv aterial	erse ev	ent repo	orung, a al Orga	evice tra	opedic ir	calls)	12
	(joint	replace	ments,	bone g	rafts, si	oinal in	nplants), Cardi	lovascu	lar devi	ces (sten	ts, heart	valves.	12
	pacem	akers,	defibri	llators)	, Neur	al pros	stheses	(cochl	ear im	plants,	retinal in	mplants,	brain-	
	compu	iter inte	rfaces)	, Ethica	l and so	ocial iss	ues rela	ated to l	piomate	rials and	l artificia	l organs,	Future	
	directi	ons and	i emerg	ing tec	hnologi	les in b	iomater	als and	1 artific	ial orga	ns.			
• D'	atori-1 C	laise	Amtic	du -4'	to M ·]	Kelerel	ices	dde D '	Date - A	llon C II	ffer F	ndari 1 T	Cal-
 Biomaterials Science: An Introduction to Materials in Medicine by Buddy D. Ratner, Allan S. Hoffman, Frederick J. Schoe and Jack E. Lemons, Academic Press. 										. schoen,				
• Tissu	e Engine	eering: I	Principle	es and	Applicat	tions by	Bernha	ard Pals	son, Jef	frey A.	Hubbell,	Robert P	lonsey, Jo	oseph D.
Bronzino, CRC Press														
 Artifi Regulation 	latory Af	ms by Jo fairs for	Biomat	. Бгопzı erials an	no, CKC	al Devid	ces by St	tephen F	. Amato	and Rich	ard A. En	dres, Woo	odhead Pu	ıblishing.

Cou	rse Coc	le: AM	-XXXX	X		Artifici Biomed	ial Intel lical Er	lligence ogineer	in ing		Credits (L-T-P-Cr) : 4-0-0-4				
Pre-requ	isites: I	Basic kr	nowledg	ge of bio	ology an	d physi	ology, A	AI and 1	ML						
						С	ourse C	Outcom	e						
S.No.					Outc	omes					BT Level	BT	Descript	tion	
CO1	Studen	nts will gence a	be able and its a	to expl	ain the l	basic pr iomedic	inciples	s of artif	ficial		2	U	Inderstan	d	
CO2	Stude	nts will	be able	to appl	y machi	ine lear	ning and	d deep l	earning		2,4	Under	stand, Ai	nalyse	
	algori	thms to	biomed	lical eng	gineerin	g probl	ems.	1	C						
CO3	Stude: inforn	nts will nation f	be able rom me	to use 1 dical te:	natural l xts and	anguag electror	e proce	ssing to th recor	ols to ex ds.	tract	2,4	Under	stand, Aı	nalyse	
CO4	Stude: medic	nts will al appli	be able	to desig	gn and i	mpleme	ent robo	otic syst	ems for		2,4	Under	stand, Aı	nalyse	
CO5	Students will be able to analyze the ethical and social implications of 2, 4 Understand, Astronomy of the stand social implications of th												nalyse		
	using artificial intelligence in healthcare.													-	
CO6	Students will be able to identify emerging trends and future directions 2, 3 Understand, A													apply	
	in artificial intelligence and biomedical engineering.														
	Articulation Matrix: (CO-PO-PSO Mapping)												DGOO		
CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	POII	PO12	PSO1	PSO2	
COI	3	2	3	2	1	1	-	-	-	2	2	2	2	2	
CO2	3	2	2	2	1	1	1	2	-	1	1	1	2	1	
CO3	3	2	3	2	2	1	-	-	1	1	2	2	2	1	
CO4	3 2 3 2 1 1 1 1 1 1 3 2 3 2 2 2 1 1 1 1 1 1											1			
C05	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$											2			
C06	3 3 2 2 2 2 2 1 2 1 2												2		
Module	Trading	J	40 4-4	ficial T	4.111:00		Sylla	abus		a Defin		history of	tifinin1	Hours	
1	intelligence, Applications of artificial intelligence in biomedical engineering, Types of artificial												08		
	intelligence, Applications of artificial intelligence in biomedical engineering, Types of artificial intelligence (machine learning, deep learning, natural language processing, robotics). Advantages and												iges and		
	challe	nges of	using a	rtificial	intellig	ence in	biomed	lical eng	gineering	5					
2	Mach	ine Lea	arning i	n Biom	edical H	Enginee	ring: D	efinitio	n and typ	pes of m	achine le	arning (sup	ervised,	08	
	unsup (decis	ervised	, reinior	cement), Data j	pre-proc	neural	netwo	ture extra rks) An	action, I plicatio	viacnine i	earning aig	orithms		
	biome	dical er	ngineeri	ng (diag	gnosis, j	orognos	is, drug	discov	ery).	pircatio	115 01 1116	teriffic feat	ining in		
3	Deep	Learni	ing in I	Biomed	ical En	gineeri	ng: De	finition	and typ	es of d	eep learn	ing (convo	olutional	08	
	neural	netwo	rks, recu	urrent n	eural no	etworks	, genera	ative ad	versarial	l netwoi	rks), Trai	ning deep	learning		
	model	ls (back	propaga	ation, gi al proce	adient (descent,), Applı anguag	cations	of deep	learnin	g in biom	edical eng	ineering		
4	Natur	al Lan	guage	Process	ing in	Biomed	lical E	ngineer	ing: De	finition	and appl	ications of	natural	12	
	langua	age pro	cessing	(text m	ining, i	nforma	tion ext	raction	sentime	ent anal	ysis), Ch	allenges of	natural		
	langua	age proo	cessing	in biom	edical e	ngineer	ing (me	dical te	rminolog	gy, accu	racy, priv	vacy), Appl	ications		
	of nat	ural lan	iguage j	processi	ng in b	iomedia	cal engi	neering	(clinica	l decisi	on suppo	rt, drug dis	scovery,		
	Robot	tics in I	Biomed	ical Eng	gineerii	ng: Def	inition a	and type	es of rob	otics (sı	urgical rol	bots, exosk	eletons,		
	prosth	etics), (Control	systems	s for rot	otics (F	PID, fuz	zy logic	, adaptiv	ve contr	ol), Appli	ications of	robotics		
	in bio	medical	l engine	ering (s	urgery,	rehabili	tation,	assistive	e devices	<u>s)</u>					
5	Futur Engin	e Dire	ections	and	Emergi	ng Te	chnolog	gies in	Artifi	cial In	telligenco	e in Bio	medical	12	
	Integr	ation of	• f artific	ial inte	lligence	with o	other te	chnolog	gies (Inte	ernet of	Things.	blockchair	n, cloud		
	compu	uting),	Persona	alized r	nedicin	e and	precisio	on heal	thcare,	Augmer	nted and	virtual re	ality in		
	biome	dical er	ngineeri	ng, Bra	in-comp	outer int	erfaces	and net	ural engi	neering					
1	A ant C	1 T 11	·	- II - 14		1	Refer	ences	hin D. I	D 1	A = 1 .	- Drucci			
	Artificia Handbo	u intelli	igence 1 Artificia	n Healt 1 Intelli	ncare by	y Adam in Rion	воhr a hedical	na Matt Engine	nias K. I ering by	becker, Krishr	Academic an Saray	c Press. anan Ran	iesh Kee	avan S	
Balamurugan, G. S. Mahalakshmi, CRC Press.															
3. 1	Handbo	ok Arti	ficial In	telligen	ce in M	edicine	by Lei	Xing ar	nd A. K.	Louis.					
4. 1	Deep Le	earning	for Med	lical Im	age An	alysis b	y S. Ke	vin Zho	u, Hayit	Greens	pan, and I	Dinggang S	Shen.		